
Fresnel Documentation

Release 0.13.2

The Regents of the University of Michigan

May 11, 2021

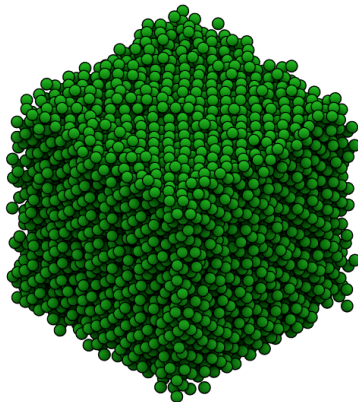
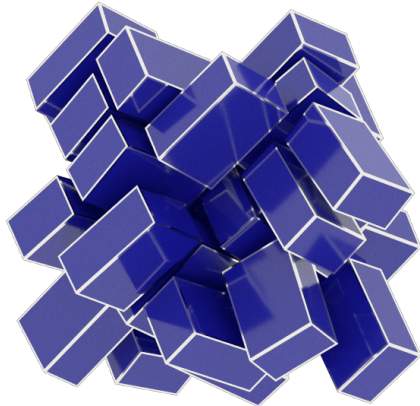
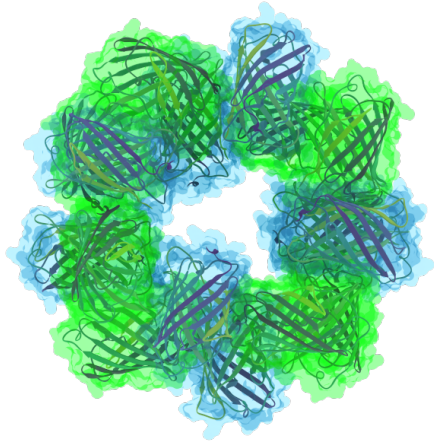
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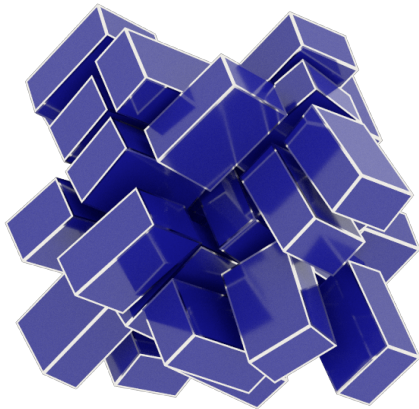
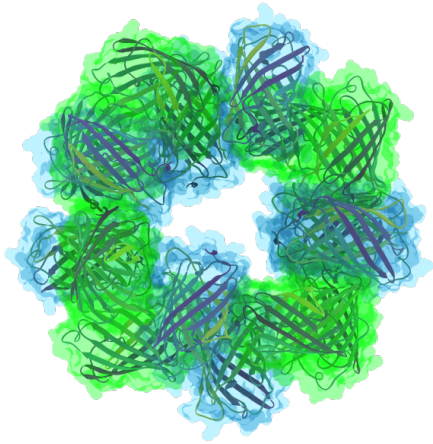
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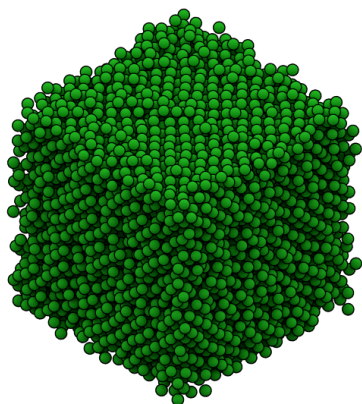
fresnel is a python library for path tracing publication quality images of soft matter simulations in real time. The fastest render performance is possible on NVIDIA GPUs using their [OptiX](#) ray tracing engine. **fresnel** also supports multi-core CPUs using Intel's [Embree](#) ray tracing kernels. Path tracing enables high quality global illumination and advanced rendering effects. **Fresnel** offers intuitive material parameters (like *roughness*, *specular*, and *metal*) and simple predefined lighting setups (like *cloudy* and *lightbox*).

Here are a few samples of what **fresnel** can do:

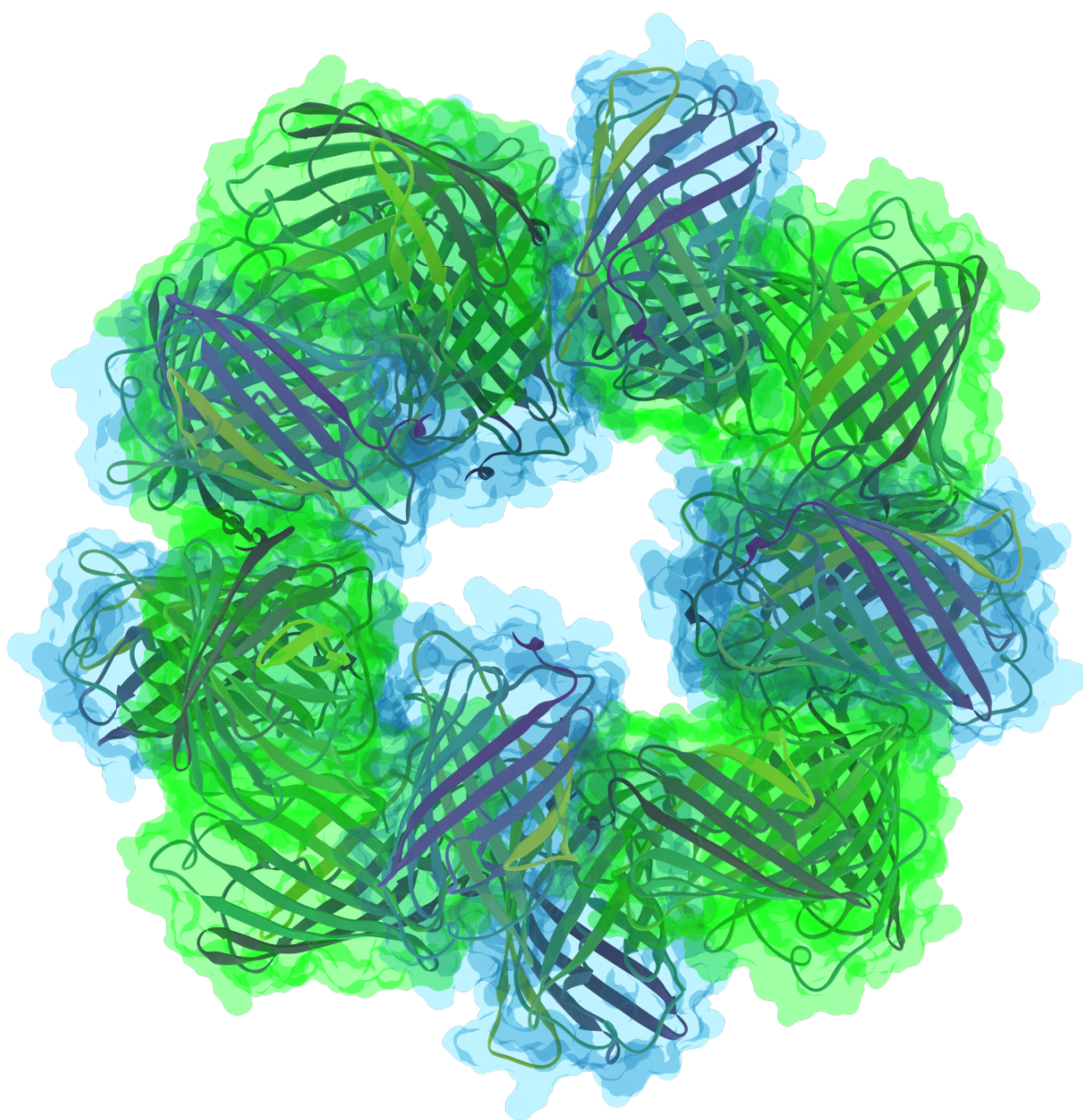


GALLERY





2.1 Protomer



Protomer on the cover of [Nature Chemistry](#) volume 11, issue 3:

- Ribbon geometry: `geometry.Mesh`
 - `material`: `roughness = 1.0, specular = 1.0, metal = 0, spec_trans = 0`
 - Generated with: `ribbon`
- Molecular surface: `geometry.Mesh`
 - `material`: `roughness = 2.0, specular = 0.95, metal = 0, spec_trans = 0.95`
 - Generated with `MSMS`
- Lighting: `light.lightbox` with background light
- Rendered with: `tracer.Path`: `samples = 64, light_samples = 32` on the GPU

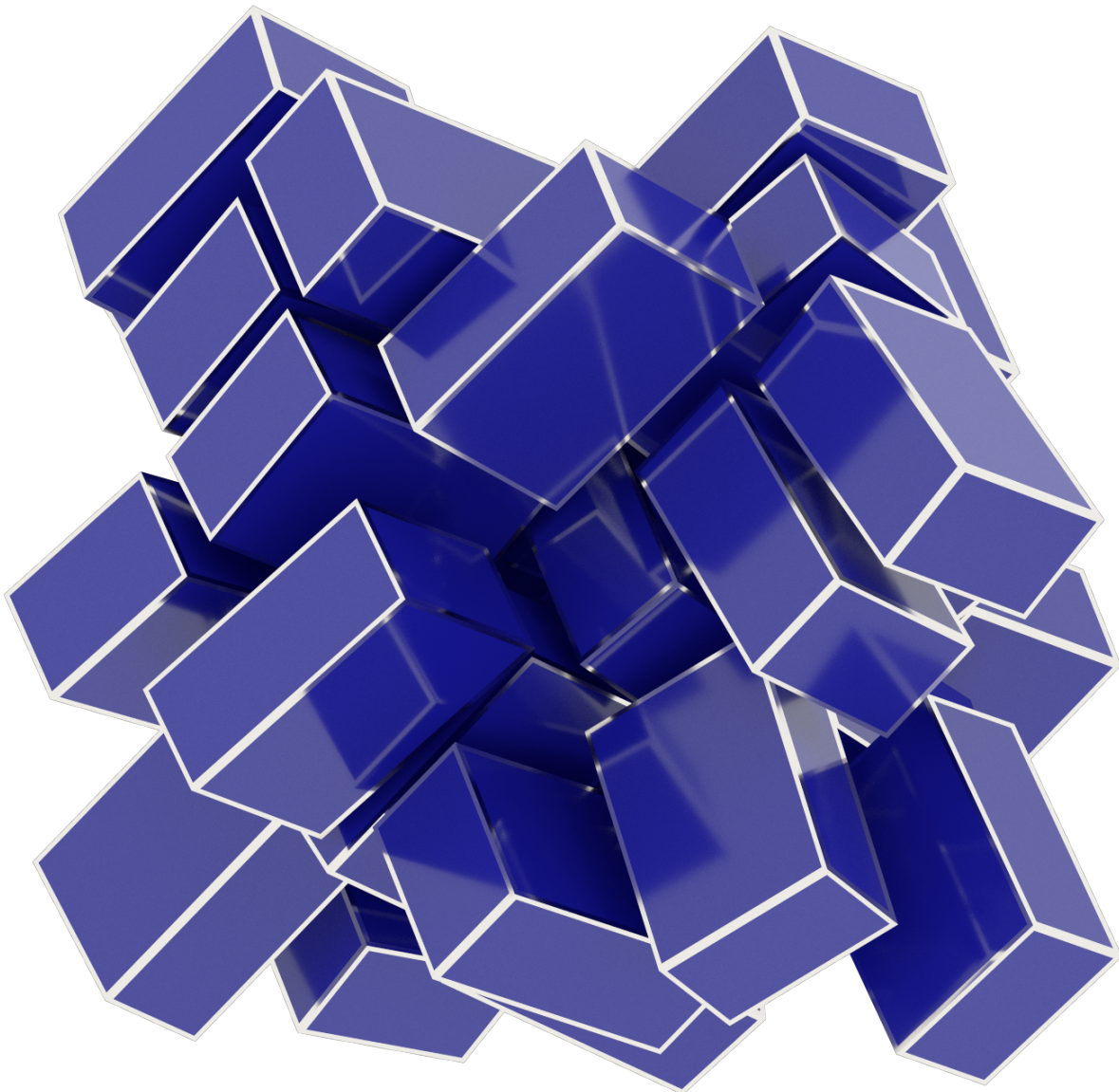
Author

Jens Glaser

CHAPTER
THREE

FEATURES

3.1 Cuboids



Cuboid example script:

- Geometry: `geometry.ConvexPolyhedron`: `outline_width = 0.015`
 - `material`: `roughness = 0.1, specular = 1, metal = 0, spec_trans = 0`
 - `outline_material`: `roughness = 0.1, metal = 1, spec_trans = 0, color = (0.95,0.93,0.88)`
 - position, orientation: output of a `HOOMD` simulation
- Lighting: `light.lightbox`
- Rendered with: `tracer.Path`: `samples = 256, light_samples = 16`

Source code

```
"""Cuboid example scene."""

import fresnel
import numpy
import PIL
import sys
import os

data = numpy.load('cuboids.npz')

scene = fresnel.Scene()
scene.lights = fresnel.light.lightbox()
W, H, D = data['width']
poly_info = fresnel.util.convex_polyhedron_from_vertices([
    [-W, -H, -D],
    [-W, -H, D],
    [-W, H, -D],
    [-W, H, D],
    [W, -H, -D],
    [W, -H, D],
    [W, H, -D],
    [W, H, D],
])

geometry = fresnel.geometry.ConvexPolyhedron(scene,
                                              poly_info,
                                              position=data['position'],
                                              orientation=data['orientation'],
                                              outline_width=0.015)
geometry.material = fresnel.material.Material(color=fresnel.color.linear(
    [0.1, 0.1, 0.6]),
                                              roughness=0.1,
                                              specular=1)
geometry.outline_material = fresnel.material.Material(color=(0.95, 0.93, 0.88),
                                                       roughness=0.1,
                                                       metal=1.0)

scene.camera = fresnel.camera.Orthographic.fit(scene, view='front')
```

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```
if 'CI' in os.environ:
    samples = 1
else:
    samples = 64

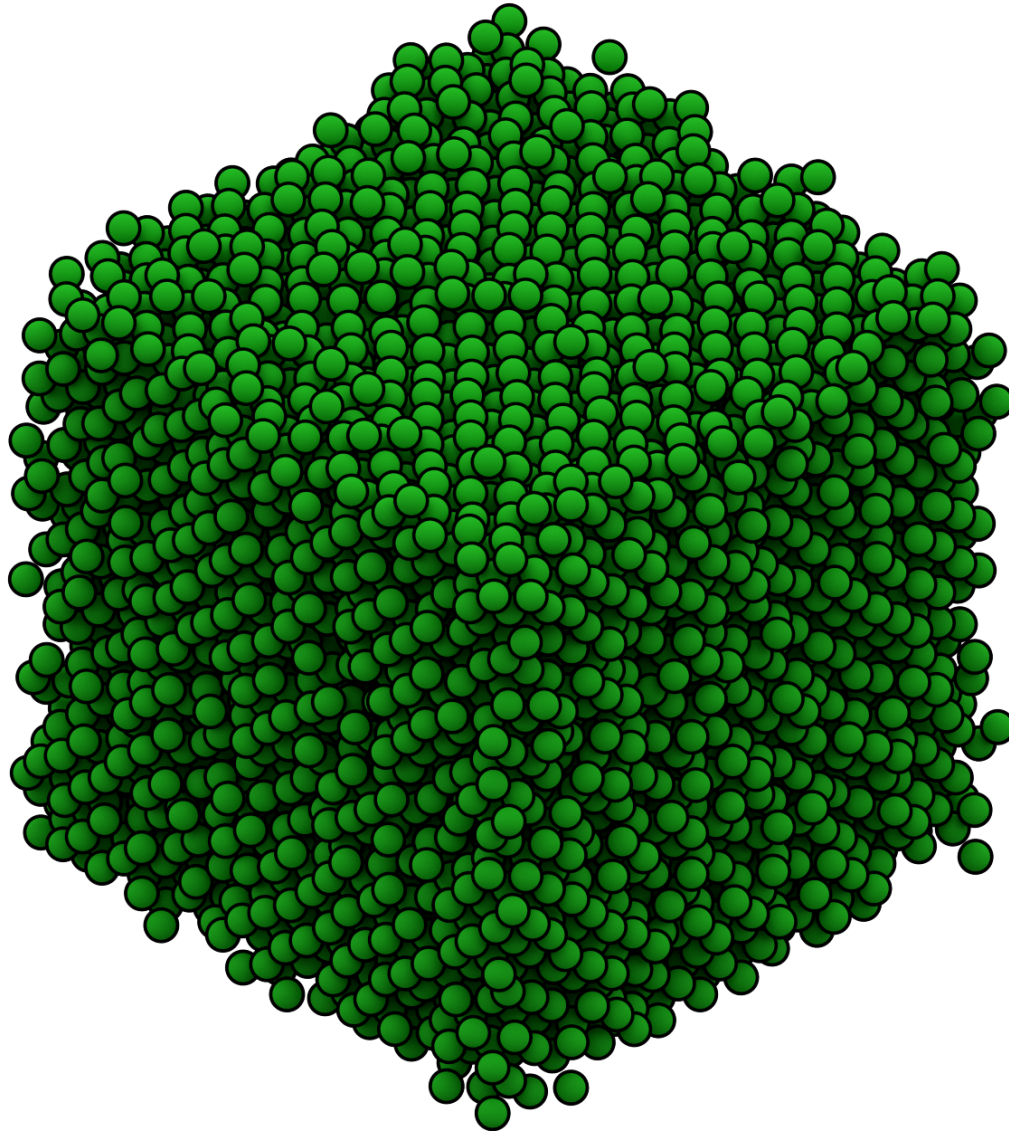
out = fresnel.pathtrace(scene, samples=samples, light_samples=32, w=580, h=580)
PIL.Image.fromarray(out[:], mode='RGBA').save('cuboid.png')

if len(sys.argv) > 1 and sys.argv[1] == 'hires':
    out = fresnel.pathtrace(scene,
                            samples=256,
                            light_samples=16,
                            w=1380,
                            h=1380)
    PIL.Image.fromarray(out[:], mode='RGBA').save('cuboid-hires.png')
```

Author

Joshua A. Anderson

3.2 Spheres



Spheres example script:

- Geometry: `geometry.Sphere`: `radius = 0.5`, `outline_width = 0.1`
 - `material`: `roughness = 0.8`, `specular = 0.2`, `metal = 0`, `spec_trans = 0`
 - `outline_material`: `solid = 1`, `color = (0,0,0)`
 - positions: output of a `HOOMD` simulation
- Lighting: `light.cloudy`
- Rendered with: `tracer.Path`: `samples = 256`, `light_samples = 16`

Source code

```
"""Sphere example scene."""

import fresnel
import numpy
import PIL
import sys
import os

data = numpy.load('spheres.npz')

scene = fresnel.Scene()
scene.lights = fresnel.light.cloudy()

geometry = fresnel.geometry.Sphere(scene,
                                   position=data['position'],
                                   radius=0.5,
                                   outline_width=0.1)

geometry.material = fresnel.material.Material(color=fresnel.color.linear(
    [0.1, 0.8, 0.1]),
                                              roughness=0.8,
                                              specular=0.2)

scene.camera = fresnel.camera.Orthographic.fit(scene)

if 'CI' in os.environ:
    samples = 1
else:
    samples = 64

out = fresnel.pathtrace(scene, samples=samples, light_samples=32, w=580, h=580)
PIL.Image.fromarray(out[:], mode='RGBA').save('sphere.png')

if len(sys.argv) > 1 and sys.argv[1] == 'hires':
    out = fresnel.pathtrace(scene,
                           samples=256,
                           light_samples=16,
                           w=1380,
                           h=1380)
    PIL.Image.fromarray(out[:], mode='RGBA').save('sphere-hires.png')
```


Author

Joshua A. Anderson

3.3 Gumballs



Spheres rendered as gumballs made from a Monte Carlo simulation with [HOOMD](#).

- Geometry: `geometry.Sphere`: `radius = 0.5`
 - `material`: `primitive_color_mix = 1.0`, `roughness = 0.2`, `specular = 0.8`
 - positions: output of a [HOOMD](#) simulation

- colors: randomly assigned from a set of gumball colors
- Lighting: `light.lightbox` with an additional light
- Rendered with: `tracer.Path: samples = 256, light_samples = 64` on the GPU

Source code

```
"""Gumballs example scene."""

import fresnel
import numpy as np
from matplotlib.colors import LinearSegmentedColormap
import PIL
import sys
import os

# First, we create a color map for gumballs.
colors = [
    '#e56d60',
    '#ee9944',
    '#716e80',
    '#eadecd',
    '#cec746',
    '#c0443f',
    '#734d56',
    '#5d5f7b',
    '#ecb642',
    '#8a9441',
]
cmap = LinearSegmentedColormap.from_list(name='gumball',
                                         colors=colors,
                                         N=len(colors))

# Next, we gather information needed for the geometry.
position = np.load('gumballs.npz')['position']
np.random.seed(123)
color = fresnel.color.linear(cmap(np.random.rand(len(position))))
material = fresnel.material.Material(
    primitive_color_mix=1.0,
    roughness=0.2,
    specular=0.8,
)

# We create a fresnel scene and its geometry.
scene = fresnel.Scene()

geometry = fresnel.geometry.Sphere(
    scene,
    position=position,
    radius=0.5,
    color=color,
    material=material,
```

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```

)

# Configure camera and lighting.
scene.camera = fresnel.camera.Perspective(position=(0, 0, 25),
                                           look_at=(0, 0, 0),
                                           up=(0, 1, 0),
                                           focal_length=0.5,
                                           f_stop=0.25)

scene.camera.focus_on = (0, 0, 5.6)
scene.lights = fresnel.light.lightbox()
scene.lights.append(
    fresnel.light.Light(direction=(0.3, -0.3, 1),
                        color=(0.5, 0.5, 0.5),
                        theta=np.pi))

if 'CI' in os.environ:
    samples = 1
else:
    samples = 128

# Execute rendering.
out = fresnel.pathtrace(scene, w=600, h=600, samples=samples, light_samples=64)
PIL.Image.fromarray(out[:], mode='RGBA').save('gumballs.png')

if len(sys.argv) > 1 and sys.argv[1] == 'hires':
    out = fresnel.pathtrace(scene,
                            w=1500,
                            h=1500,
                            samples=256,
                            light_samples=64)
    PIL.Image.fromarray(out[:], mode='RGBA').save('gumballs-hires.png')

```

Author*Bradley Dice*

INSTALLATION

fresnel binaries are available in the [glotzerlab-software Docker/Singularity](#) images and in packages on [conda-forge](#). You can also compile **fresnel** from source

4.1 Binaries

4.1.1 Conda package

fresnel is available on [conda-forge](#) on the *linux-64*, *osx-64*, and *osx-arm64* platforms. To install, download and install [miniforge](#) or [miniconda](#). Then install **fresnel** from the [conda-forge](#) channel:

```
$ conda install -c conda-forge fresnel
```

Note: The **fresnel** package on [conda-forge](#) does not support GPUs

4.1.2 Singularity / Docker images

See the [glotzerlab-software](#) documentation for instructions to install and use the containers.

4.2 Compile from source

4.2.1 Obtain the source

Download source releases directly from the web: <https://glotzerlab.engin.umich.edu/downloads/fresnel/>:

```
$ curl -O https://glotzerlab.engin.umich.edu/downloads/fresnel/fresnel-v0.13.2.tar.gz
```

Or, clone using git:

```
$ git clone --recursive https://github.com/glotzerlab/fresnel
```

Fresnel uses git submodules. Either clone with the `--recursive` option, or execute `git submodule update --init` to fetch the submodules.

4.2.2 Configure a virtual environment

When using a shared Python installation, create a **virtual environment** where you can install **fresnel**:

```
$ python3 -m venv /path/to/virtual/environment
```

Activate the environment before configuring and before executing **fresnel** scripts:

```
$ source /path/to/virtual/environment/bin/activate
```

Tell CMake to search in the virtual environment first:

```
$ export CMAKE_PREFIX_PATH=/path/to/virtual/environment
```

Note: Other types of virtual environments (such as *conda*) may work, but are not thoroughly tested.

4.2.3 Install Prerequisites

fresnel requires:

- C++14 capable compiler
- CMake ≥ 3.8
- pybind11 ≥ 2.2
- Python ≥ 3.6
- numpy
- Qhull ≥ 2015.2
- For CPU execution (required when `ENABLE_EMBREE=ON`):
 - Intel TBB $\geq 4.3.20150611$
 - Intel Embree $\geq 3.0.0$
- For GPU execution (required when `ENABLE_OPTIX=ON`):
 - OptiX == 6.0
 - CUDA ≥ 10

`ENABLE_EMBREE` (*defaults ON*) and `ENABLE_OPTIX` (*defaults OFF*) are orthogonal settings, either or both may be enabled.

Additional packages may be needed:

- pyside2
 - Required to enable interactive widgets. (runtime)
- pillow
 - Required to display rendered output in Jupyter notebooks automatically. (runtime)
 - Required to execute unit tests.
- pytest
 - Required to execute unit tests.

- sphinx, sphinx_rtd_theme, and nbsphinx
 - Required to build the user documentation.
- doxygen
 - Required to build developer documentation.

Install these tools with your system or virtual environment package manager. **fresnel** developers have had success with pacman ([arch linux](#)), apt-get ([ubuntu](#)), Homebrew ([macOS](#)), and MacPorts ([macOS](#)):

```
$ your-package-manager install cmake doxygen embree pybind11 python python-pillow python-
↳pytest python-sphinx python-sphinx_rtd_theme python-nbsphinx intell-tbb qhull
```

Typical HPC cluster environments provide python, numpy, and cmake via a module system:

```
$ module load gcc python cmake
```

Note: Packages may be named differently, check your system’s package list. Install any `-dev` packages as needed.

Tip: You can install numpy and other python packages into your virtual environment:

```
python3 -m pip install numpy
```

4.2.4 Compile

Configure with **cmake** and compile with **make**:

```
$ cd /path/to/fresnel
$ mkdir build
$ cd build
$ cmake ../
$ make install -j10
```

By default, **fresnel** builds the Embree (CPU) backend. Pass `-DENABLE_OPTIX=ON` to **cmake** to enable the GPU accelerated OptiX backend.

4.2.5 Run tests

To run tests, execute `pytest` in the build directory or in an environment where **fresnel** is installed to run all tests.

```
$ pytest --pyargs fresnel
```

4.2.6 Build user documentation

Build the user documentation with **sphinx**:

```
$ cd /path/to/fresnel
$ cd doc
$ make html
$ open build/html/index.html
```

4.2.7 Build C++ Documentation

To build the developer documentation, execute **doxygen** in the repository root. It will write HTML output in `devdoc/html/index.html`.

CHANGE LOG

fresnel releases follow semantic versioning.

5.1 v0.x

5.1.1 v0.13.2 (2021-05-11)

Added

- Support macos-arm64.

5.1.2 v0.13.1 (2021-03-11)

Fixed

- Add missing version module

5.1.3 v0.13.0 (2021-03-11)

Added

- Perspective camera.
- Depth of field effect.

Changed

- Reduce latency in `interact.SceneView` while rotating the view.
- Improve user experience with mouse rotations in `interact.SceneView`.
- [breaking] - Moved `camera.orthographic` to `camera.Orthographic`.
- [breaking] - Moved `camera.fit` to `camera.Orthographic.fit`.

Removed

- [breaking] - Removed “auto” camera in `Scene`. Use `camera.Orthographic.fit`

5.1.4 v0.12.0 (2020-02-27)

Added

- `preview` and `tracer.Preview` accept a boolean flag `anti_alias` to enable or disable anti-aliasing.

Changed

- `preview` and `tracer.Preview` enable anti-aliasing by default.
- Python, Cython, and C code must follow strict style guidelines.
- Renamed `util.array` to `util.Array`
- Renamed `util.image_array` to `util.ImageArray`
- Converted `interact.SceneView.setScene` to a property: `scene`

Removed

- `preview` and `tracer.Preview` no longer accept the `aa_level` argument - use `anti_alias`.

5.1.5 v0.11.0 (2019-10-30)

Added

- Added box geometry convenience class `Box`.

Removed

- Support for **Python** 3.5.

Fixed

- Compile on systems where `libqhullcpp.a` is missing or broken.
- Find **Embree** headers when they are not in the same path as **TBB**.

5.1.6 v0.10.1 (2019-09-05)

Fixed

- Restore missing examples on `readthedocs`.

5.1.7 v0.10.0 (2019-08-19)

Changed

- **CMake** ≥ 3.8 is required at build time.
- **pybind11** ≥ 2.2 is required at build time.
- **qhull** ≥ 2015 is required.
- install to the **Python** `site-packages` directory by default.
- **CI** tests execute on Microsoft Azure Pipelines.

Fixed

- Improved installation documentation.

5.1.8 v0.9.0 (2019-04-30)

- Added support for linearizing colors of shape (4).
- Improve examples.

5.1.9 v0.8.0 (2019-03-05)

- Documentation improvements.
- Add `geometry.Polygon`: Simple and/or rounded polygons in the $z=0$ plane.
- API breaking changes:
 - Remove: `geometry.Prism`

5.1.10 v0.7.1 (2019-02-05)

- Fix **conda-forge** build on mac

5.1.11 v0.7.0 (2019-02-05)

- Add `util.convex_polyhedron_from_vertices`: compute convex polyhedron plane origins and normals given a set of vertices
- Improve documentation
- Add `interact.SceneView`: **pyside2** widget for interactively rendering scenes with path tracing
- Add `geometry.Mesh`: Arbitrary triangular mesh geometry, instanced with N positions and orientations
- **fresnel** development is now hosted on github: <https://github.com/glotzerlab/fresnel/>
- Improve `light.lightbox` lighting setup
- API breaking changes:
 - `geometry.ConvexPolyhedron` arguments changed. It now accepts polyhedron information as a dictionary.

5.1.12 v0.6.0 (2018-07-06)

- Implement `tracer.Path` on the GPU.
- Implement `ConvexPolyhedron` geometry on the GPU.
- Improve path tracer performance with Russian roulette termination.
- Compile warning-free.
- Fix sphere intersection test bugs on the GPU.
- `tracer.Path` now correctly starts sampling over when resized.
- Wrap C++ code with **pybind 2.2**
- Make documentation available on readthedocs: <http://fresnel.readthedocs.io>
- Fresnel is now available on **conda-forge**: <https://anaconda.org/conda-forge/fresnel>

- embree ≥ 3.0 is now required for CPU support
- Improve documentation

5.1.13 v0.5.0 (2017-07-27)

- Add new lighting setups
 - `lightbox`
 - `cloudy`
 - `ring`
- Adjust brightness of lights in existing setups
- Remove `clearcoat` material parameter
- Add `spec_trans` material parameter
- Add Path tracer to render scenes with indirect lighting, reflections, and transparency (*CPU-only*)
- Add `ConvexPolyhedron` geometry (*CPU-only, beta API, subject to change*)
- Add `fresnel.preview` function to easily generate Preview traced renders with one line
- Add `fresnel.pathtrace` function to easily generate Path traced renders with one line
- Add anti-aliasing (always on for the Path tracer, set `aa_level > 0` to enable for Preview)
- API breaking changes:
 - `render` no longer exists. Use `preview` or `pathtrace`.
 - `tracer.Direct` is now `tracer.Preview`.

CPU-only features will be implemented on the GPU in a future release.

5.1.14 v0.4.0 (2017-04-03)

- Enforce requirement: Embree $\geq 2.10.0$
- Enforce requirement Pybind =1.8.1
- Enforce requirement TBB ≥ 4.3
- Rewrite camera API, add `camera.fit` to fit the scene
- scenes default to an automatic fit camera
- Implement area lights, add default lighting setups
- Scene now supports up to 4 lights, specified in camera space
- Implement Disney's principled BRDF
- `Tracer.histogram` computes a histogram of the rendered image
- `Tracer.enable_highlight_warning` highlights overexposed pixels with a given warning color
- `Device.available_modes` lists the available execution modes
- `Device.available_gpus` lists the available GPUs
- Device can now be limited to n GPUs
- API breaking changes:

- `camera.Orthographic` is now `camera.orthographic`
- Device now takes the argument n instead of *limit*
- Scene no longer has a `light_direction` member

5.1.15 v0.3.0 (2017-03-09)

- Suppress “cannot import name” messages
- Support Nx3 and Nx4 inputs to `color.linear`

5.1.16 v0.2.0 (2017-03-03)

- Parallel rendering on the CPU
- Fix PTX file installation
- Fix python 2.7 support
- Unit tests
- Fix bug in sphere rendering on GPU

5.1.17 v0.1.0 (2017-02-02)

- Prototype API
- Sphere geometry
- Prism geometry
- outline materials
- diffuse materials
- Direct tracer

USER COMMUNITY

6.1 fresnel-users mailing list

Subscribe to the [fresnel-users](#) mailing list to receive release announcements, post questions for advice on using the software, and discuss potential new features.

6.2 Issue tracker

File bug reports on [fresnel's issue tracker](#).

6.3 Contribute

fresnel is an open source project. Contributions are accepted via pull request to [fresnel's github repository](#). Please review `CONTRIBUTING.MD` in the repository before starting development. You are encouraged to discuss your proposed contribution with the **fresnel** user and developer community who can help you design your contribution to fit smoothly into the existing ecosystem.

INTRODUCTION

Fresnel is a python library that can ray trace publication quality images in real time. It provides a simple python API to define a **scene** consisting of any number of **geometry** primitives and **render** it to an output image.

To start, import the `fresnel` python module.

```
[1]: import fresnel
```

7.1 Define a scene

A **Scene** defines a coordinate system, the **camera** view, the **light sources**, and contains a number of **geometry** primitives. Create a new **Scene** class instance. Scenes come with a default automatic camera that fits the geometry and a default set of lights.

```
[2]: scene = fresnel.Scene()
```

7.2 Add geometry to the scene

A **Scene** may consist of any number of **geometry** objects. Each **geometry** object consists of N primitives of the same type, and a **material** that describes how the primitives interact with light sources. Create 8 spheres with radius 1.0.

```
[3]: geometry = fresnel.geometry.Sphere(scene, N=8, radius=1.0)
```

Geometry objects have a number of per-primitive attributes. These are exposed with an interface compatible with **numpy** arrays, and can copy data from **numpy** arrays efficiently. Set the positions of the spheres:

```
[4]: geometry.position[:] = [[1,1,1],  
                             [1,1,-1],  
                             [1,-1,1],  
                             [1,-1,-1],  
                             [-1,1,1],  
                             [-1,1,-1],  
                             [-1,-1,1],  
                             [-1,-1,-1]]
```

Set the **material** of the geometry object to a rough blue surface:

```
[5]: geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),  
                                                  roughness=0.8)
```

7.3 Set the camera

The **camera** defines the view of the scene. **fresnel** can auto-fit a camera to the **scene**'s geometry:

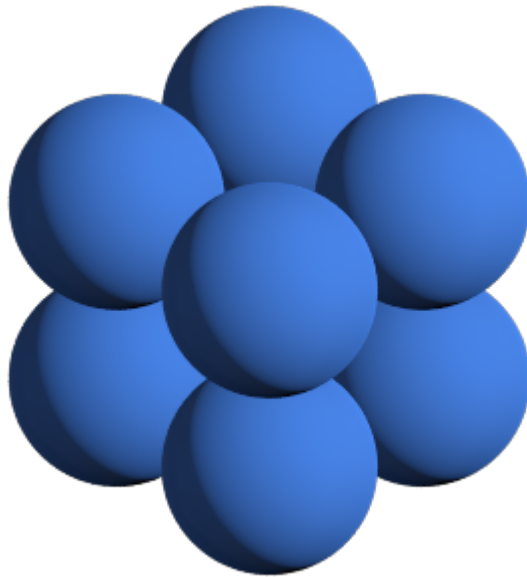
```
[6]: scene.camera = fresnel.camera.Orthographic.fit(scene)
```

7.4 Render the scene

preview quickly renders the scene from the view point of the camera. Anti-aliasing is on by default to smooth edges in the image.

```
[7]: fresnel.preview(scene)
```

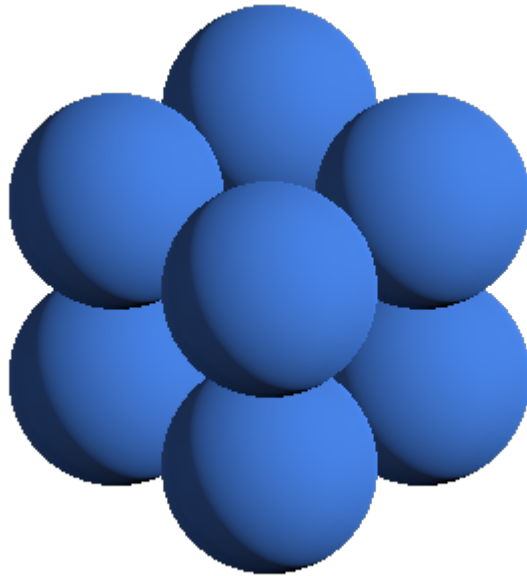
```
[7]:
```



Disable *anti-aliasing* if you desire a quicker render.

```
[8]: fresnel.preview(scene, anti_alias=False)
```

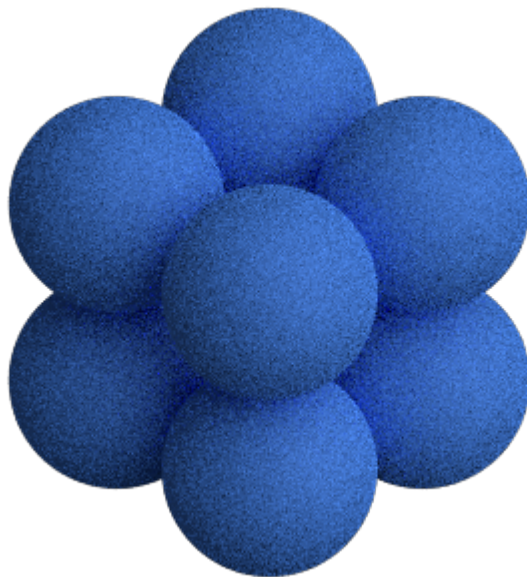

[8]:



preview only applies direct lighting. Use **pathtrace** to account for indirect lighting. (anti-aliasing is always enabled when path tracing).

[9]: `fresnel.pathtrace(scene)`

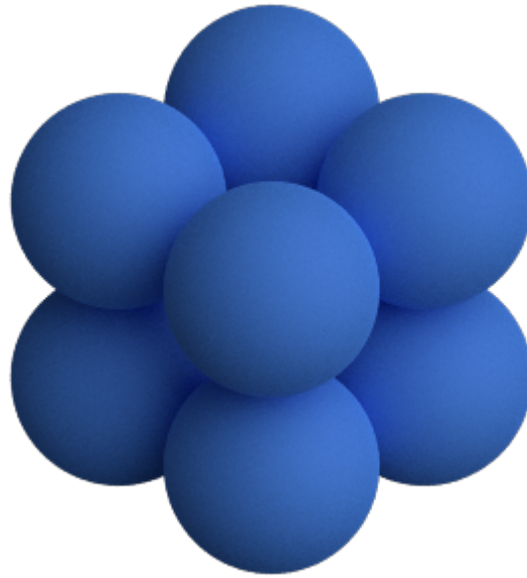
[9]:



The resulting image is noisy. Increase the number of *light samples* to obtain a clean image.

```
[10]: fresnel.pathtrace(scene, light_samples=40)
```

```
[10]:
```



7.5 Save output

preview and *pathtrace* return output buffers that can be used like HxWx4 RGBA **numpy** arrays. You can pass this standard format on to other python libraries that work images (e.g. [matplotlib](#)).

```
[11]: out = fresnel.preview(scene)
      print(out[:].shape)
      print(out[:].dtype)
```

```
(370, 600, 4)
uint8
```

Use [Pillow](#) to save the rendered output to a png file with transparency.

```
[12]: import PIL
```

```
[13]: image = PIL.Image.fromarray(out[:], mode='RGBA')
      image.save('output.png')
```

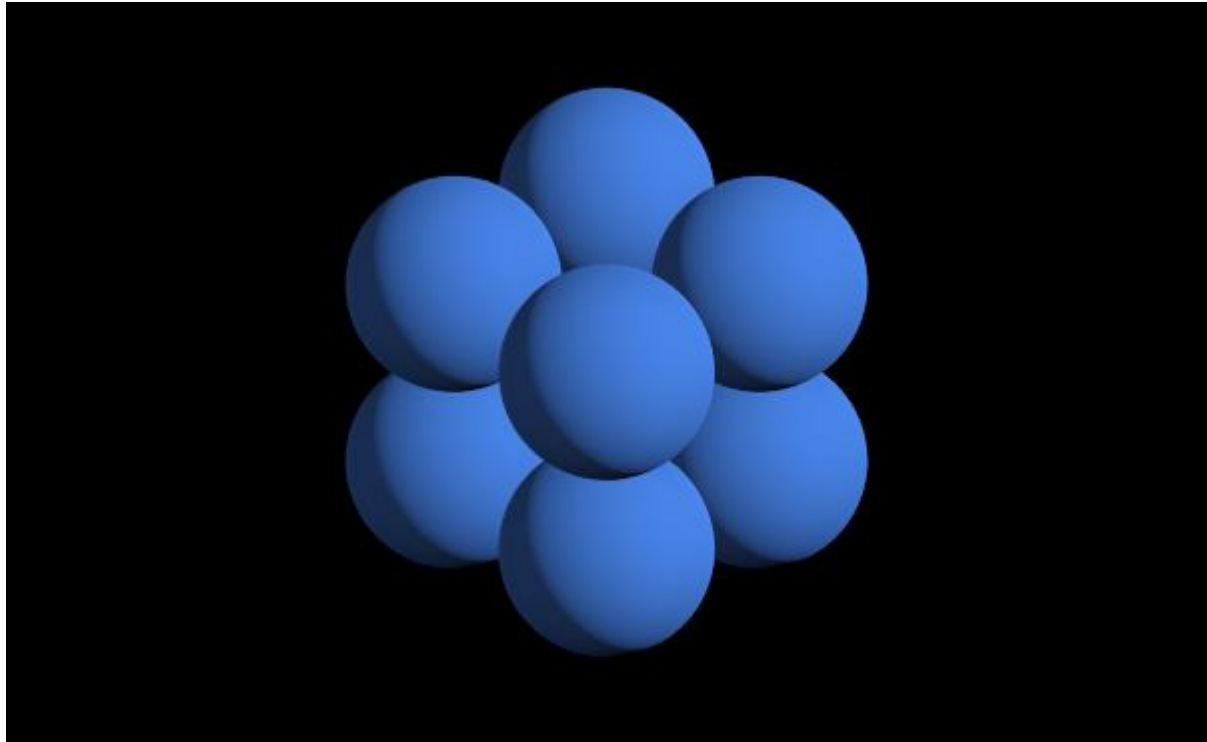
To save a JPEG, create an RGB image. This ignores the alpha channel, so the scene background color will show.

```
[14]: image = PIL.Image.fromarray(out[:, :, 0:3], mode='RGB')
      image.save('output.jpeg')
```

This is what `output.jpeg` looks like (the default background color is black):

```
[15]: import IPython.display  
      IPython.display.Image('output.jpeg')
```

```
[15]:
```



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PRIMITIVE PROPERTIES

Each **geometry** type specifies a number of per-primitive properties. For example, the **Sphere** geometry has per-primitive *position*, *radius*, and *color*.

```
[1]: import fresnel
scene = fresnel.Scene()
```

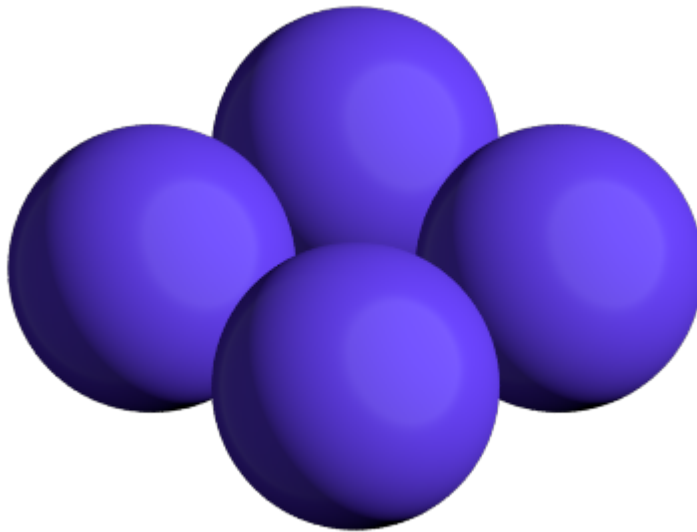
8.1 Setting properties when creating the geometry

Any of the properties may be set when the **geometry** is created, or they may be left as default values.

```
[2]: geometry = fresnel.geometry.Sphere(scene,
                                         position = [[1,0,1],
                                                       [1,0,-1],
                                                       [-1,0,1],
                                                       [-1,0,-1]],
                                         radius=1.0,
                                         material = fresnel.material.Material(color=fresnel.
                                         ↪color.linear([0.42,0.267,1]))
                                         # per-primitive color left default
                                         )
scene.camera = fresnel.camera.Orthographic.fit(scene)
```

```
[3]: fresnel.preview(scene)
```

[3]:



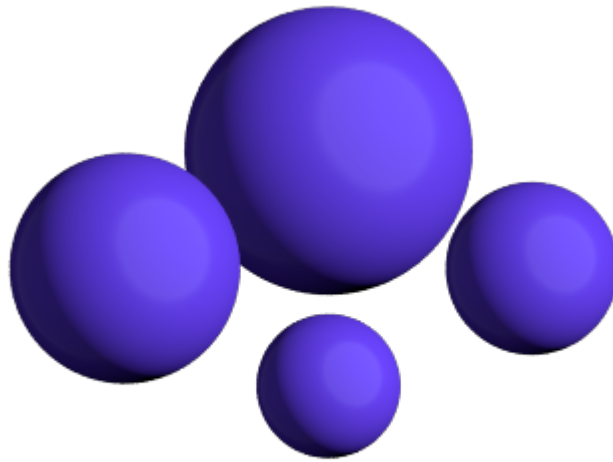
8.2 Changing properties after creation

Access the per-primitive properties as if they were **numpy** arrays. The *radius* property for the **Sphere geometry** sets the radius of each primitive.

```
[4]: geometry.radius[:] = [0.5, 0.6, 0.8, 1.0]
```

```
[5]: fresnel.preview(scene)
```

[5]:

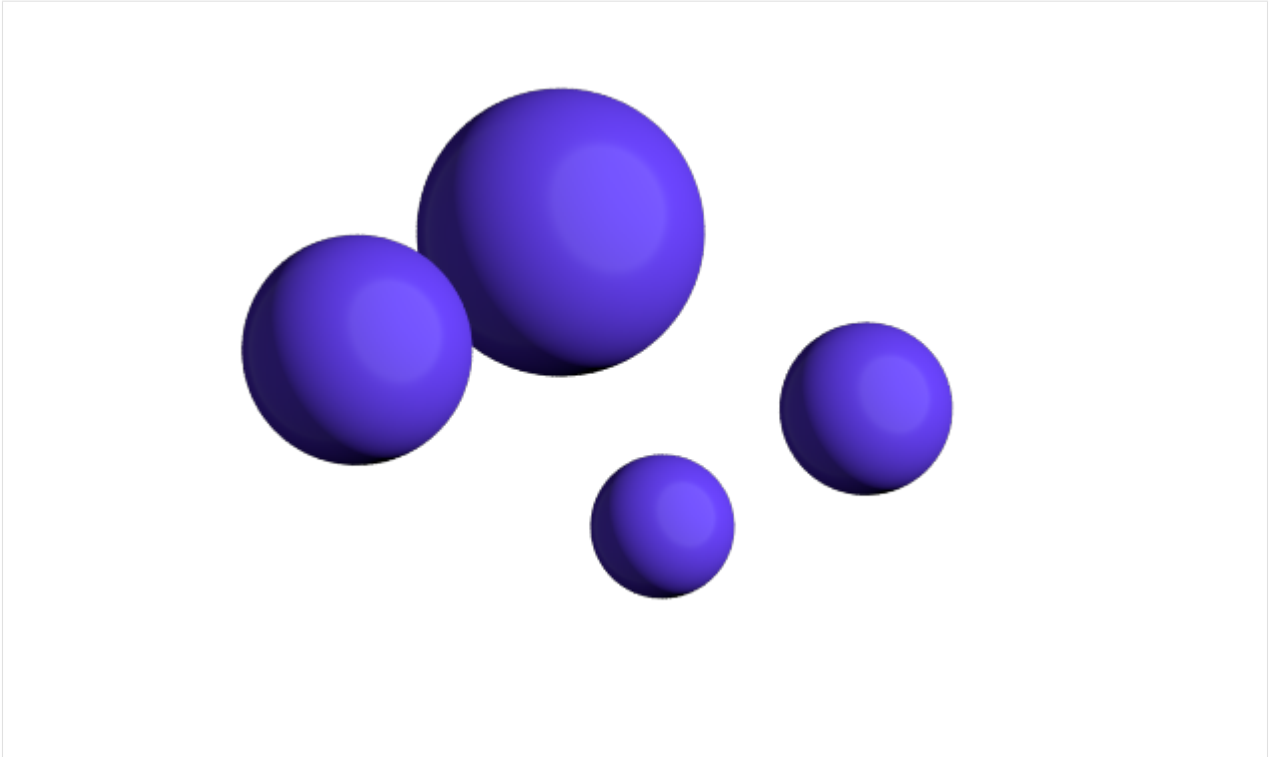


The *position* property sets the position of each sphere in the scene's coordinate system.

```
[6]: geometry.position[:] = [[1.5,0,1],  
                             [1.5,0,-1],  
                             [-1.5,0,1],  
                             [-1.5,0,-1]]
```

```
[7]: fresnel.preview(scene)
```

[7]:

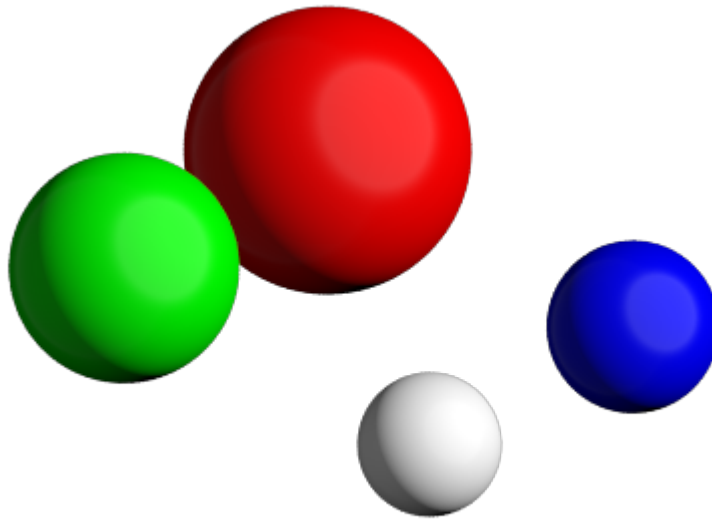


The *color* property sets a per primitive color. The geometry **material color** and the **primitive color** are mixed with fraction **primitive_color_mix**. A value of 1.0 selects the primitive color, 0.0 selects the *material* color and values in between mix the colors.

```
[8]: geometry.material.primitive_color_mix = 1.0
      geometry.color[:] = fresnel.color.linear([[1,1,1], [0,0,1], [0,1,0], [1,0,0]])
```

```
[9]: fresnel.preview(scene)
```

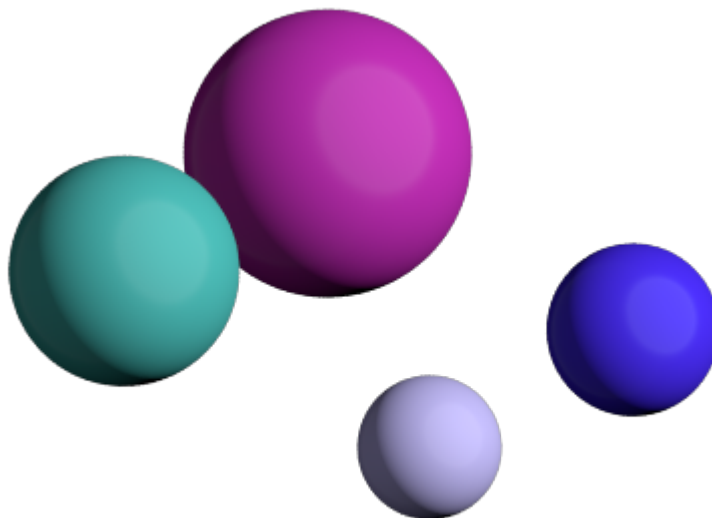

[9]:



```
[10]: geometry.material.primitive_color_mix = 0.5
```

```
[11]: fresnel.preview(scene)
```

[11]:



8.3 Reading primitive properties

Primitive properties may be read as well as written.

```
[12]: geometry.radius[:]
```

```
[12]: array([0.5, 0.6, 0.8, 1. ], dtype=float32)
```

```
[13]: geometry.position[:]
```

```
[13]: array([[ 1.5,  0. ,  1. ],
           [ 1.5,  0. , -1. ],
           [-1.5,  0. ,  1. ],
           [-1.5,  0. , -1. ]], dtype=float32)
```

```
[14]: geometry.color[:]
```

```
[14]: array([[1., 1., 1.],
           [0., 0., 1.],
           [0., 1., 0.],
           [1., 0., 0.]], dtype=float32)
```

8.4 Common errors

Primitive properties may be accessed like **numpy** arrays, but they may not be assigned directly.

```
[15]: geometry.radius = 1.0
```

```
-----
AttributeError                                Traceback (most recent call last)
<ipython-input-15-020bd663bace> in <module>
----> 1 geometry.radius = 1.0

AttributeError: can't set attribute
```

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MATERIAL PROPERTIES

Each **geometry** has an associated **material**. The **material** is a set of parameters that defines how light interacts with the **geometry**. Here is a test scene to demonstrate these properties.

```
[1]: import fresnel
import math
device = fresnel.Device()
scene = fresnel.Scene(device)
position = []
for k in range(5):
    for i in range(5):
        for j in range(5):
            position.append([2*i, 2*j, 2*k])
geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
scene.camera = fresnel.camera.Orthographic.fit(scene)
```

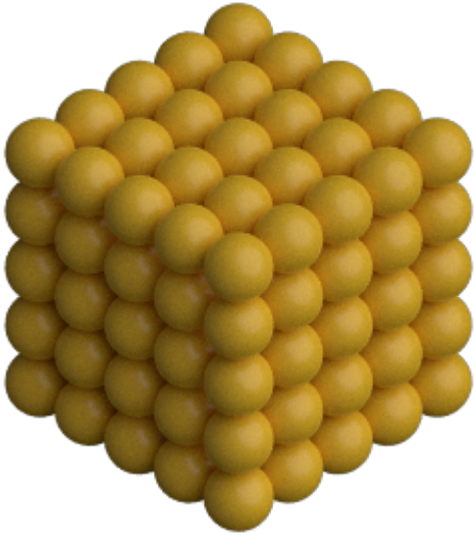
9.1 Material color

The **color** of a material sets its base color. Default material parameters set a primarily diffuse material with light specular highlights.

```
[2]: geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.9,0.714,0.
↪ 169]))
```

```
[3]: fresnel.pathtrace(scene, w=300, h=300, light_samples=40)
```

[3]:



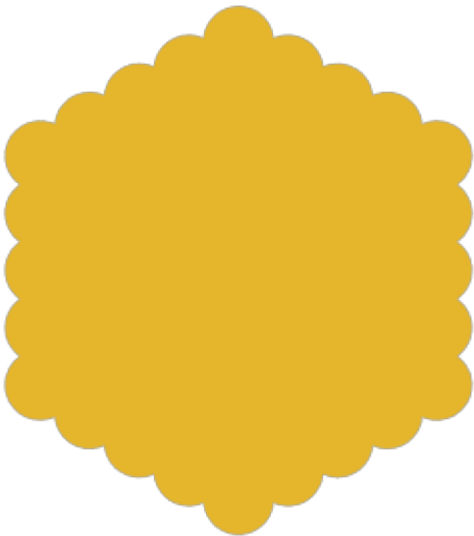
9.2 Solid color materials

Set the **solid** parameter to 1.0 to disable material interaction with light. A **solid** material has no shading applied and always displays as **color**.

```
[4]: geometry.material.solid = 1.0
```

```
[5]: fresnel.preview(scene, w=300, h=300)
```

[5]:



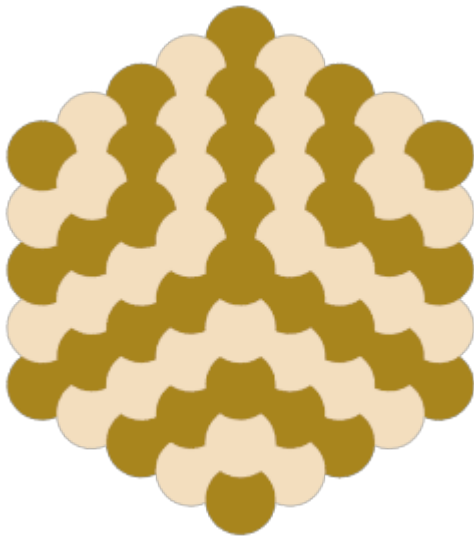
9.3 Geometry / primitive color mixing

Set **primitive_color_mix** to any value in the range 0.0 to 1.0 to control the amount that the per-primitive colors mix with the geometry color.

```
[6]: geometry.material.primitive_color_mix = 0.5
      geometry.color[::2] = fresnel.color.linear([0,0,0])
      geometry.color[1::2] = fresnel.color.linear([1,1,1])
```

```
[7]: fresnel.preview(scene, w=300, h=300)
```

```
[7]:
```



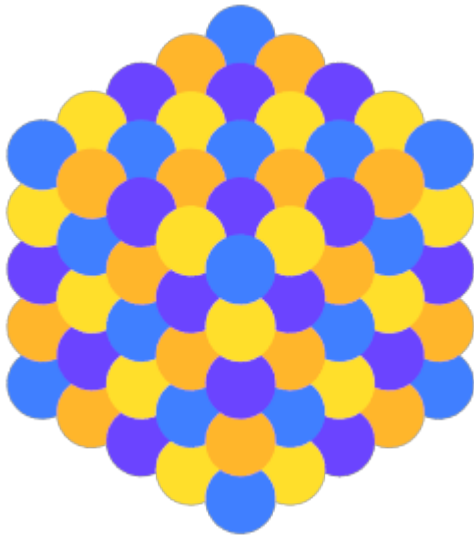
Typical use cases utilize values of either 0.0 (force a single color defined by the material) or 1.0 (force the per primitive color.)

```
[8]: geometry.material.primitive_color_mix = 1.0

      geometry.color[::4] = fresnel.color.linear([0.25,0.5,1])
      geometry.color[1::4] = fresnel.color.linear([1,0.714,0.169])
      geometry.color[2::4] = fresnel.color.linear([0.42,0.267,1])
      geometry.color[3::4] = fresnel.color.linear([1,0.874,0.169])
```

```
[9]: fresnel.preview(scene, w=300, h=300)
```

[9]:



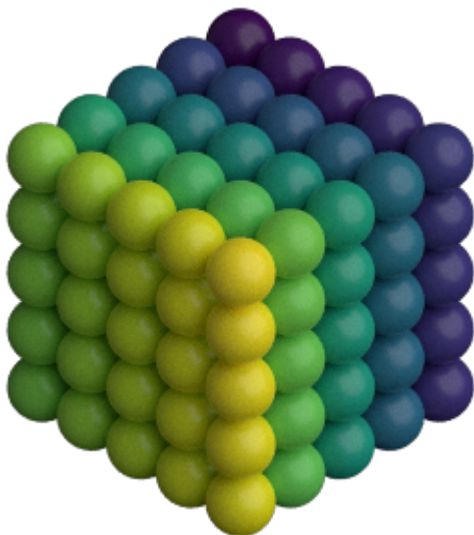
To use a **matplotlib** color map, pass the output of the color map to `fresnel.color.linear` so the output colors appear as intended.

```
[10]: import matplotlib, matplotlib.cm
import numpy
geometry.material.solid = 0.0
mapper = matplotlib.cm.ScalarMappable(norm = matplotlib.colors.Normalize(vmin=0, vmax=1,
↪ clip=True),
                                     cmap = matplotlib.cm.get_cmap(name='viridis'))

v = numpy.linspace(0,1,len(position))
geometry.color[:] = fresnel.color.linear(mapper.to_rgba(v))
```

```
[11]: fresnel.pathtrace(scene, w=300, h=300, light_samples=40)
```

[11]:



9.4 All properties

Materials have a number of intuitive properties. All are defined in a nominal range from 0 to 1, though some values can be pushed past 1 for extremely strong effects.

- roughness - Set the roughness of the material. Recommend values ≥ 0.1 .
- specular - Control the strength of the specular highlights
- metal - 0: dielectric materials (plastic, glass, etc...). 1: pure metals.
- spec_trans - Set the fraction of light that passes through the material.

Here are some examples of different material parameters.

```
[12]: scene2 = fresnel.Scene(device)
spheres = []
for i in range(11):
    spheres.append(fresnel.geometry.Sphere(scene2, position = (i, 0, 0), radius=0.4))
    spheres[i].material = fresnel.material.Material(color=(.1,.7,.1))

tracer = fresnel.tracer.Path(device=device, w=1000, h=75)

scene2.lights = [fresnel.light.Light(direction=(1,1,-1), color=(0.5, 0.5, 0.5)),
                 fresnel.light.Light(direction=(-1,-1,1), color=(0.5, 0.5, 0.5))]

scene2.camera = fresnel.camera.Orthographic.fit(scene2)
```

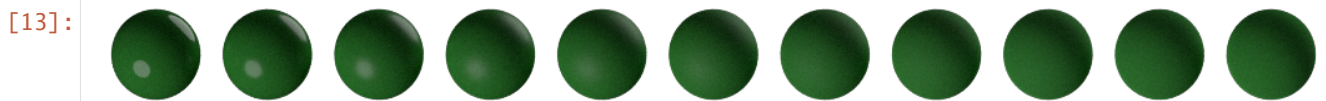
9.4.1 Examples

These examples are front lit from the lower left and back lit from the upper right.

Vary roughness in a specular material from 0.1 to 1.1

```
[13]: for i in range(11):
    spheres[i].material.specular = 1.0
    spheres[i].material.roughness = i/10+0.1

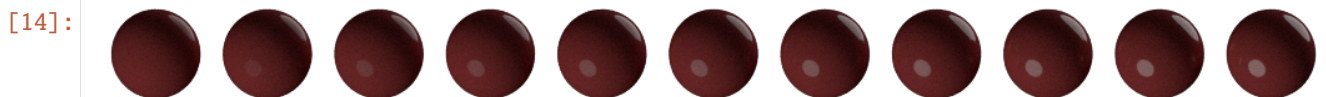
tracer.sample(scene2, samples=64, light_samples=40)
```



Vary specular from 0 to 1 with constant roughness.

```
[14]: for i in range(11):
    spheres[i].material.specular = i/10
    spheres[i].material.roughness = 0.1
    spheres[i].material.color=(.7,.1,.1)

tracer.sample(scene2, samples=64, light_samples=40)
```

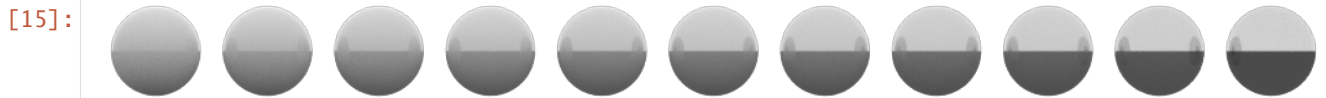


The following examples use cloudy lighting which places a bright hemisphere of light above the scene and a dim hemisphere of light below the scene.

Vary metal from 0 to 1 with a rough material. (metal materials look best when there is other geometry to reflect from the surface)

```
[15]: for i in range(11):
        spheres[i].material.specular = 1.0
        spheres[i].material.color=(.7,.7,.7)
        spheres[i].material.metal = i/10

scene2.lights = fresnel.light.cloudy()
tracer.sample(scene2, samples=64, light_samples=40)
```



Vary spec_trans from 0 to 1 with all other quantities constant.

```
[16]: for i in range(11):
        spheres[i].material.metal = 0.0
        spheres[i].material.spec_trans = i/10
        spheres[i].material.color=(.1,.1,.7)

tracer.sample(scene2, samples=64, light_samples=40)
```



Execute this notebook with **ipywidgets** installed and use the panel below to explore the material parameters and how they react to different lighting angles.

```
[17]: import ipywidgets

tracer.resize(450,450)

@ipywidgets.interact(color=ipywidgets.ColorPicker(value='#1c1c7f'),
                    primitive_color_mix=ipywidgets.FloatSlider(value=0.0, min=0.0,
↪max=1.0, step=0.1, continuous_update=False),
                    roughness=ipywidgets.FloatSlider(value=0.3, min=0.1, max=1.0,
↪step=0.1, continuous_update=False),
                    specular=ipywidgets.FloatSlider(value=0.5, min=0.0, max=1.0, step=0.
↪1, continuous_update=False),
                    spec_trans=ipywidgets.FloatSlider(value=0.0, min=0.0, max=1.0,
↪step=0.1, continuous_update=False),
                    metal=ipywidgets.FloatSlider(value=0, min=0.0, max=1.0, step=1.0,
↪continuous_update=False),
                    light_theta=ipywidgets.FloatSlider(value=5.5, min=0.0, max=2*math.
↪pi, step=0.1, continuous_update=False),
                    light_phi=ipywidgets.FloatSlider(value=0.8, min=0.0, max=math.pi,
↪step=0.1, continuous_update=False))
def test(color, primitive_color_mix, roughness, specular, spec_trans, metal, light_theta,
↪ light_phi):
```

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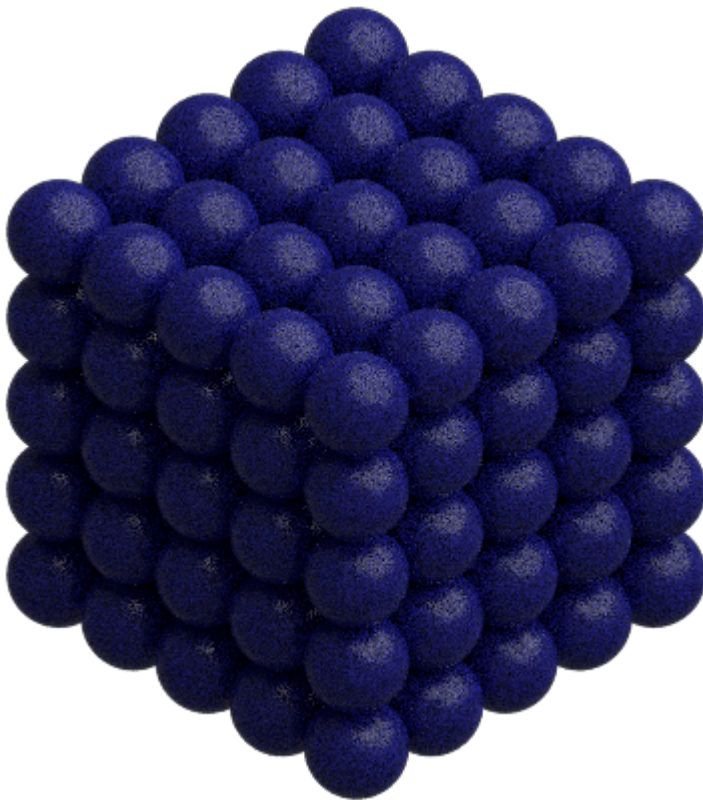
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```

r = int(color[1:3], 16)/255;
g = int(color[3:5], 16)/255;
b = int(color[5:7], 16)/255;
scene.lights[0].direction = (math.sin(light_phi)*math.cos(-light_theta),
                             math.cos(light_phi),
                             math.sin(light_phi)*math.sin(-light_theta))

scene.lights[1].theta = math.pi
geometry.material = fresnel.material.Material(color=fresnel.color.linear([r,g,b]),
                                              primitive_color_mix=primitive_color_
↪mix,
                                              roughness=roughness,
                                              metal=metal,
                                              specular=specular,
                                              spec_trans=spec_trans
                                              )
return tracer.sample(scene, samples=64, light_samples=1)

```



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OUTLINE MATERIALS

Each **geometry** has an associated **outline material** and an **outline width**. The **outline material** has all the same attributes as a normal material, but it is only applied in a thin line around each geometry primitive. The width of that line is the **outline width**.

```
[1]: import fresnel
import math
scene = fresnel.Scene()
position = []
for k in range(5):
    for i in range(5):
        for j in range(5):
            position.append([2*i, 2*j, 2*k])
geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
geometry.color[::4] = fresnel.color.linear([0.25,0.5,1])
geometry.color[1::4] = fresnel.color.linear([1,0.714,0.169])
geometry.color[2::4] = fresnel.color.linear([0.42,0.267,1])
geometry.color[3::4] = fresnel.color.linear([1,0.874,0.169])
geometry.material = fresnel.material.Material(solid=0.0, primitive_color_mix=1.0,
↪color=fresnel.color.linear([0,0,0]))
fresnel.light.cloudy();
scene.camera = fresnel.camera.Orthographic.fit(scene)
```

10.1 Enabling outlines

The default **outline width** is 0. Set a non-zero outline width to enable the outlines.

```
[2]: geometry.outline_width
```

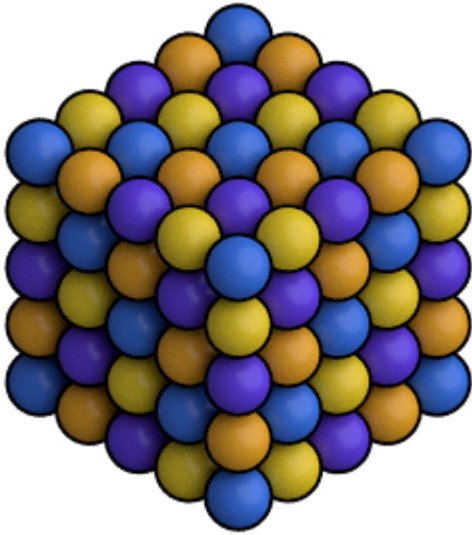
```
[2]: 0.0
```

The **outline width** is in distance units in the same coordinate system as scene. The is *width* units wide perpendicular to the view direction. Outlines enhance the separation between primitives visually. They work well with diffuse and solid colored primitives.

```
[3]: geometry.outline_width = 0.12
```

```
[4]: fresnel.pathtrace(scene, w=300, h=300,light_samples=40)
```

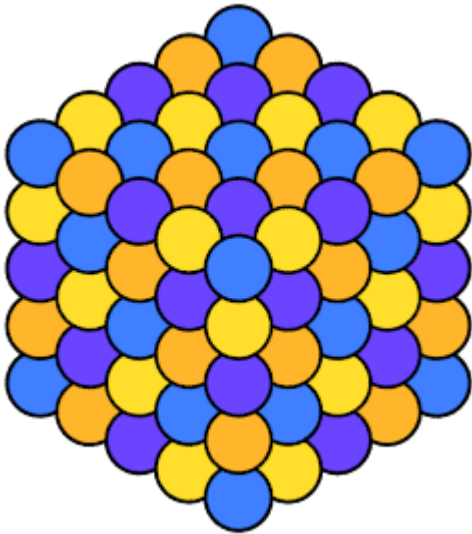
[4]:



```
[5]: geometry.material.solid = 1.0
```

```
[6]: fresnel.preview(scene, w=300, h=300)
```

[6]:



10.2 Outline material properties

The default **outline material** is a solid black.

```
[7]: geometry.outline_material.color
```

```
[7]: (0.0, 0.0, 0.0)
```

```
[8]: geometry.outline_material.solid
```

```
[8]: 1.0
```

```
[9]: geometry.outline_material.primitive_color_mix
```

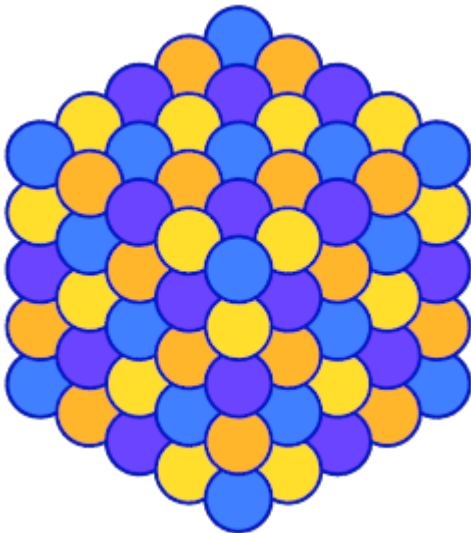
```
[9]: 0.0
```

The **outline material** has all the same properties as a normal material.

```
[10]: geometry.outline_material.color = fresnel.color.linear(fresnel.color.linear([0.08,0.341,  
→0.9]))
```

```
[11]: fresnel.preview(scene, w=300, h=300)
```

```
[11]:
```

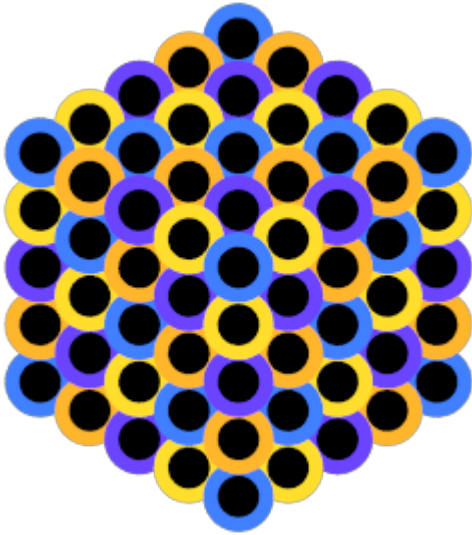


Outlines may be colored by the primitives:

```
[12]: geometry.material.primitive_color_mix = 0.0  
geometry.outline_material.primitive_color_mix = 1.0  
geometry.outline_width = 0.4
```

```
[13]: fresnel.preview(scene, w=300, h=300)
```

[13]:

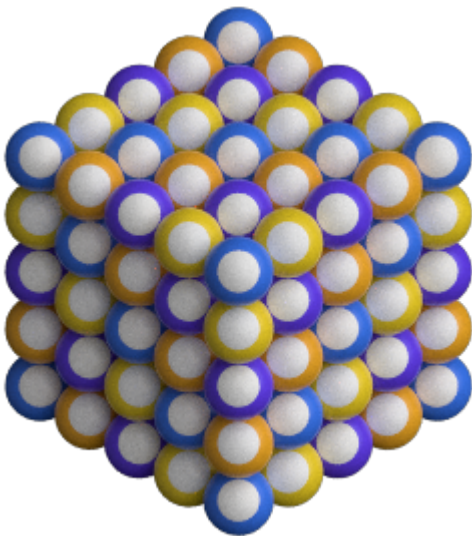


Outlines may have diffuse shading:

```
[14]: geometry.material.color = fresnel.color.linear([1,1,1])  
       geometry.material.solid = 0  
       geometry.outline_material.solid = 0
```

```
[15]: fresnel.pathtrace(scene, w=300, h=300, light_samples=40)
```

[15]:



Or be metallic:

```
[16]: geometry.material.color = fresnel.color.linear([0.08,0.341,0.9])  
  
       geometry.outline_material.solid = 0  
       geometry.outline_material.color = [0.95,0.95,0.95]
```

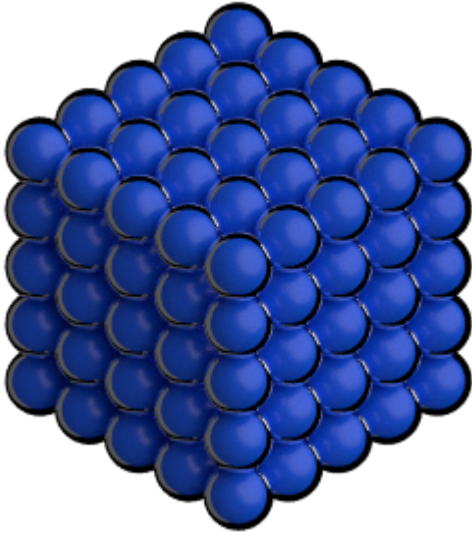
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```
geometry.outline_material.roughness = 0.1  
geometry.outline_material.metal = 1  
geometry.outline_material.primitive_color_mix = 0.0  
geometry.outline_width = 0.2
```

```
[17]: fresnel.pathtrace(scene, w=300, h=300, light_samples=40)
```

```
[17]:
```



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SCENE PROPERTIES

Each **Scene** has a **background color** and **alpha**, **lights**, and a **camera**.

```
[1]: import fresnel
import math
scene = fresnel.Scene()
position = []
for i in range(6):
    position.append([2*math.cos(i*2*math.pi / 6), 2*math.sin(i*2*math.pi / 6), 0])

geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
geometry.material = fresnel.material.Material(solid=0.0, color=fresnel.color.linear([1,0.
↪874,0.169]))
geometry.outline_width = 0.12
scene.camera = fresnel.camera.Orthographic.fit(scene)
```

11.1 Background color and alpha

The default **background color** is black (0,0,0) and the **background alpha** is 0 (transparent).

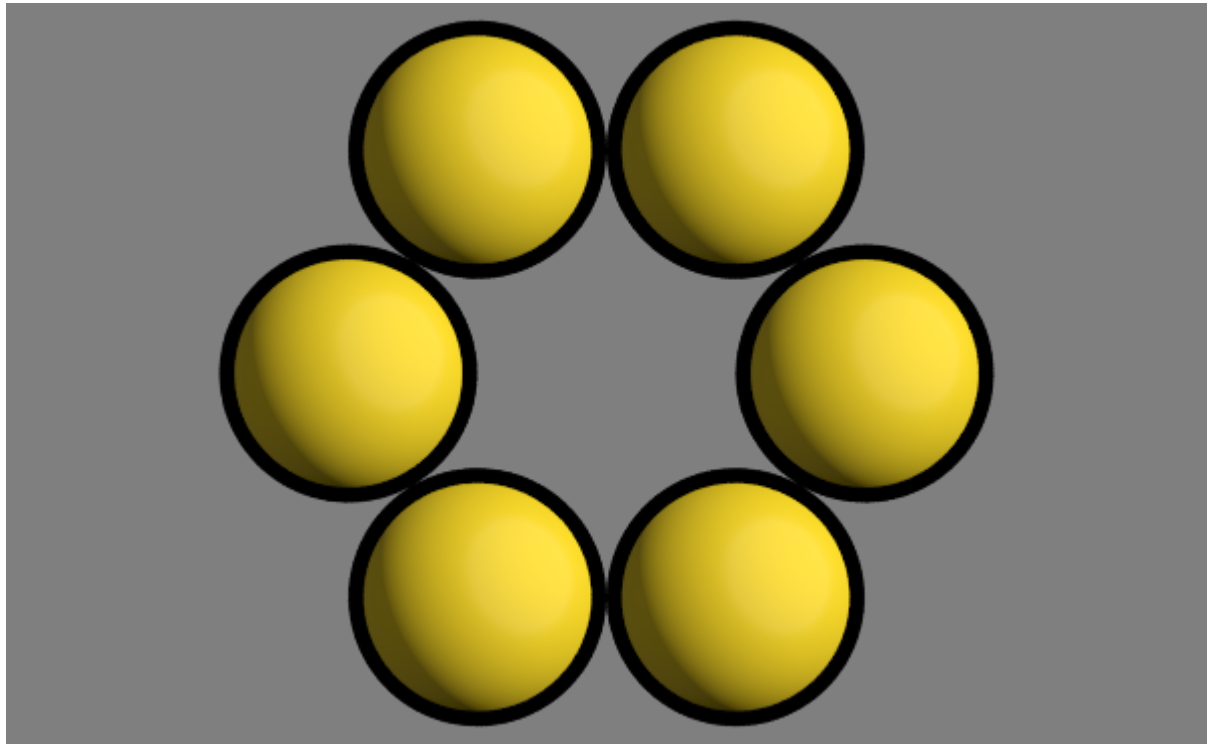
```
[2]: scene.background_color
[2]: array([0., 0., 0.], dtype=float32)
```

```
[3]: scene.background_alpha
[3]: 0.0
```

The background color is applied to any pixel in the output image where no object is present. Change the **background alpha** to only partially transparent:

```
[4]: scene.background_alpha = 0.5
[5]: fresnel.preview(scene)
```

[5]:

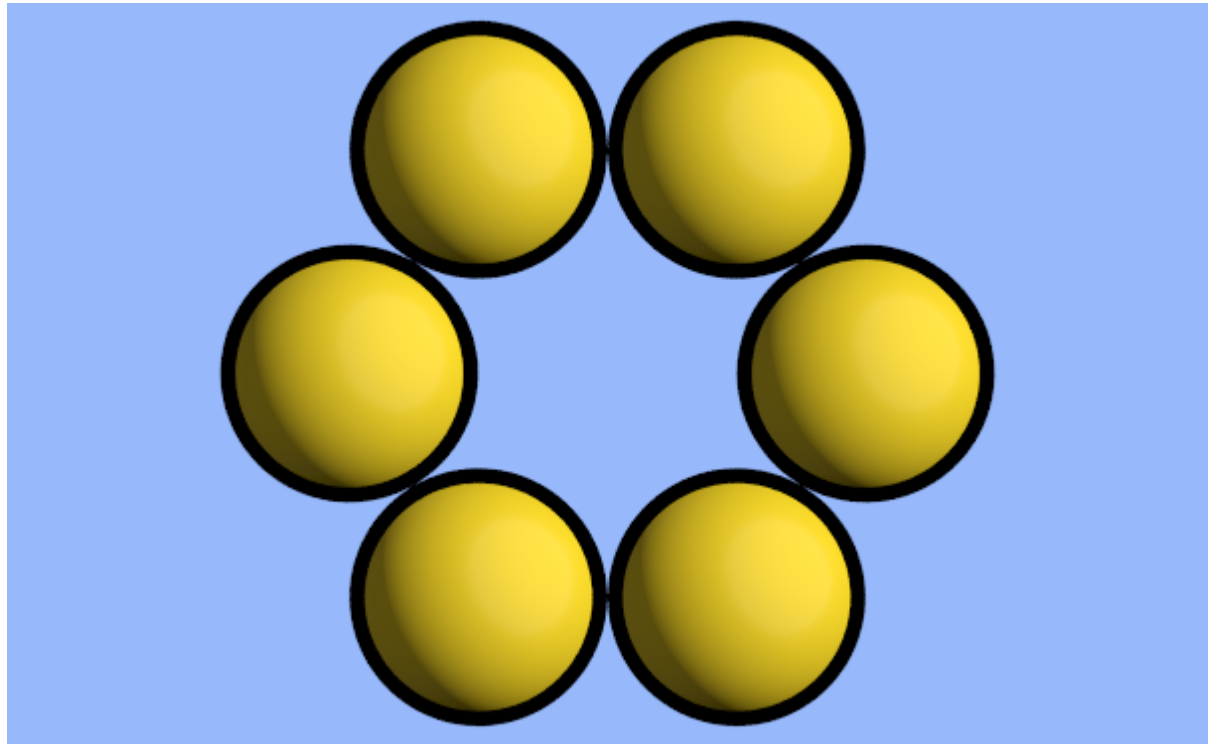


Set a solid background color:

```
[6]: scene.background_alpha = 1.0  
scene.background_color = fresnel.color.linear([0.592, 0.722, 0.98])
```

```
[7]: fresnel.preview(scene)
```

[7]:



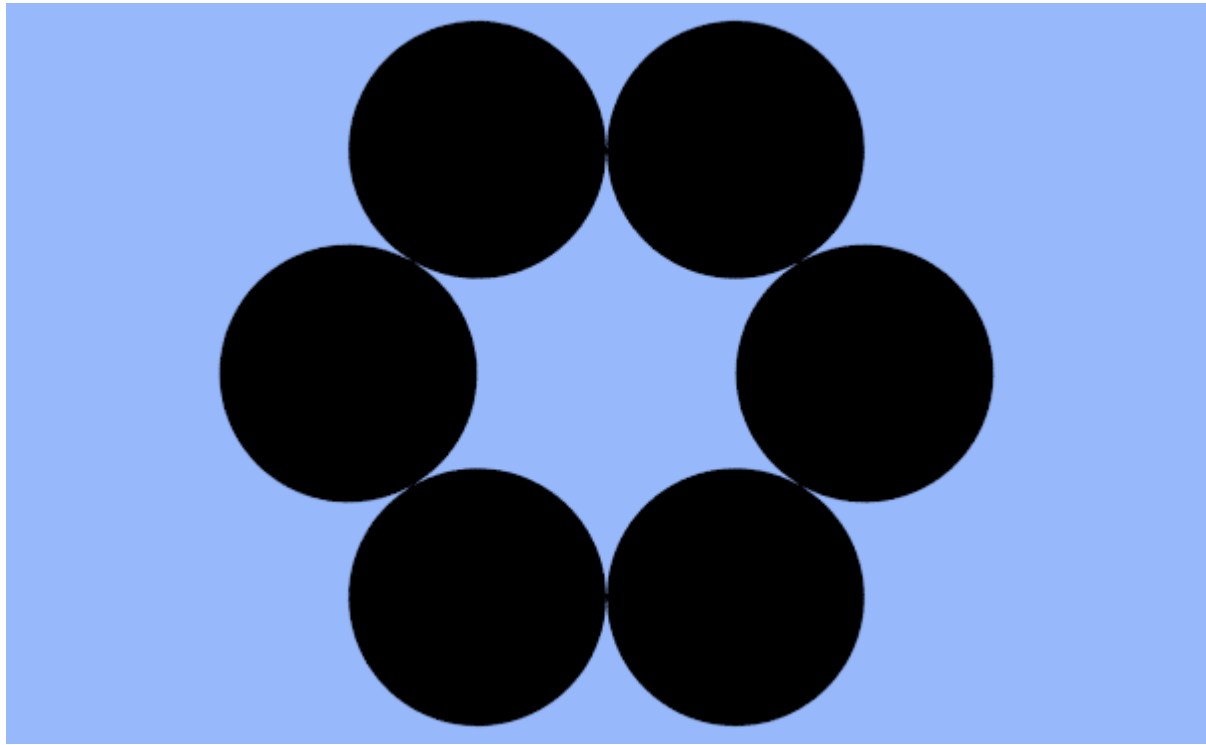
11.2 Light sources

Light sources light the objects in the scene. Without lights, all objects are black.

[8]: `scene.lights.clear()`

[9]: `fresnel.preview(scene)`

[9]:

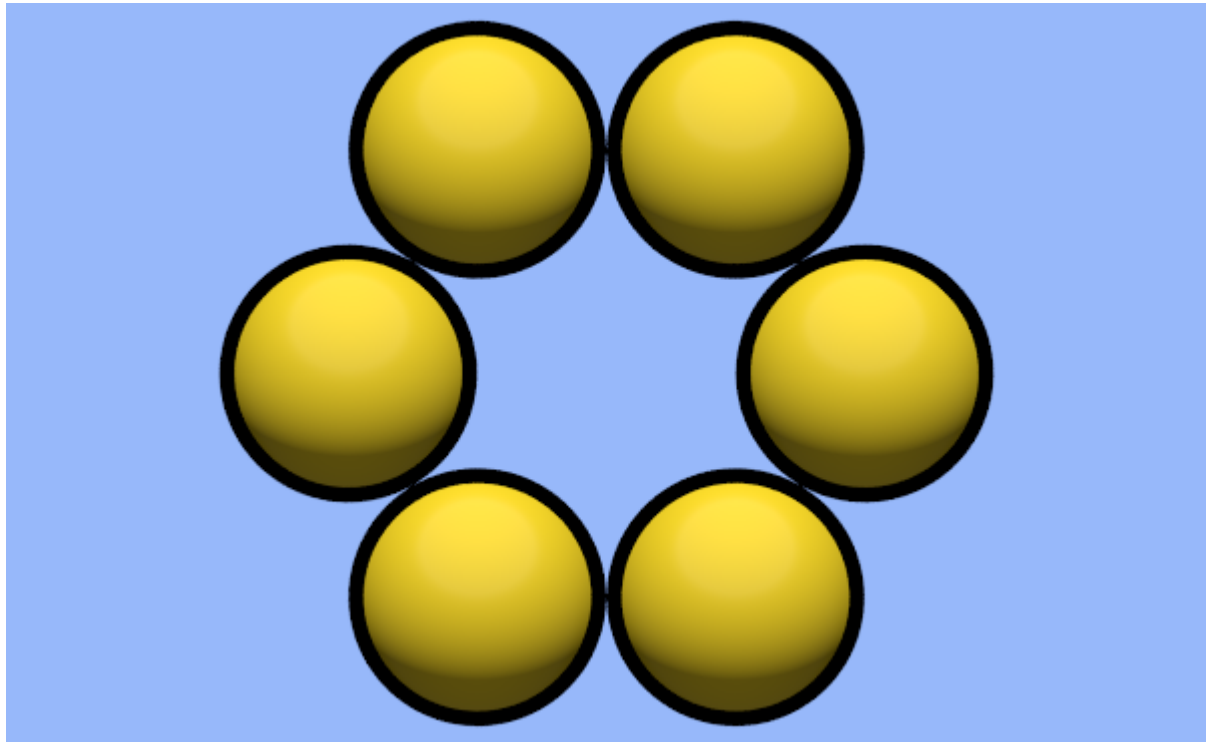


Fresnel defines several standard lighting setups that may be easily applied.

```
[10]: scene.lights = fresnel.light.butterfly()
```

```
[11]: fresnel.preview(scene)
```

[11]:

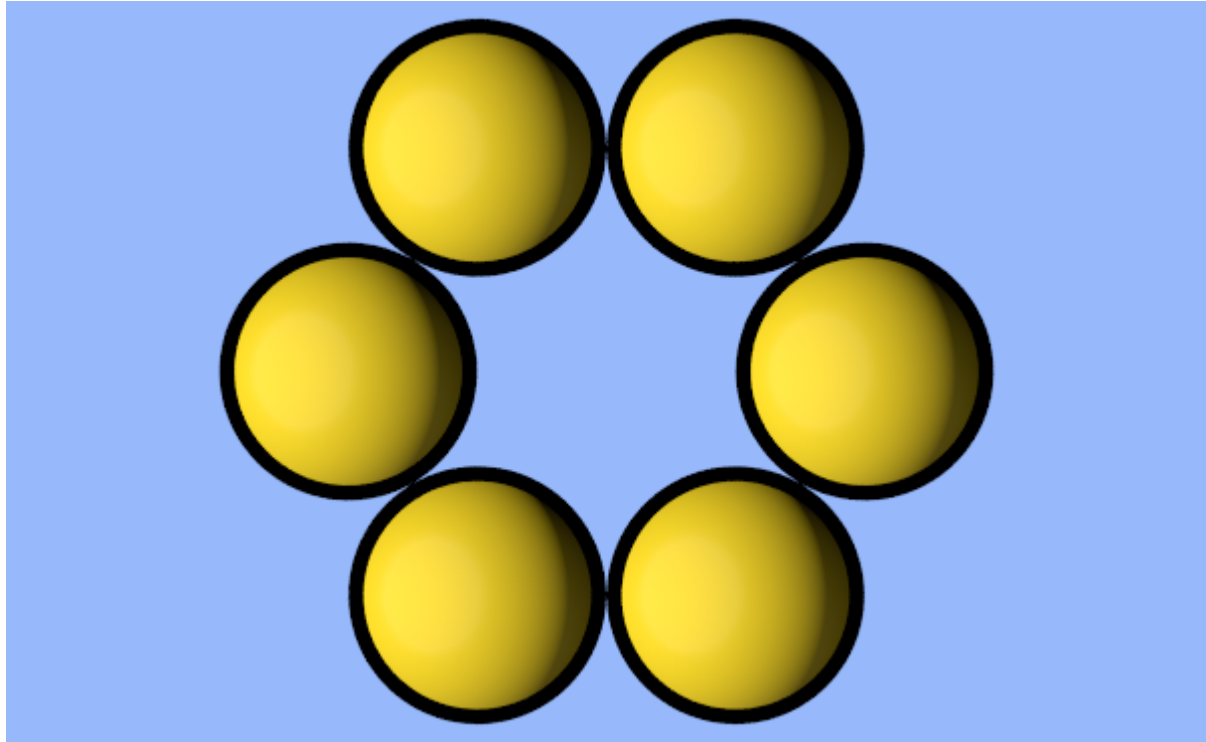


You can modify individual lights.

```
[12]: scene.lights[0].direction = (-1, 0, 1)
```

```
[13]: fresnel.preview(scene)
```

```
[13]:
```



11.3 Camera

The camera defines the view to render into the scene. The default camera is an orthographic camera at (0,0,100), look at (0,0,0), and has a height of 100:

```
[14]: scene2 = fresnel.Scene()
print(scene2.camera)
```

```
fresnel.camera.Orthographic(position=(0.0, 0.0, 100.0), look_at=(0.0, 0.0, 0.0), up=(0.0,
↪ 1.0, 0.0), height=100.0)
```

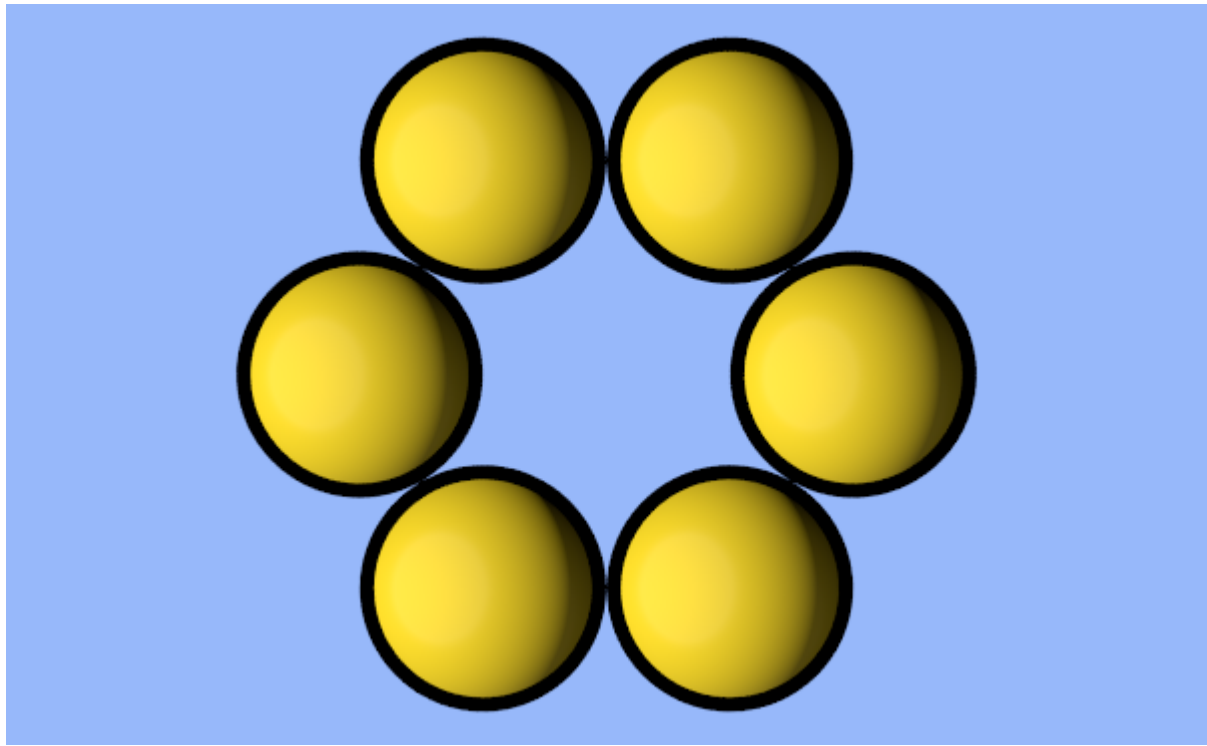
You can automatically fit an orthographic camera to the scene with `camera.Orthographic.fit`. Call it **after** defining all of the geometry in your scene.

```
[15]: scene.camera = fresnel.camera.Orthographic.fit(scene)
```

A **camera** is defined by its *position*, *look-at point*, *up vector* and *height* of the view into the scene. All of these quantities are in scene coordinates.

```
[16]: scene.camera = fresnel.camera.Orthographic(position=(0,0,2), look_at=(0,0,0), up=(0,1,0),
↪ height=6)
fresnel.preview(scene)
```

[16]:

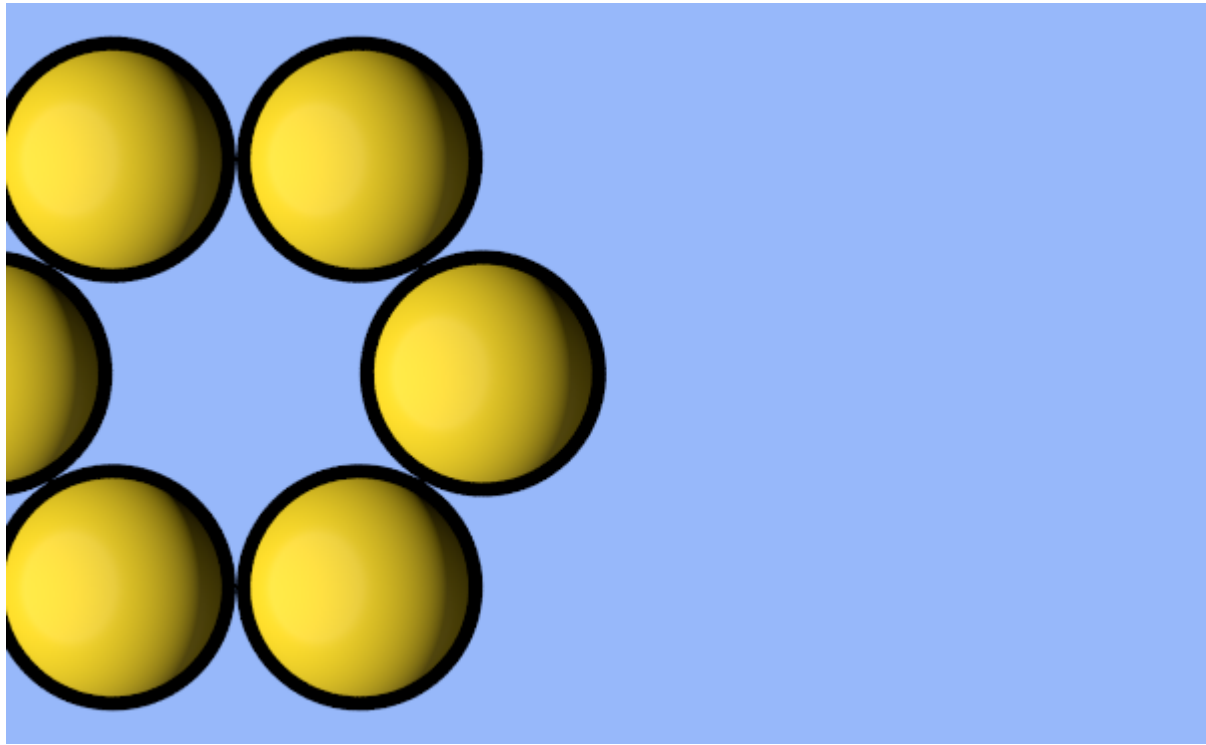


You can modify these parameters individually.

```
[17]: scene.camera.position = (3, 0, 10)  
scene.camera.look_at=(3,0,0)
```

```
[18]: fresnel.preview(scene)
```

[18]:



Print the full representation of the camera.

[19]: `print(repr(scene.camera))`

```
fresnel.camera.Orthographic(position=(3.0, 0.0, 10.0), look_at=(3.0, 0.0, 0.0), up=(0.0, 1.0, 0.0), height=6.0)
```

You can copy and paste this text to reproduce the same camera elsewhere.

[20]: `scene.camera = fresnel.camera.Orthographic(position=(3.0, 0.0, 10.0),
look_at=(3.0, 0.0, 0.0),
up=(0.0, 1.0, 0.0),
height=6.0)`

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LIGHTING SETUPS

Each **Scene** has associated **lights**. The lights control how the objects in a scene is lit.

```
[1]: import fresnel
import math
import matplotlib, matplotlib.cm
from matplotlib import pyplot
%matplotlib inline
import numpy

device = fresnel.Device()
scene = fresnel.Scene(device)
position = []
for k in range(5):
    for i in range(5):
        for j in range(5):
            position.append([2*i, 2*j, 2*k])
geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
geometry.material = fresnel.material.Material(primitive_color_mix=1.0, color=(1,1,1))
mapper = matplotlib.cm.ScalarMappable(norm = matplotlib.colors.Normalize(vmin=0, vmax=1,
↪clip=True),
                                     cmap = matplotlib.cm.get_cmap(name='viridis'))

v = numpy.linspace(0,1,len(position))
geometry.color[:] = fresnel.color.linear(mapper.to_rgba(v))
scene.camera = fresnel.camera.Orthographic.fit(scene, view='isometric')
tracer = fresnel.tracer.Path(device, w=450, h=450)
```

12.1 Lighting presets

Fresnel defines many lighting presets that use classic photography techniques to light the scene. Create a setup and assign it to the Scene's lights.

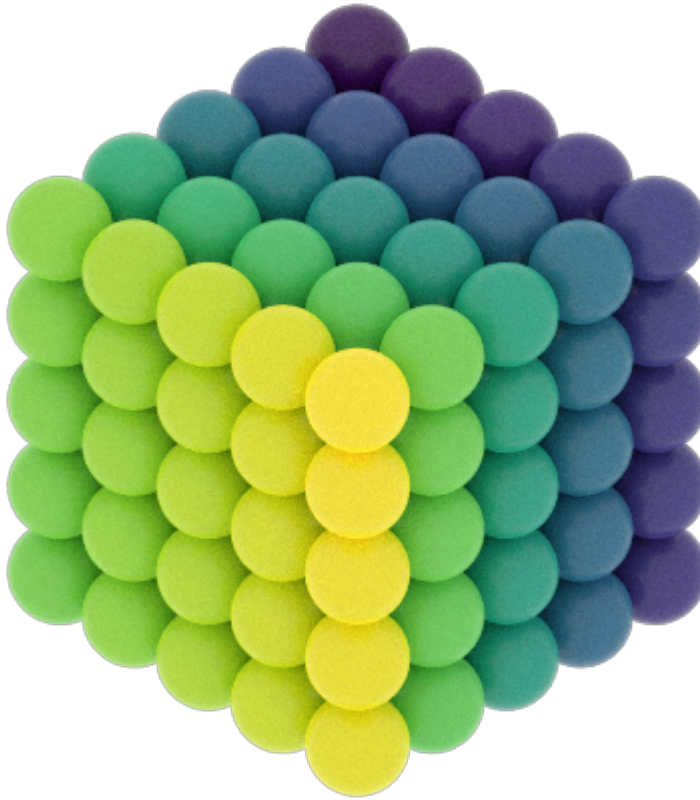
The images in these examples are noisy because of the small number of samples. Increase the number of samples to obtain less noisy images.

12.1.1 Light box

A light box lights the scene equally from all sides. This type of lighting is commonly used product photography.

```
[2]: scene.lights = fresnel.light.lightbox()  
tracer.sample(scene, samples=64, light_samples=10)
```

[2]:

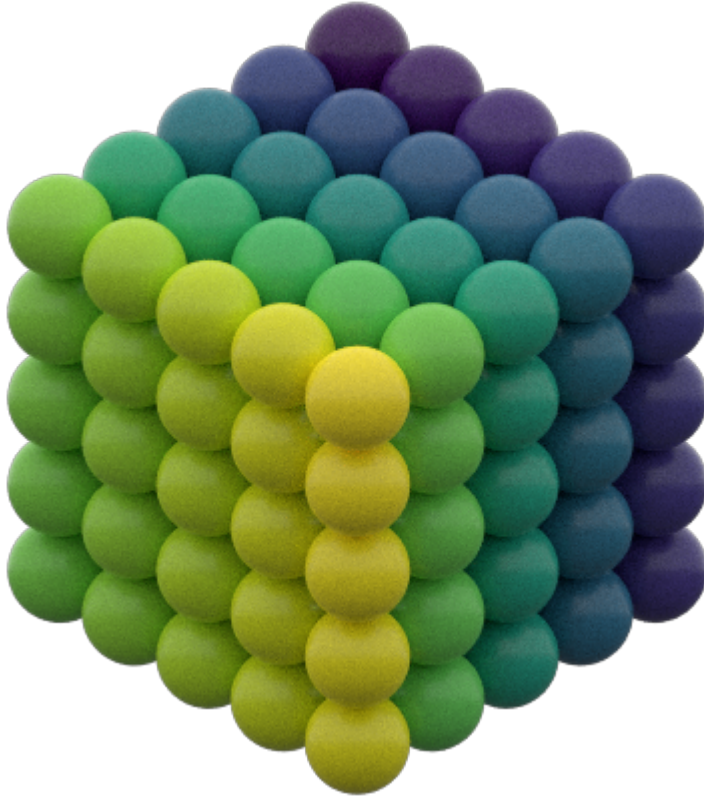


12.1.2 Cloudy

Cloudy lighting mimics a cloudy day. Strong light comes from all directions above, while weak light comes from below.

```
[3]: scene.lights = fresnel.light.cloudy()  
tracer.sample(scene, samples=64, light_samples=10)
```

[3]:

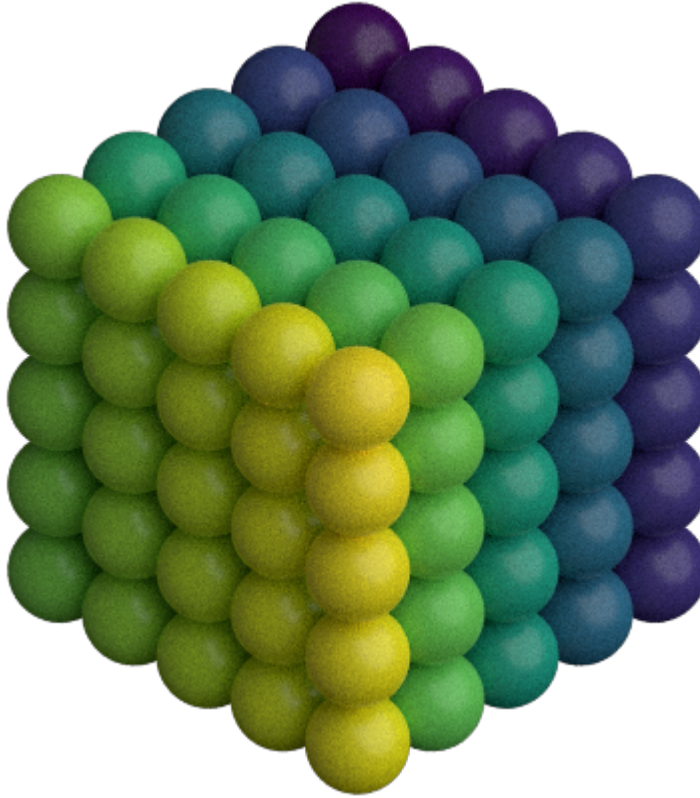


12.1.3 Rembrandt

Rembrandt lighting places the key light 45 degrees to one side and slightly up.

```
[4]: scene.lights = fresnel.light.rembrandt()  
tracer.sample(scene, samples=64, light_samples=10)
```

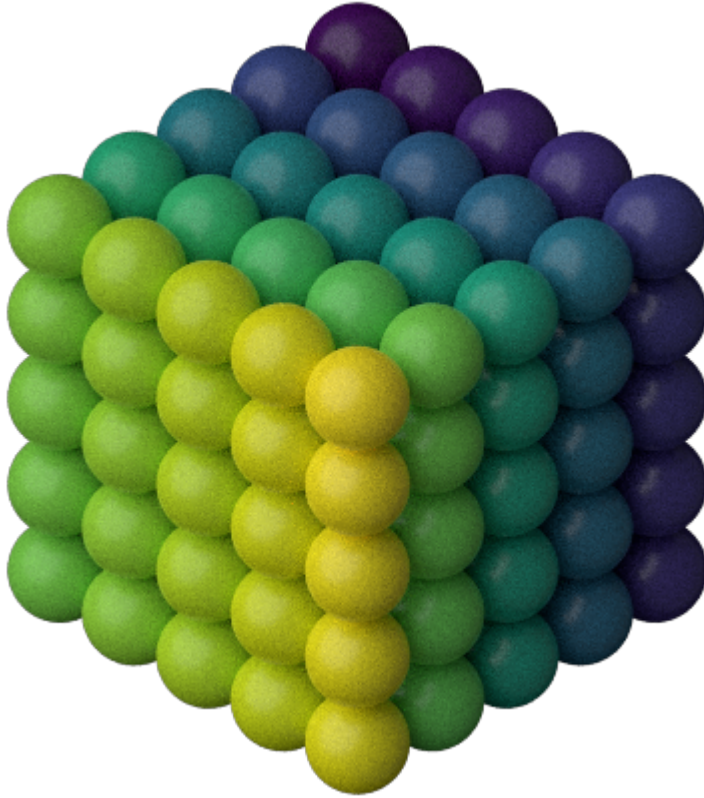
[4]:



Use the *side* argument specify which side to place the key light on.

```
[5]: scene.lights = fresnel.light.rembrandt(side='left')
      tracer.sample(scene, samples=64, light_samples=10)
```

[5]:

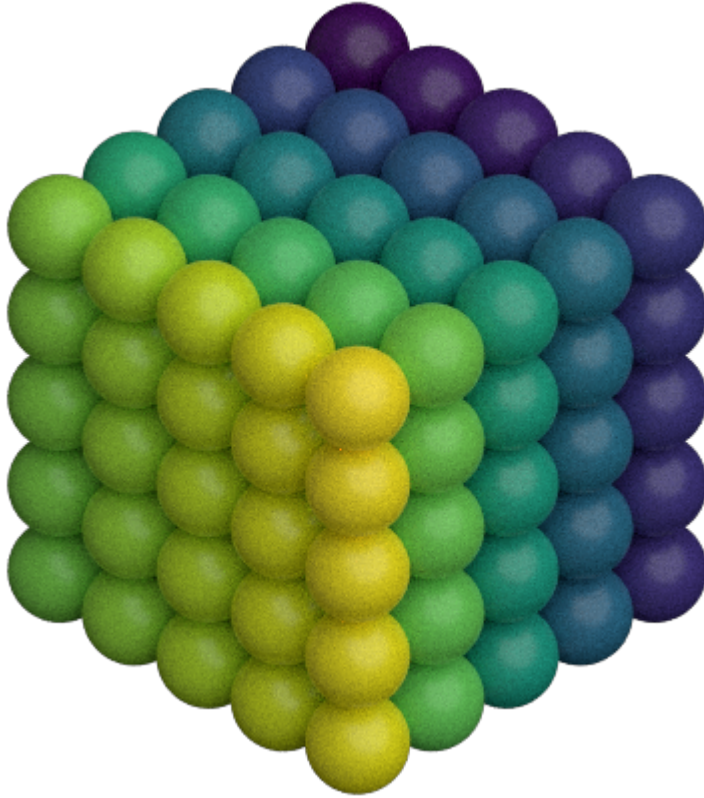


12.1.4 Loop lighting

Loop lighting places the key light slightly to one side and slightly up.

```
[6]: scene.lights = fresnel.light.loop()  
tracer.sample(scene, samples=64, light_samples=10)
```

[6]:

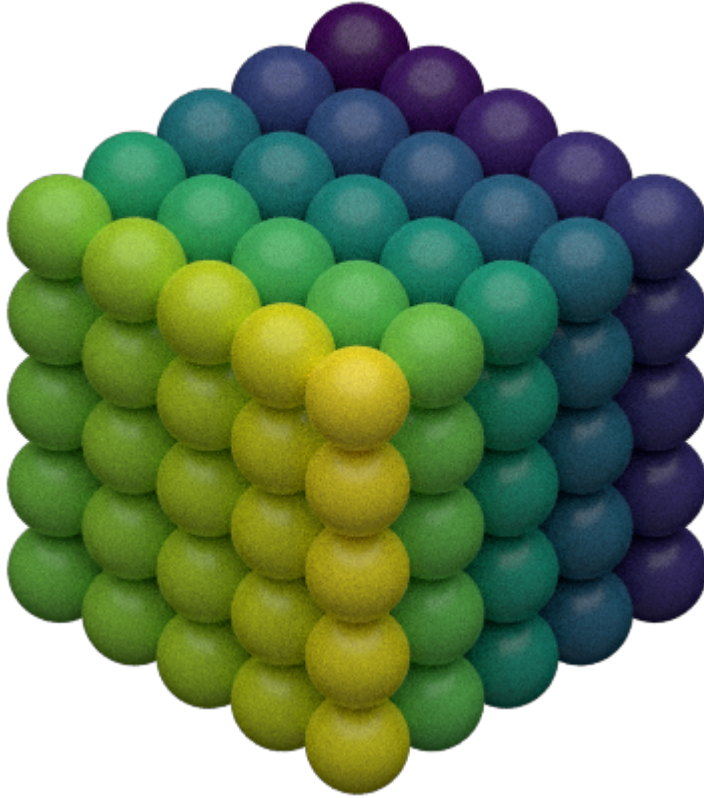


12.1.5 Butterfly lighting

Butterfly lighting places the key light high above the camera.

```
[7]: scene.lights = fresnel.light.butterfly()  
tracer.sample(scene, samples=64, light_samples=10)
```

[7]:

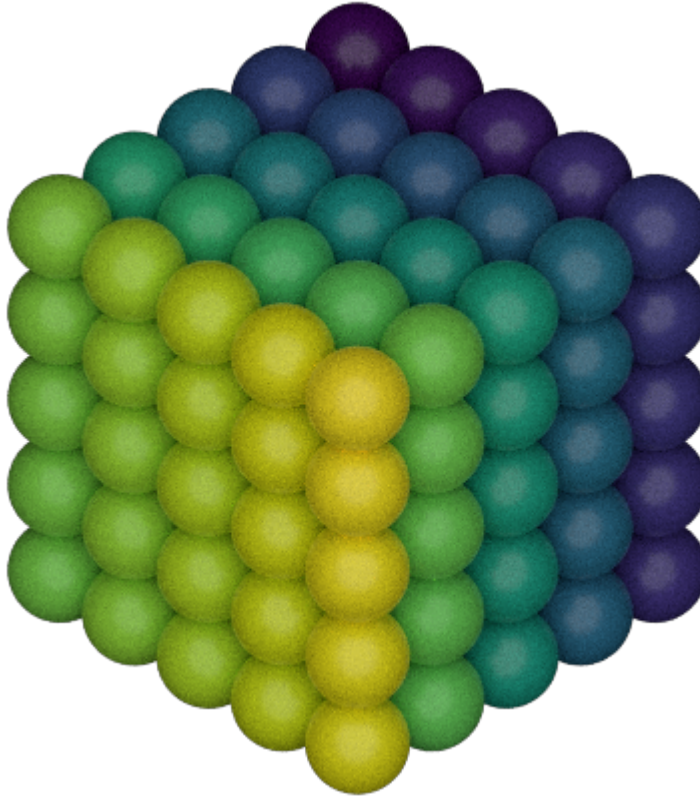


12.1.6 Ring lighting

The ring lighting setup provides a strong front area light. This type of lighting is common in fashion photography.

```
[8]: scene.lights = fresnel.light.ring()  
tracer.sample(scene, samples=64, light_samples=10)
```


[8]:



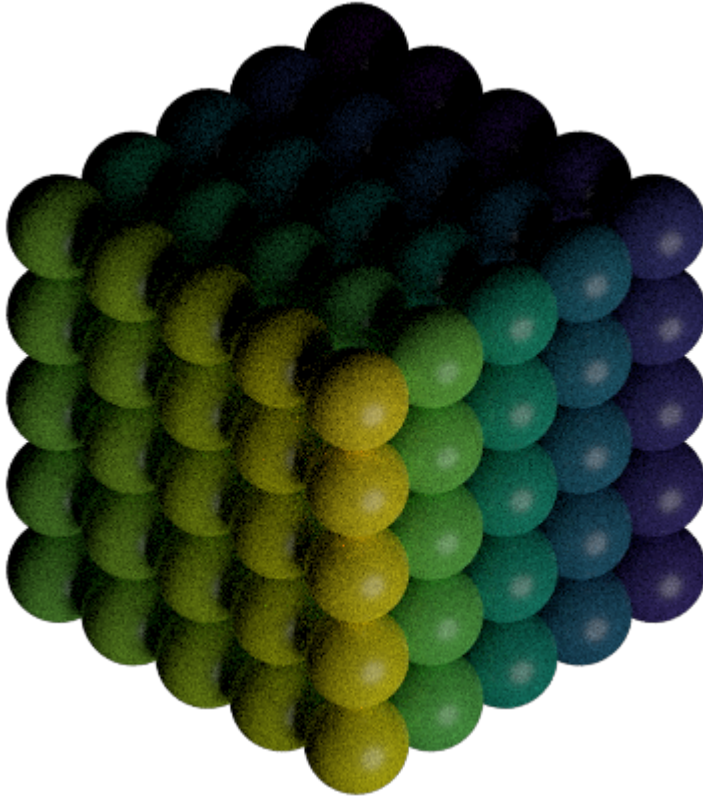
12.2 Custom lights

You can define your own custom lights. Provide a *direction* vector pointing to the light in the coordinate system of the camera (+x points to the right, +y points up, and +z points out of the screen). The light color defines both the color (RGB) and the intensity of the light in a linear sRGB color space.

```
[9]: my_lights = [fresnel.light.Light(direction=(1,-1,1), color=(1,1,1))]  
scene.lights = my_lights
```

```
[10]: tracer.sample(scene, samples=64, light_samples=10)
```

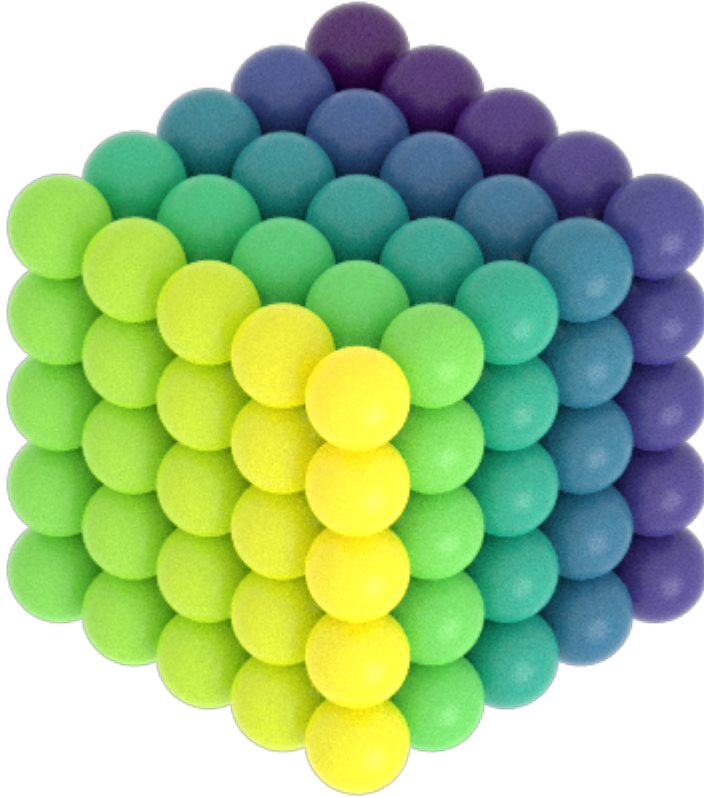

[10]:



The shadows are very dark. Add another light to fill them in. You can access the scene's lights directly. The value *theta* defines the half angle width of the light source. Large lights provide soft shadows.

```
[11]: scene.lights.append(fresnel.light.Light(direction=(0,0,1), color=(1,1,1), theta=3.14))
tracer.sample(scene, samples=64, light_samples=10)
```

[11]:

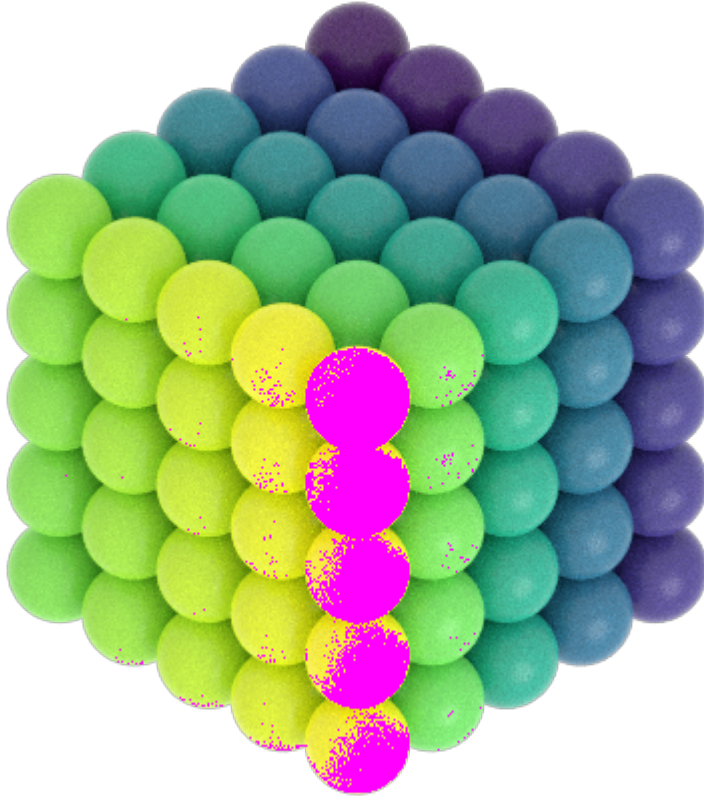


This image is overexposed.

Highlight warnings show overexposed areas of the image as a special color (default: magenta).

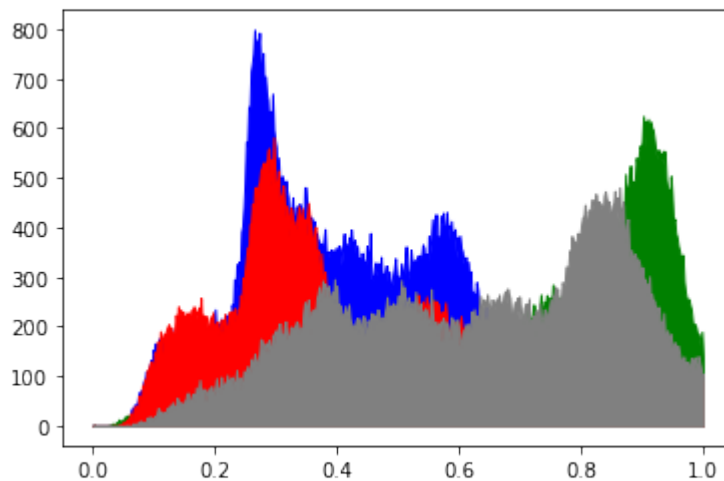
```
[12]: tracer.enable_highlight_warning()  
tracer.render(scene)
```

[12]:



If the histogram is blocking up at 1.0, there are overexposed highlights.

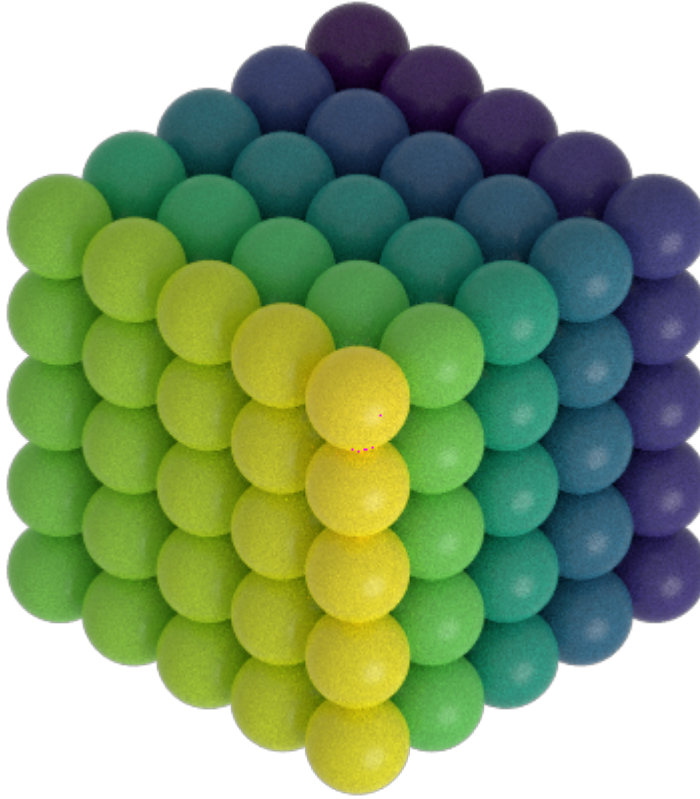
```
[13]: L, bins = tracer.histogram()
pyplot.fill_between(bins, L[:,3], color='blue');
pyplot.fill_between(bins, L[:,2], color='green');
pyplot.fill_between(bins, L[:,1], color='red');
pyplot.fill_between(bins, L[:,0], color='gray');
```



Reduce the intensity of the light to correctly expose the image.

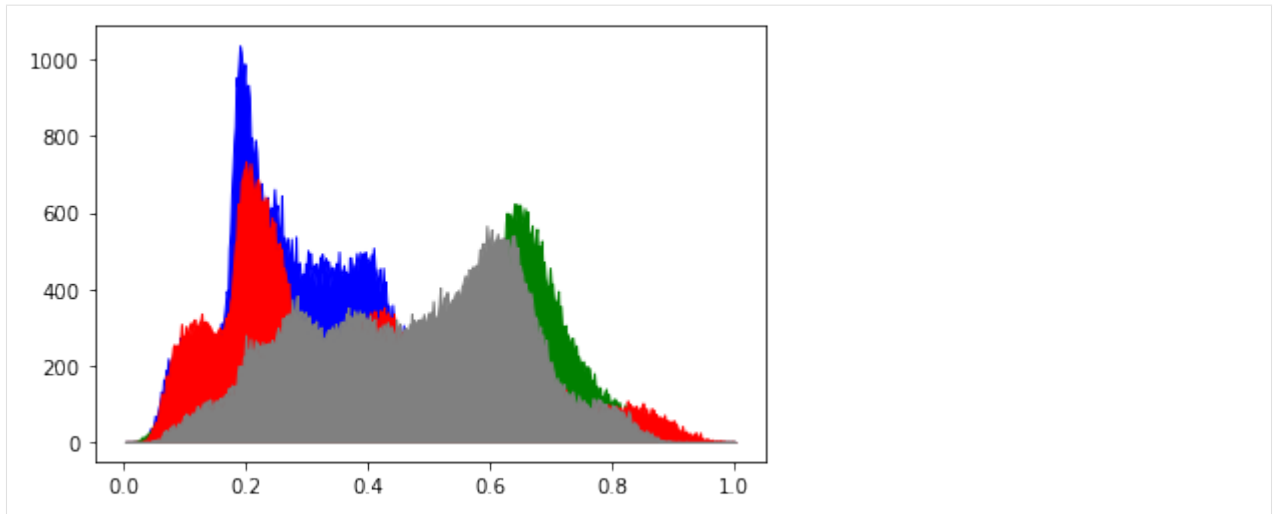
```
[14]: scene.lights[1].color=(0.45,0.45,0.45)
      tracer.sample(scene, samples=64, light_samples=10)
```

[14]:



Now there are no clipping warnings and the histogram shows a perfectly exposed image.

```
[15]: L, bins = tracer.histogram()
      pyplot.fill_between(bins, L[:,3], color='blue');
      pyplot.fill_between(bins, L[:,2], color='green');
      pyplot.fill_between(bins, L[:,1], color='red');
      pyplot.fill_between(bins, L[:,0], color='gray');
```

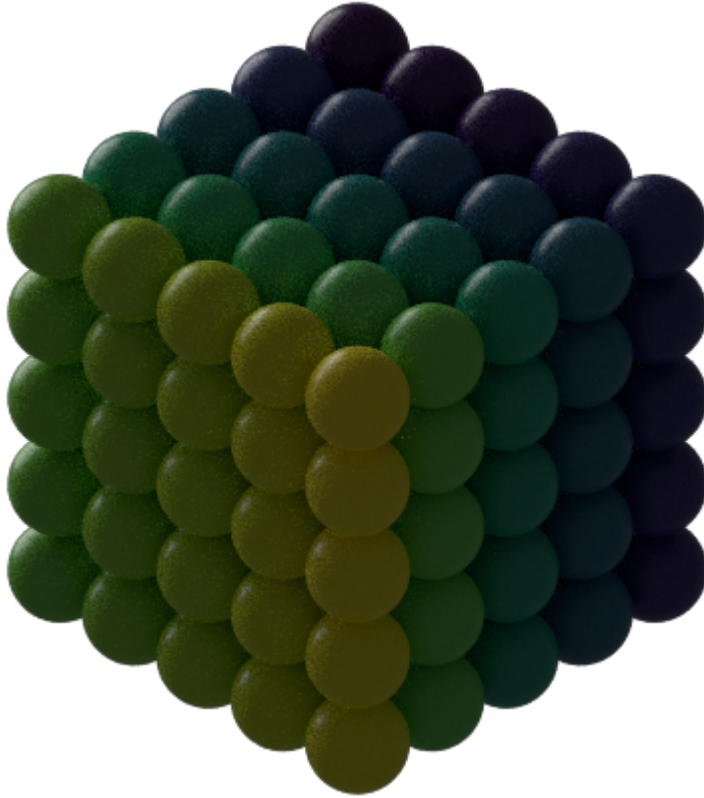


`scene.lights` has typical sequence like behavior. You can assign a sequence of `Light` objects to it, append lights to it, and loop over the lights in it. For example, reverse the direction of every light:

```
[16]: for l in scene.lights:
        d = l.direction;
        l.direction = (-d[0], -d[1], -d[2])
```

```
[17]: scene.lights[1].color=(0.05,0.05,0.05)
        tracer.disable_highlight_warning()
        tracer.sample(scene, samples=64, light_samples=10)
```

[17]:



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SPHERE

```
[ ]: import fresnel
     scene = fresnel.Scene()
```

The **sphere geometry** defines a set of N spheres. Each sphere has its own *position*, *radius*, and *color*.

```
[ ]: geometry = fresnel.geometry.Sphere(scene, N=3)
     geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),
                                                roughness=0.8)
```

13.1 Geometric properties

position defines the position of each sphere.

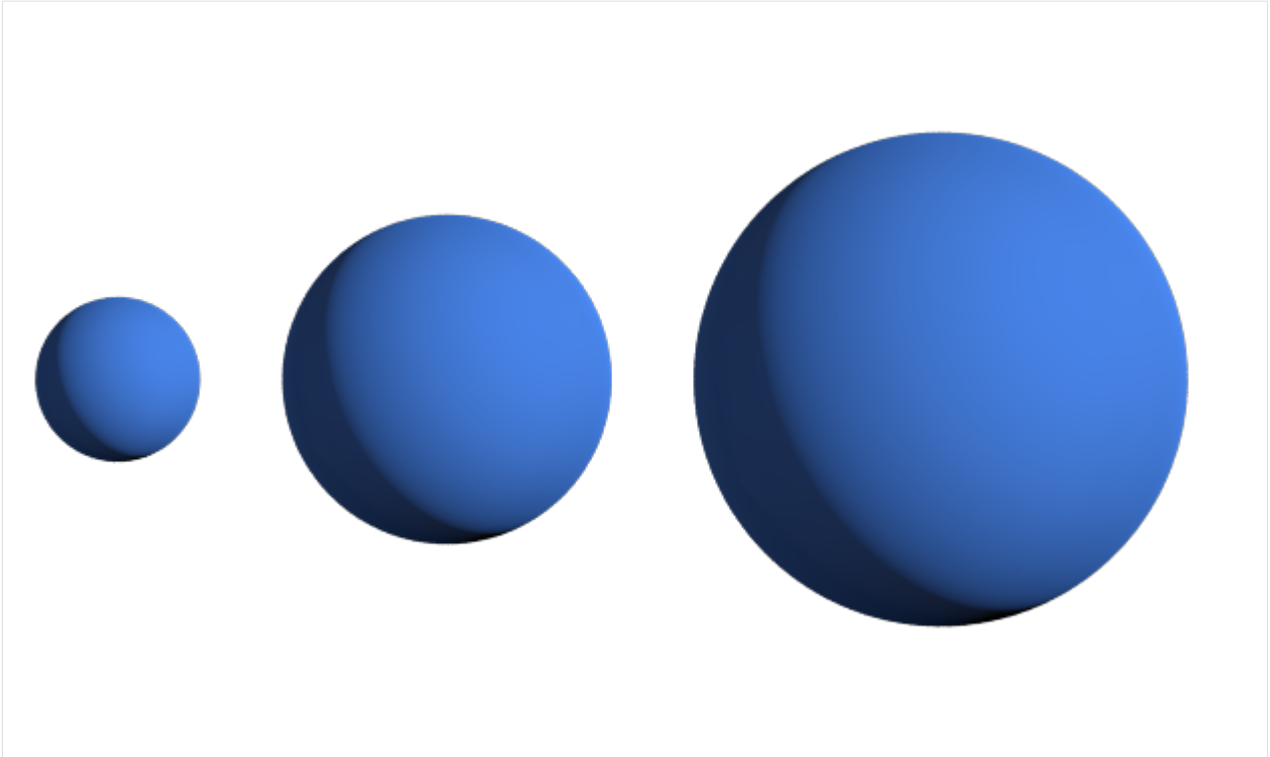
```
[ ]: geometry.position[:] = [[-2,0,0], [0, 0, 0], [3, 0, 0]]
```

radius sets the radius of each sphere.

```
[ ]: geometry.radius[:] = [0.5, 1.0, 1.5]
```

```
[5]: scene.camera = fresnel.camera.Orthographic.fit(scene, view='front', margin=0.5)
     fresnel.preview(scene)
```

[5]:



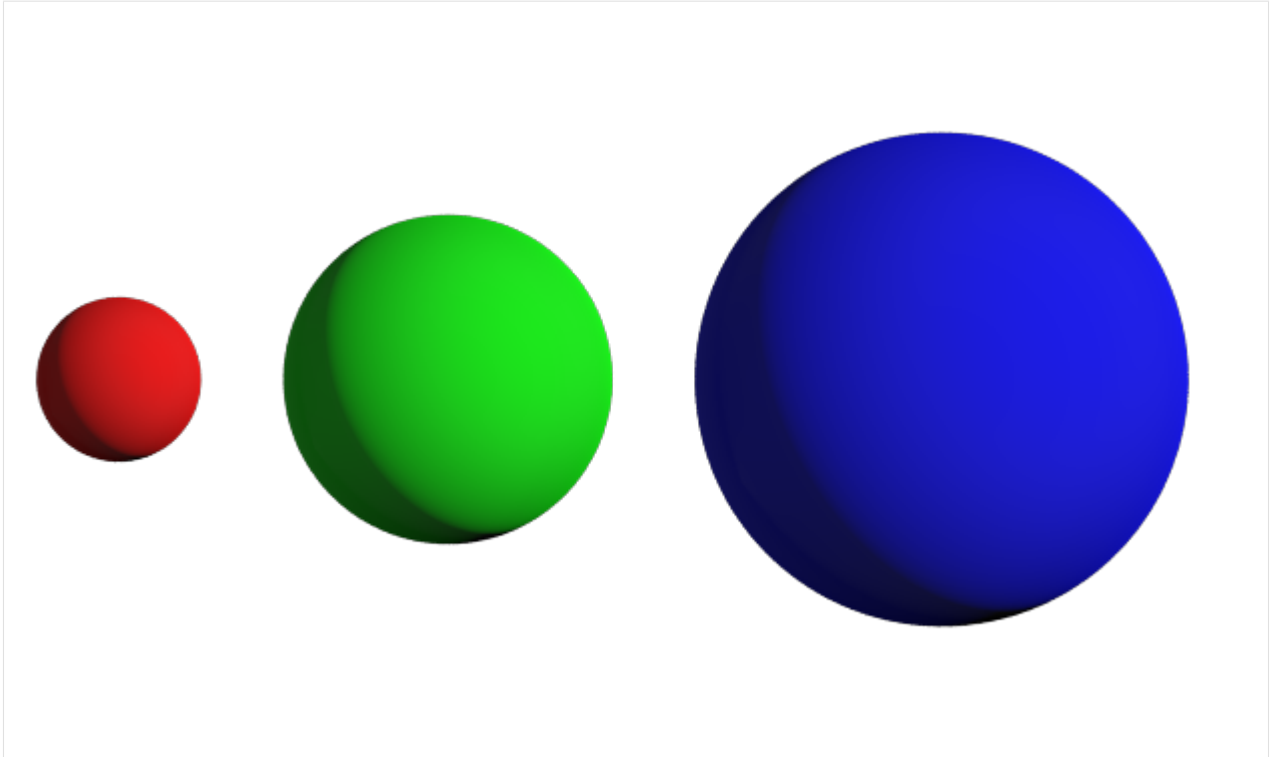
13.2 Color

color sets the color of each sphere (when when *primitive_color_mix* > 0)

```
[6]: geometry.color[:] = fresnel.color.linear([[0.9,0,0], [0, 0.9, 0], [0, 0, 0.9]])  
      geometry.material.primitive_color_mix = 1.0
```

```
[7]: fresnel.preview(scene)
```


[7]:



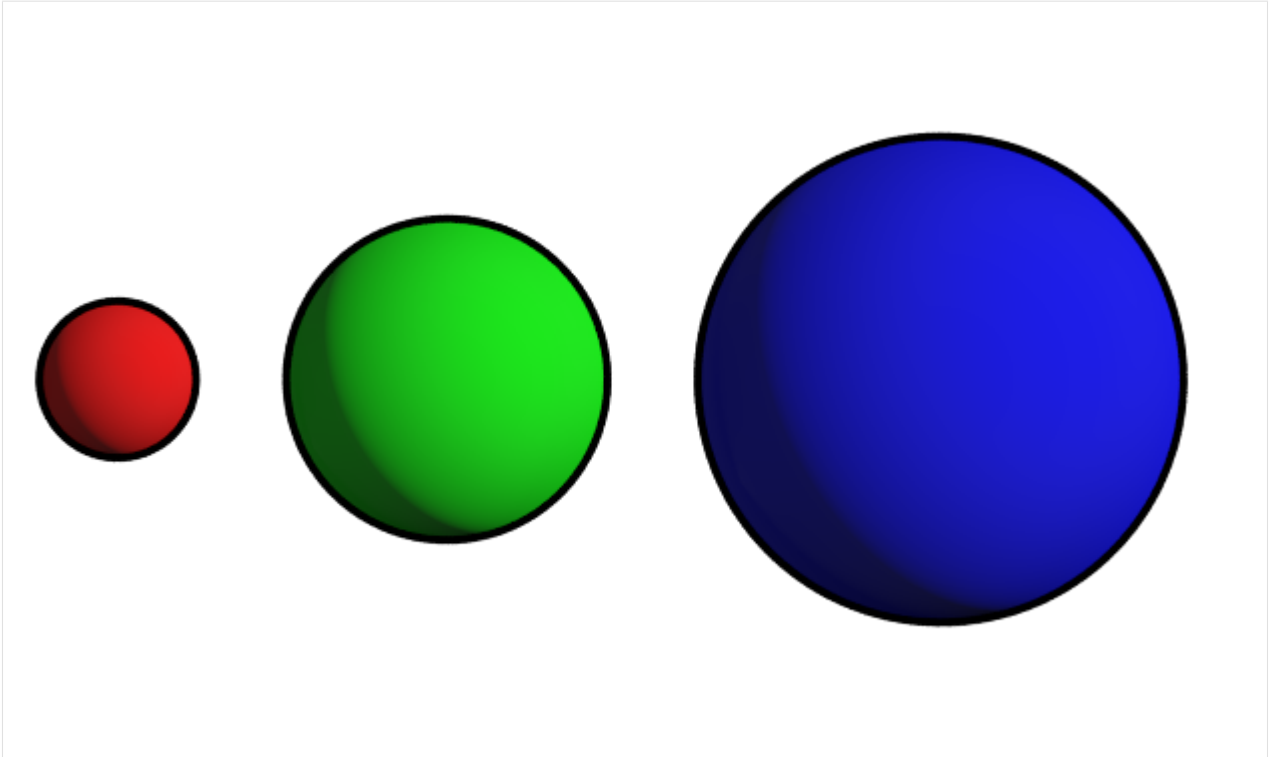
13.3 Outlines

Outlines are applied on the outer edge of the sphere in the view plane.

```
[8]: geometry.outline_width = 0.05
```

```
[9]: fresnel.preview(scene)
```

[9]:



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CYLINDER

```
[1]: import fresnel
scene = fresnel.Scene()
```

The **cylinder geometry** defines a set of N spherocylinders. Each spherocylinder is defined by two end points and has its own *radius*, and end point *colors*.

```
[2]: geometry = fresnel.geometry.Cylinder(scene, N=3)
geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),
                                             roughness=0.8)
```

14.1 Geometric properties

points defines the end points of each cylinder.

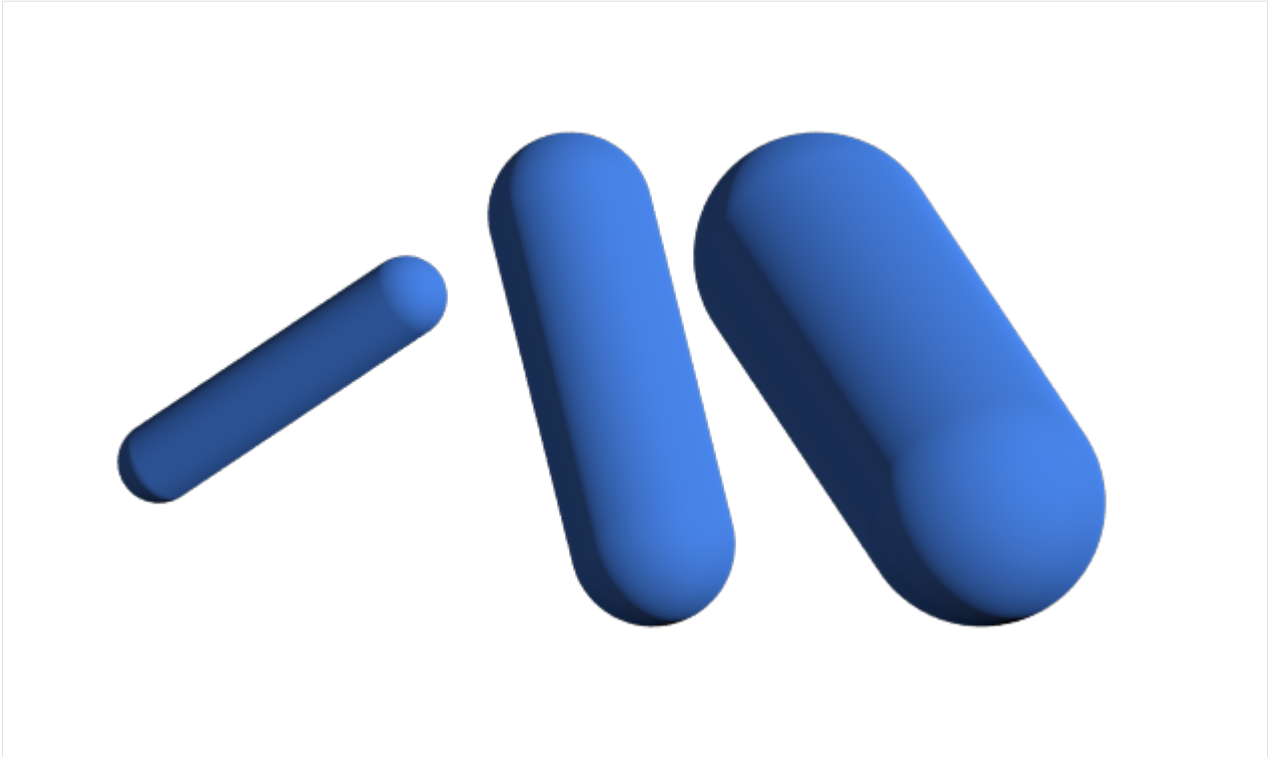
```
[3]: geometry.points[:] = [[[-5,-1,-1], [-2, 1, 1]],
                           [[1, -2, 1],[0, 2, -1]],
                           [[5, -1.5, 2], [3, 1.5, -2]]]
```

radius sets the radius of each spherocylinder.

```
[4]: geometry.radius[:] = [0.5, 1.0, 1.5]
```

```
[5]: scene.camera = fresnel.camera.Orthographic.fit(scene, view='front', margin=0.5)
fresnel.preview(scene)
```

[5]:



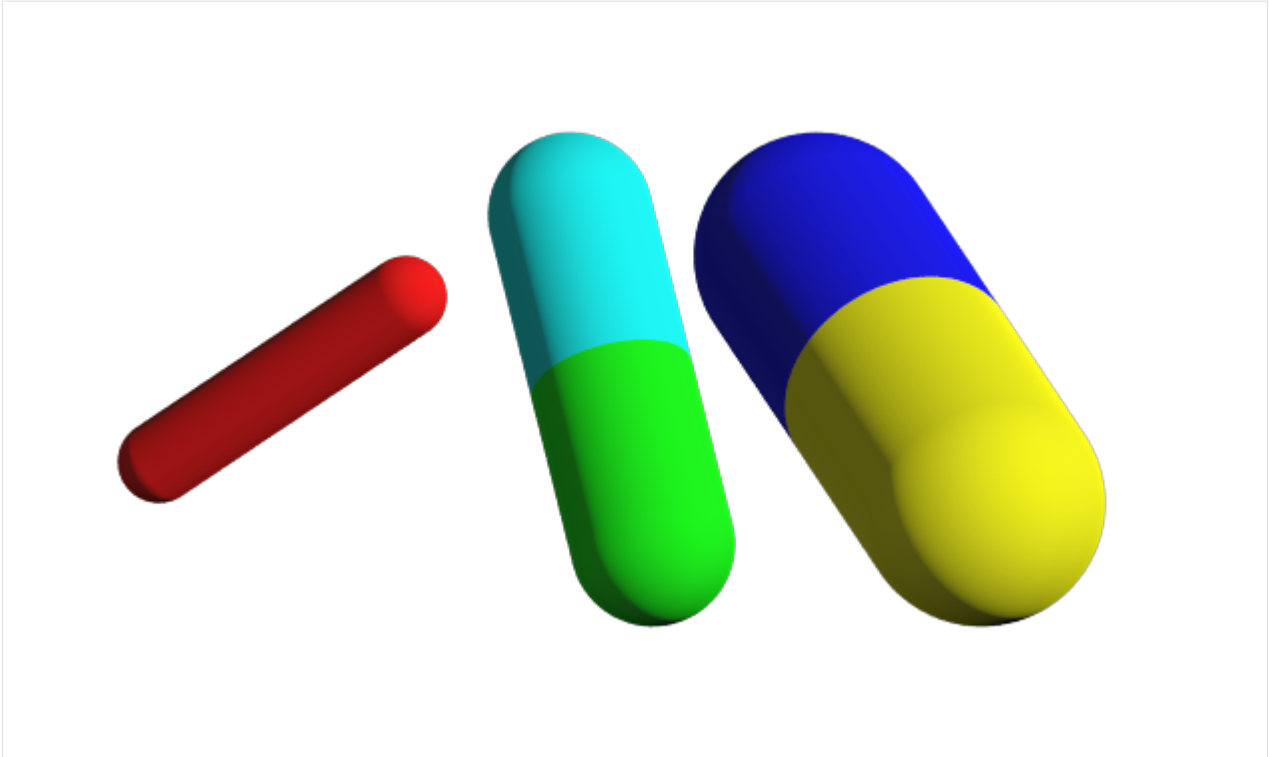
14.2 Color

color sets the color of the end points of each cylinder (when *primitive_color_mix* > 0). The color transitions at the midpoint.

```
[6]: geometry.color[:] = [[[0.9,0,0], [0.9, 0, 0]],  
                        [[0, 0.9, 0], [0, 0.9, 0.9]],  
                        [[0.9, 0.9, 0], [0, 0, 0.9]]]  
geometry.material.primitive_color_mix = 1.0
```

```
[7]: fresnel.preview(scene)
```

[7]:



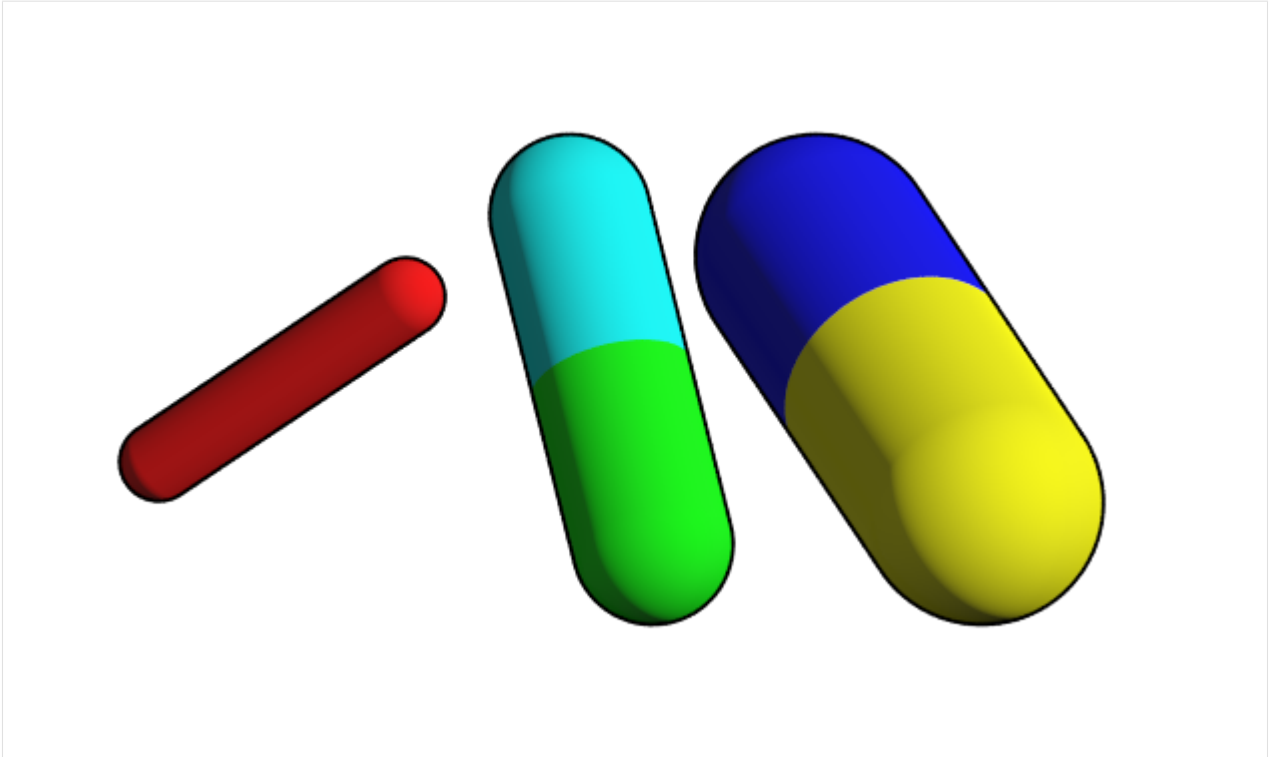
14.3 Outlines

Outlines are applied on the outer edge of the cylinder in the view plane.

```
[8]: geometry.outline_width = 0.05
```

```
[9]: fresnel.preview(scene)
```

[9]:



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CONVEX POLYHEDRON

```
[1]: import fresnel
import itertools
import math
import numpy as np
device = fresnel.Device()
scene = fresnel.Scene(device)
```

The **convex polyhedron geometry** defines a set of N convex polyhedra. The shape of all N polyhedra is identical and defined by P planes. Each polyhedron has its own *position*, *orientation*, and *color*. You must also specify the circumsphere radius r . Note that the information used to draw a convex polyhedron is easily obtained from its vertices via the `util.convex_polyhedron_from_vertices()` utility function.

To construct a truncated cube:

```
[2]: # first get cube verts
pm = [-1, 1]
cube_verts = list(itertools.product(pm, repeat=3))
trunc_cube_verts = []
# truncate by removing corners and adding vertices to edges
for p1, p2 in itertools.combinations(cube_verts, 2):
    # don't add points along any diagonals
    match = (p1[0]==p2[0], p1[1]==p2[1], p1[2]==p2[2])
    if match.count(False) == 1: # only 1 coordinate changes, not a diagonal
        p1, p2 = np.array(p1), np.array(p2)
        vec = p2 - p1
        trunc_cube_verts.append(p1 + vec/3)
        trunc_cube_verts.append(p1 + 2*vec/3)
```

```
[3]: c1 = fresnel.color.linear([0.70, 0.87, 0.54])*0.8
c2 = fresnel.color.linear([0.65,0.81,0.89])*0.8
colors = {8: c1, 3: c2}
poly_info = fresnel.util.convex_polyhedron_from_vertices(trunc_cube_verts)
for idx, fs in enumerate(poly_info['face_sides']):
    poly_info['face_color'][idx] = colors[fs]
geometry = fresnel.geometry.ConvexPolyhedron(scene,
                                              poly_info,
                                              N=3
                                              )
geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),
                                              roughness=0.8)
```

15.1 Geometric properties

position defines the position of the center of each convex polyhedron.

```
[4]: geometry.position[:] = [[-3,0,0], [0, 0, 0], [3, 0, 0]]
```

orientation sets the orientation of each convex polyhedron as a quaternion

```
[5]: geometry.orientation[:] = [[1, 0, 0, 0],
                                [0.80777943, 0.41672122, 0.00255412, 0.41692838],
                                [0.0347298, 0.0801457, 0.98045, 0.176321]]
```

```
[6]: scene.camera = fresnel.camera.Orthographic.fit(scene, view='front', margin=0.8)
fresnel.preview(scene)
```

[6]:



15.2 Color

color sets the color of each individual convex polyhedron (when *primitive_color_mix* > 0 and *color_by_face* < 1)

```
[7]: geometry.color[:] = fresnel.color.linear([[0.9,0,0], [0, 0.9, 0], [0, 0, 0.9]])
geometry.material.primitive_color_mix = 1.0
fresnel.preview(scene)
```

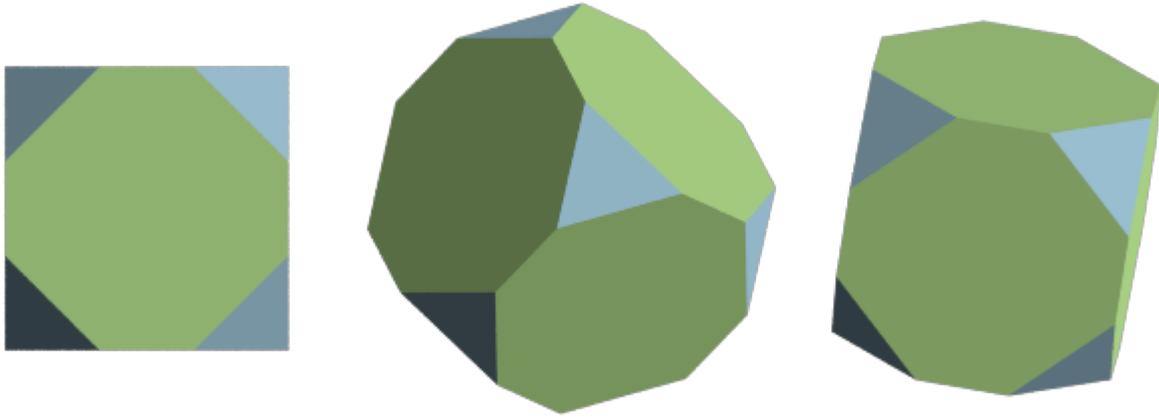

[7]:



Set `color_by_face > 0` to color the faces of the polyhedra independently. `poly_info['face_colors']` (i.e., the output of `convex_polyhedron_from_vertices`, which we modified above) sets the color of each face. Above, we set the color of the each face based on number of sides it has.

```
[8]: geometry.color_by_face = 1.0  
      fresnel.preview(scene)
```

[8]:

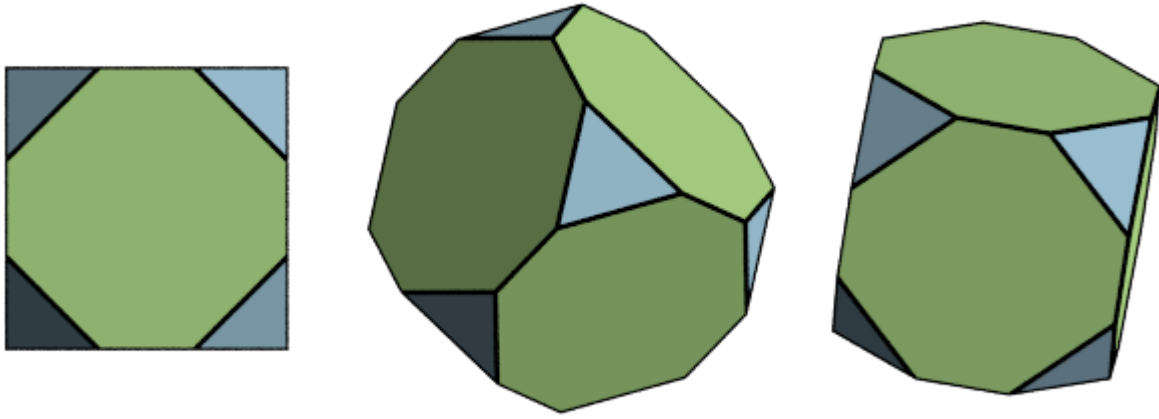


15.3 Outlines

Outlines are applied at the outer edge of each face.

```
[9]: geometry.outline_width = 0.02  
fresnel.preview(scene)
```

[9]:



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```
[1]: import fresnel
import numpy
import matplotlib, matplotlib.cm
```


MESH

The **mesh geometry** defines a generic triangle mesh. Define a mesh with an 3Tx3 array where T is the number of triangles. Triangles must be specified with a counter clockwise winding. Here is the [Stanford bunny](https://graphics.stanford.edu/~mdfisher/Data/Meshes/bunny.obj) as an example:

```
[2]: # https://graphics.stanford.edu/~mdfisher/Data/Meshes/bunny.obj
verts = numpy.load('bunny.npy')
```

16.1 Geometric properties

Pass the vertices to the mesh geometry.

```
[3]: scene1 = fresnel.Scene()
bunny = fresnel.geometry.Mesh(scene1,vertices=verts,N=1)

[4]: bunny.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),↵
↵↵roughness=0.6)
scene1.camera = fresnel.camera.Orthographic.fit(scene1,margin=0)
scene1.lights = fresnel.light.cloudy()
fresnel.pathtrace(scene1, samples=200)
```

[4]:

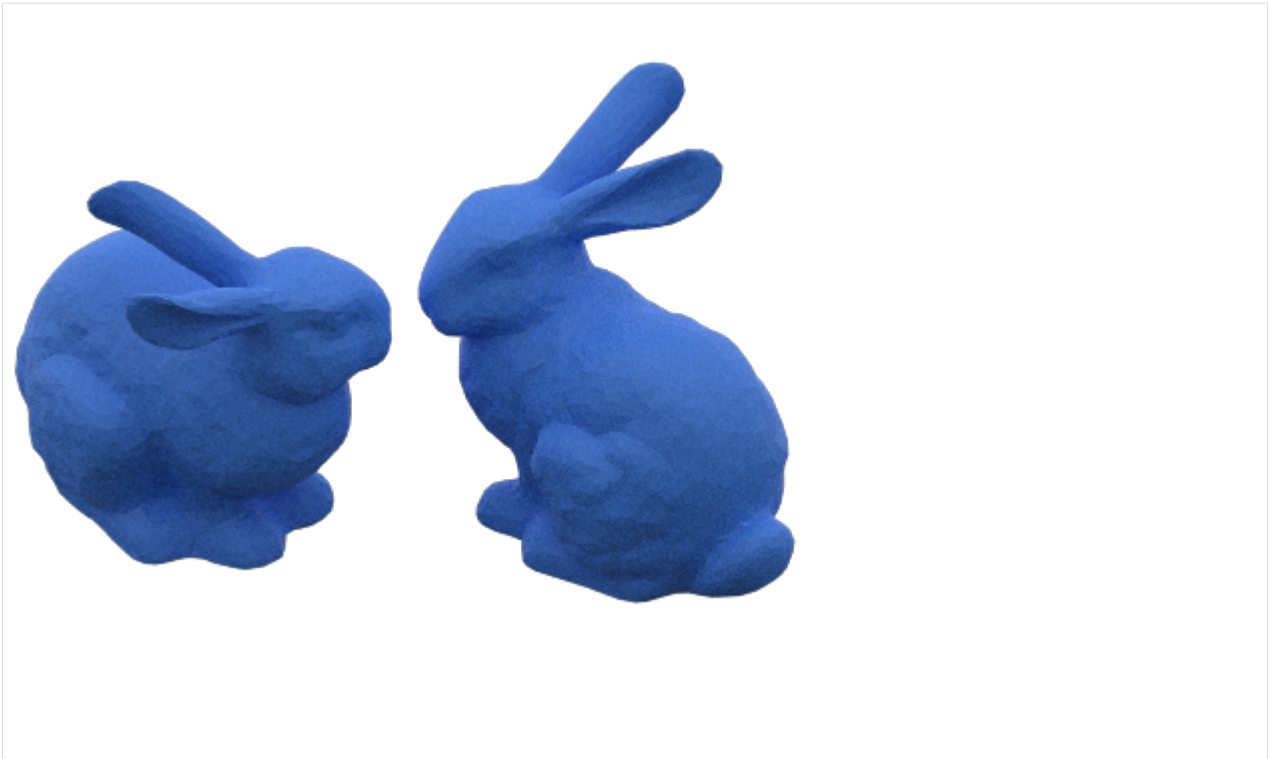


Specify position and orientation to instantiate the mesh many times.

```
[5]: scene2 = fresnel.Scene()
bunnies = fresnel.geometry.Mesh(scene2, vertices=verts, N=2)
bunnies.position[:] = [[0,0,0], [-0.11,0,0.1]]
bunnies.orientation[:] = [[1,0,0,0], [0,0,1,0]]
```

```
[6]: bunnies.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,0.9]),
↪roughness=0.6)
scene2.camera = fresnel.camera.Orthographic.fit(scene1, margin=0)
scene2.lights = fresnel.light.cloudy()
fresnel.pathtrace(scene2, samples=200)
```

[6]:



16.2 Color

Specify per vertex colors. These colors are smoothly interpolated across the triangles. Set `primitive_color_mix=1` to choose the per-vertex colors.

Color the bunny based on the y-coordinate of the mesh:

```
[7]: mapper = matplotlib.cm.ScalarMappable(norm = matplotlib.colors.Normalize(vmin=-0.08,
↪vmax=0.05, clip=True),
                                         cmap = matplotlib.cm.get_cmap(name='viridis'))

bunny.color[:] = fresnel.color.linear(mapper.to_rgba(verts[:,1]))
bunny.material.primitive_color_mix = 1.0
```

```
[8]: fresnel.pathtrace(scene1, samples=200)
```

[8]:



Here is a single triangle demo to demonstrate the interpolation:

```
[9]: scene3 = fresnel.Scene()
triangle = fresnel.geometry.Mesh(scene3, vertices=[[0,0,0],[1,0,0],[0,1,0]], N=1)
triangle.material.solid = 1
triangle.material.primitive_color_mix = 1.0
triangle.color[:] = [[1,0,0], [0,1,0], [0,0,1]]
```

```
[10]: scene3.camera = fresnel.camera.Orthographic.fit(scene3, view='front')
fresnel.preview(scene3)
```


[10]:

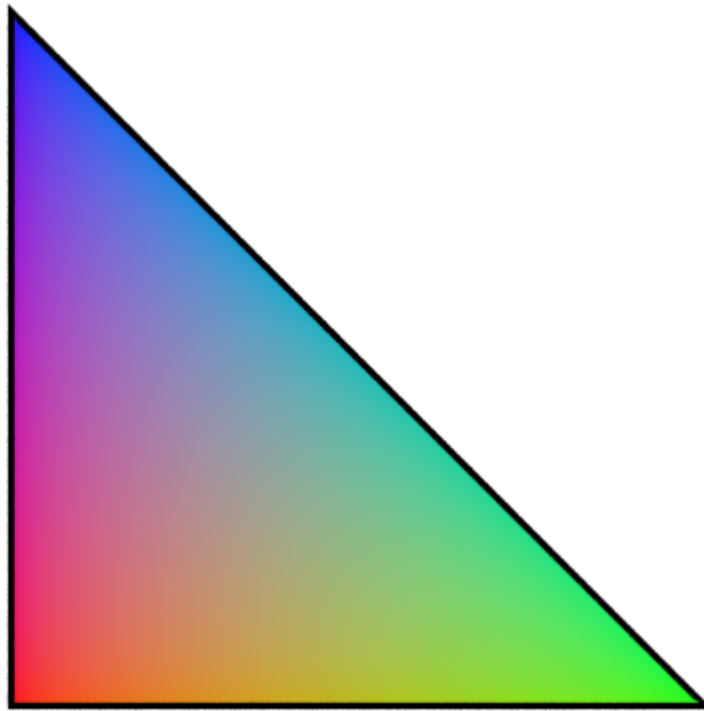


16.3 Outlines

Outlines are placed on the outer edge of each triangle in the mesh.

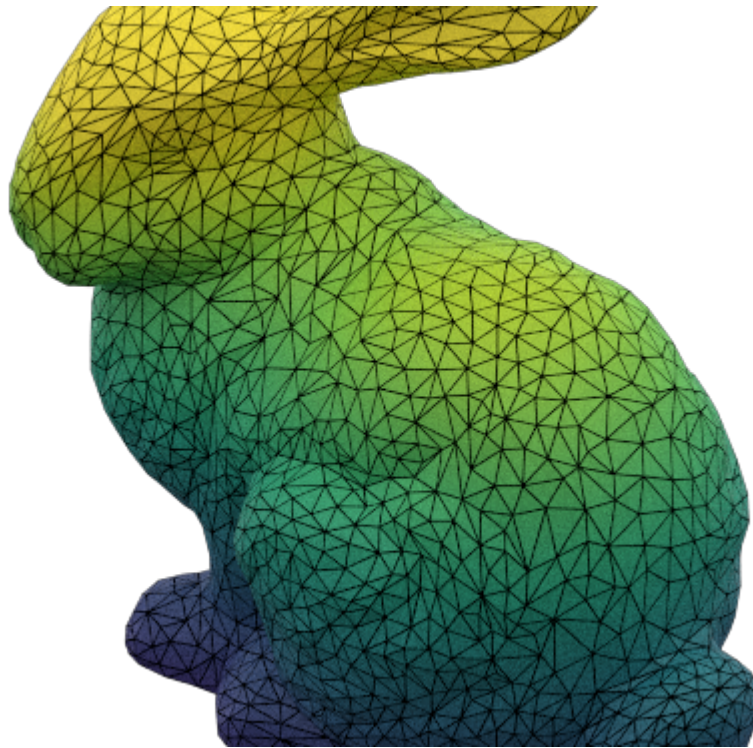
```
[11]: triangle.outline_width=0.01  
fresnel.preview(scene3)
```

[11]:



```
[12]: bunny.outline_width=0.0002  
scene1.camera.height *= 0.5  
fresnel.pathtrace(scene1, samples=200)
```

[12]:



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examples repository.

POLYGON

```
[1]: import fresnel
scene = fresnel.Scene()
```

The **polygon geometry** defines a set of N simple polygons in two dimensions. All polygons in the geometry have the same vertices. Each polygon has a separate *position*, orientation *angle*, and *color*.

```
[2]: geometry = fresnel.geometry.Polygon(scene,
                                         N=2,
                                         vertices = [[0, -1], [1, 1],
                                                       [0, 0.5], [-1, 1]])
geometry.material.color = fresnel.color.linear([0.20,0.64,0.58])
geometry.material.solid=1
```

17.1 Geometric properties

position defines the position of each polygon in the $z=0$ plane.

```
[3]: geometry.position[:] = [[-1,0],
                             [1, 0]]
```

angle defines the rotation angle of each polygon

```
[4]: geometry.angle[:] = [0.1, -1.0]
```

```
[5]: scene.camera = fresnel.camera.Orthographic.fit(scene)
fresnel.preview(scene)
```

[5]:



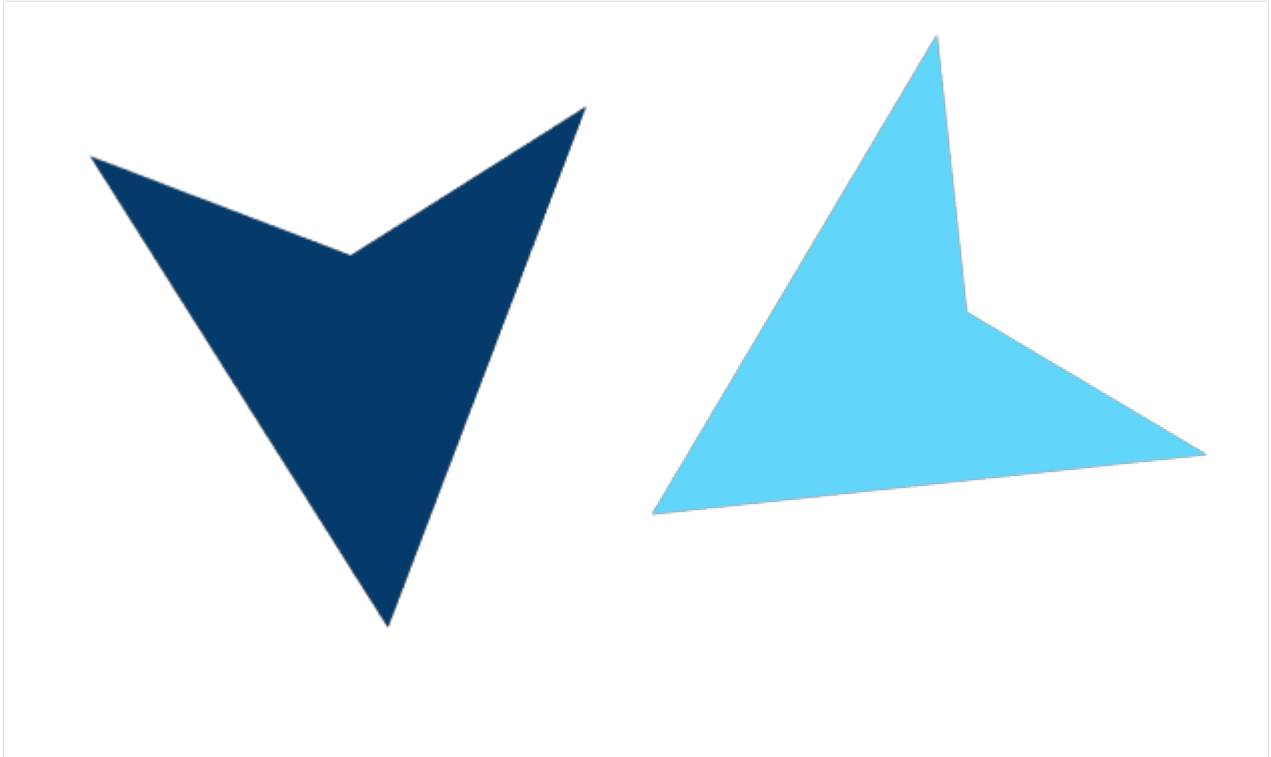
17.2 Color

color sets the color of each polygon (when *primitive_color_mix* > 0).

```
[6]: geometry.color[:] = [fresnel.color.linear([0.02,0.23,0.42]),  
                           fresnel.color.linear([0.38,0.84,0.98])];  
geometry.material.primitive_color_mix = 1.0
```

```
[7]: fresnel.preview(scene)
```

[7]:



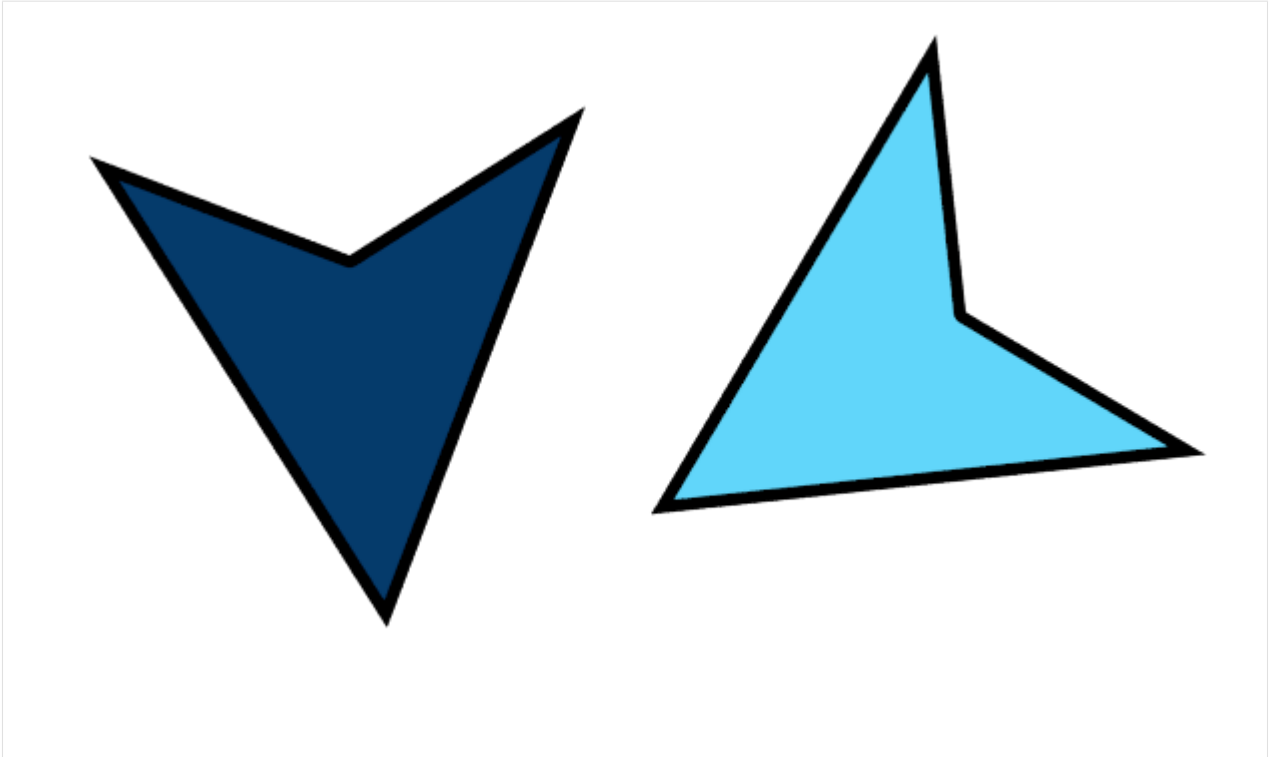
17.3 Outlines

Outlines are applied inside the outer edge of the polygon in the $z=0$ plane.

```
[8]: geometry.outline_width = 0.05
```

```
[9]: fresnel.preview(scene)
```

[9]:



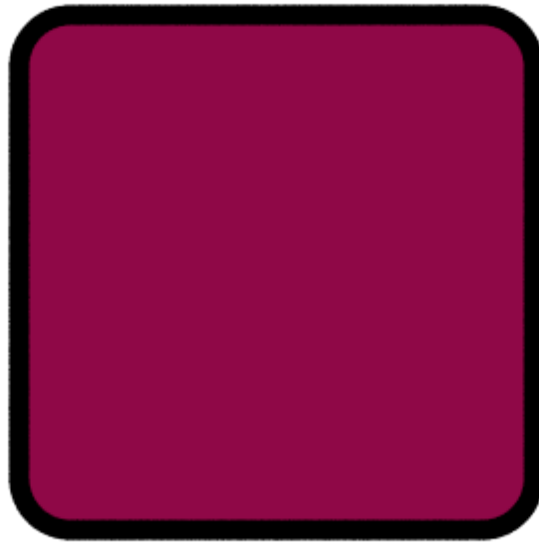
17.4 Rounded polygons

Specify *rounding_radius* to round the edges of the polygon.

```
[10]: scene2 = fresnel.Scene()
       geometry2 = fresnel.geometry.Polygon(scene2,
                                             rounding_radius=0.3,
                                             N=1,
                                             vertices = [[-1, -1], [1, -1],
                                                         [1, 1], [-1, 1]],
                                             outline_width=0.1)
       geometry2.material.color=fresnel.color.linear([0.56,0.03,0.28])
       geometry2.material.solid=1
       scene2.camera = fresnel.camera.Orthographic.fit(scene2)
```

```
[11]: fresnel.preview(scene2)
```


[11]:



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BOX

```
[1]: import sys

import fresnel

scene = fresnel.Scene()
```

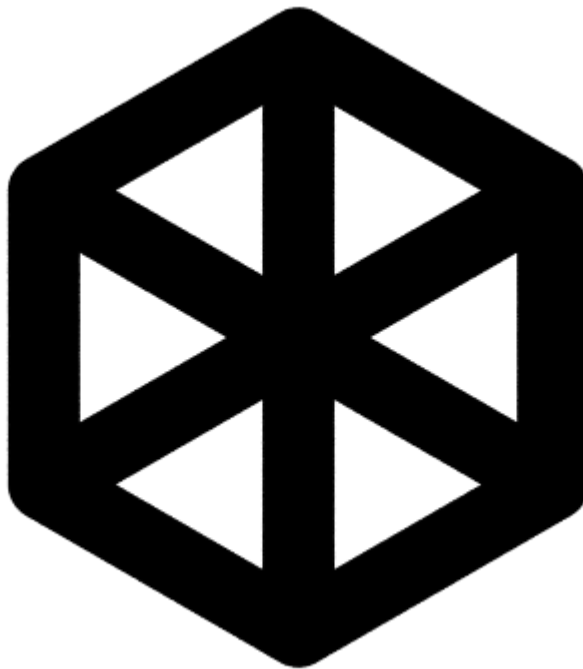
The Box geometry is a convenience class that uses the Cylinder geometry to draw a box. The Box geometry supports triclinic boxes and follows [hoomd-blue](#) box conventions. For cubic boxes, only one length is needed.

```
[2]: my_box = [5]
```

```
[3]: geometry = fresnel.geometry.Box(scene, my_box)
```

```
[4]: scene.camera = fresnel.camera.Orthographic.fit(scene)
fresnel.preview(scene)
```

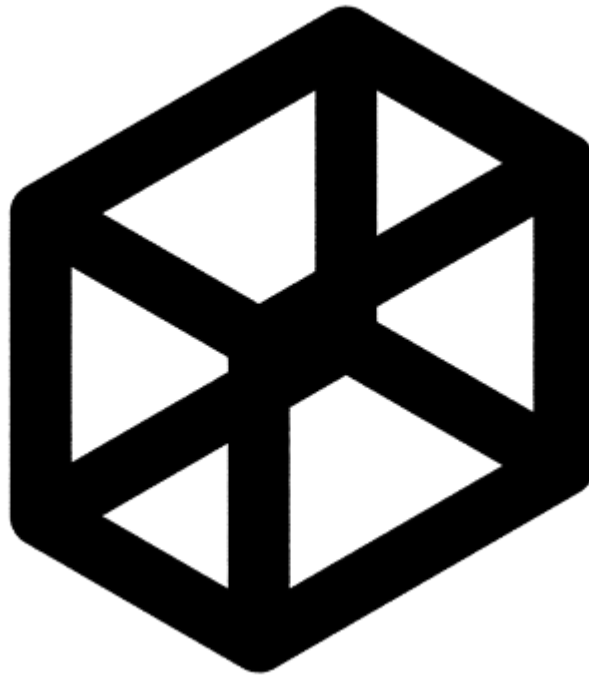
```
[4]:
```



Orthorhombic boxes require an Lx, Ly, and Lz

```
[5]: my_box = [5,6,7]
      scene = fresnel.Scene()
      geometry = fresnel.geometry.Box(scene, my_box)
      scene.camera = fresnel.camera.Orthographic.fit(scene)
      fresnel.preview(scene)
```

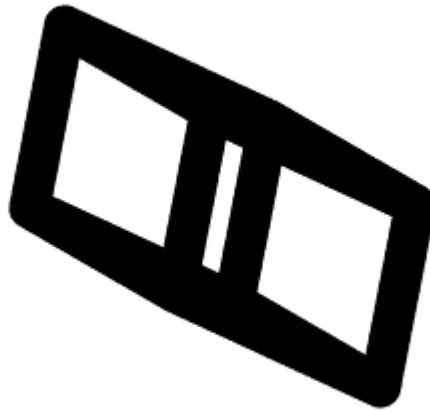
[5]:



Triclinic boxes are supported by using 6 terms, Lx, Ly, Lz, xy, xz, yz.

```
[6]: my_box = [5,6,7, .2, 0, .9]
      scene = fresnel.Scene()
      geometry = fresnel.geometry.Box(scene, my_box)
      scene.camera = fresnel.camera.Orthographic.fit(scene)
      fresnel.preview(scene)
```

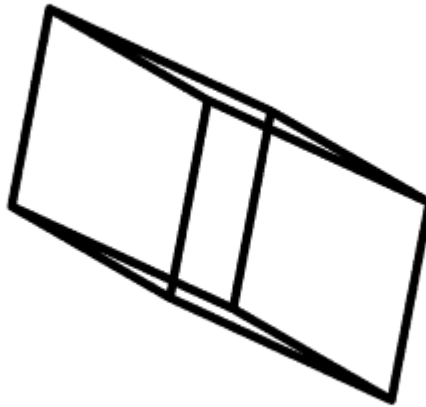
[6]:



The radius defaults to 0.5 but can be specified when the box is created

```
[7]: my_box = [5,6,7, .2, 0, .9]
      scene = fresnel.Scene()
      geometry = fresnel.geometry.Box(scene, my_box, box_radius=.1)
      scene.camera = fresnel.camera.Orthographic.fit(scene)
      fresnel.preview(scene)
```

[7]:



Or changed later

```
[8]: geometry.box_radius = 1
scene.camera = fresnel.camera.Orthographic.fit(scene)
fresnel.preview(scene)
```

[8]:



The box color can also be set on initialization.

```
[9]: my_box = [5, 6, 7, 0.2, 0, 0.9]
      scene = fresnel.Scene()
      geometry = fresnel.geometry.Box(scene, my_box, box_color=[214 / 255, 67 / 255, 9 / 255])
      scene.camera = fresnel.camera.Orthographic.fit(scene)
      fresnel.preview(scene)
```

[9]:



Or changed later.

```
[10]: geometry.box_color = [0, 51 / 255, 160 / 255]
      fresnel.preview(scene)
```

[10]:



The box size and shape can also be updated.

```
[11]: geometry.box = [4, 4, 5, 0.6, 0,0]  
fresnel.preview(scene)
```

[11]:



MULTIPLE GEOMETRIES

A **Scene** may consist of more than one geometry object. For fast performance, try to condense the scene down to as few geometries with as many primitives as possible. Multiple geometries allow for different materials to be applied to the same type of geometry and for different types of geometry in the same scene.

```
[1]: import fresnel
scene = fresnel.Scene()
```

19.1 Create multiple geometries

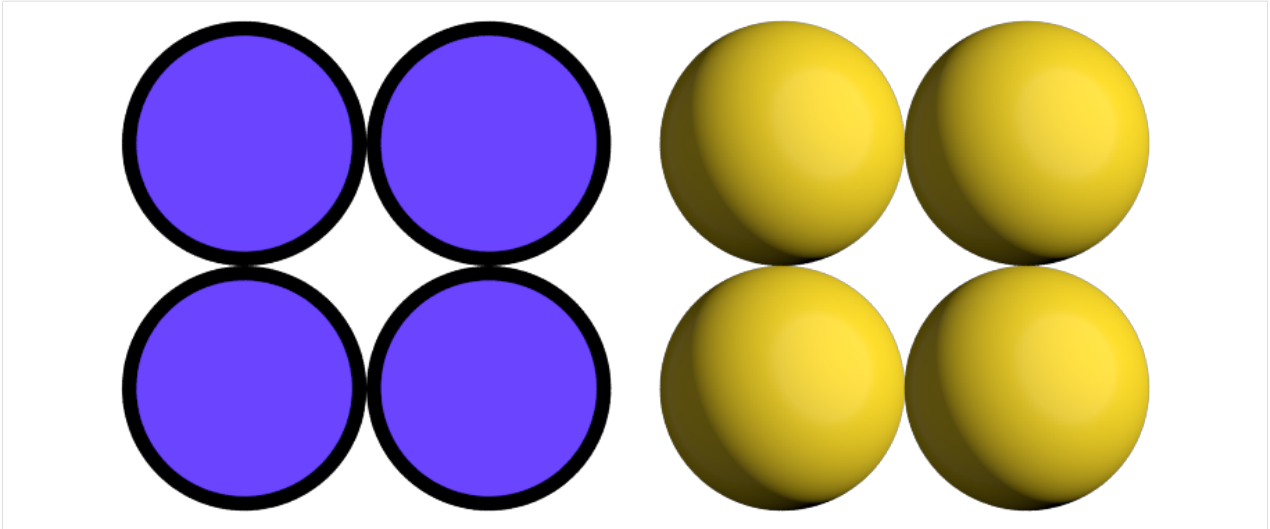
To create multiple geometries, instantiate several instances of the geometry class.

```
[2]: geom1 = fresnel.geometry.Sphere(scene, position = [[-3.2, 1, 0], [-3.2, -1, 0], [-1.2, 1,
↪ 0], [-1.2, -1, 0]], radius=1.0)
geom1.material = fresnel.material.Material(solid=1.0, color=fresnel.color.linear([0.42,0.
↪ 267,1]))
geom1.outline_width = 0.12
```

```
[3]: geom2 = fresnel.geometry.Sphere(scene, position = [[3.2, 1, 0], [3.2, -1, 0], [1.2, 1,
↪ 0], [1.2, -1, 0]], radius=1.0)
geom2.material = fresnel.material.Material(solid=0.0, color=fresnel.color.linear([1,0.
↪ 874,0.169]))
```

```
[4]: scene.camera = fresnel.camera.Orthographic.fit(scene)
fresnel.preview(scene, w=900, h=370)
```

[4]:



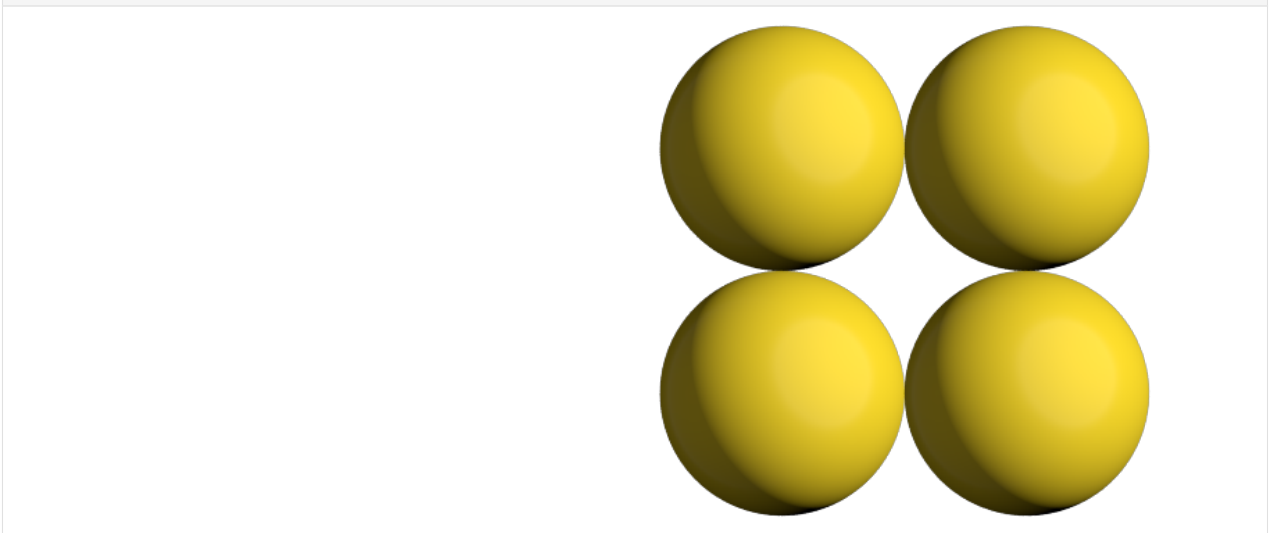
19.2 Disable geometries

disable a geometry to prevent it from appearing in the scene.

```
[5]: geom1.disable()
```

```
[6]: fresnel.preview(scene, w=900, h=370)
```

[6]:

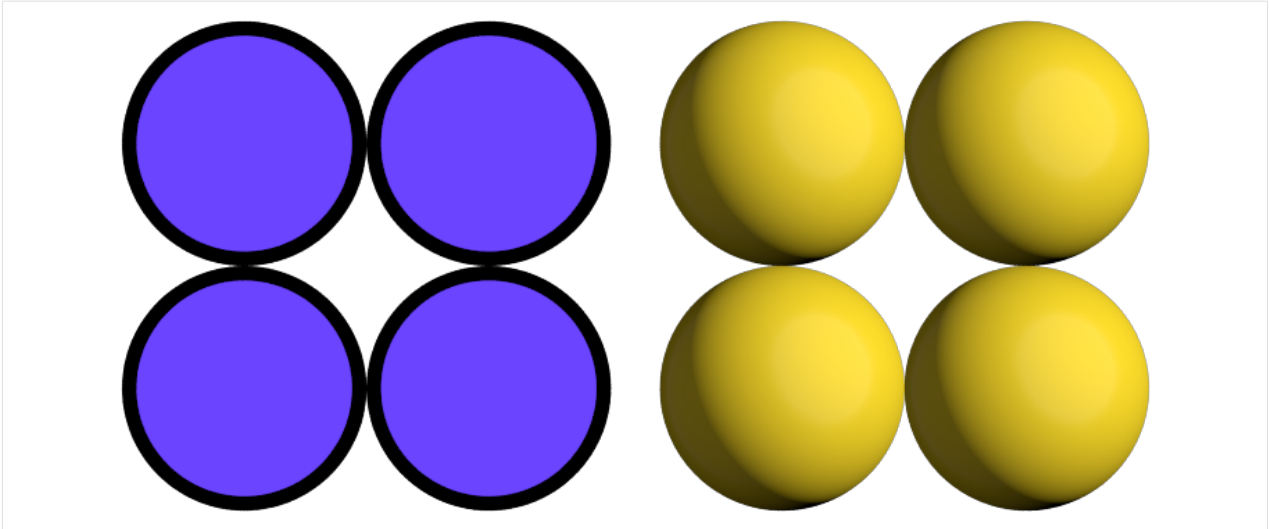


enable the geometry to make it appear again.

```
[7]: geom1.enable()
```

```
[8]: fresnel.preview(scene, w=900, h=370)
```

[8]:



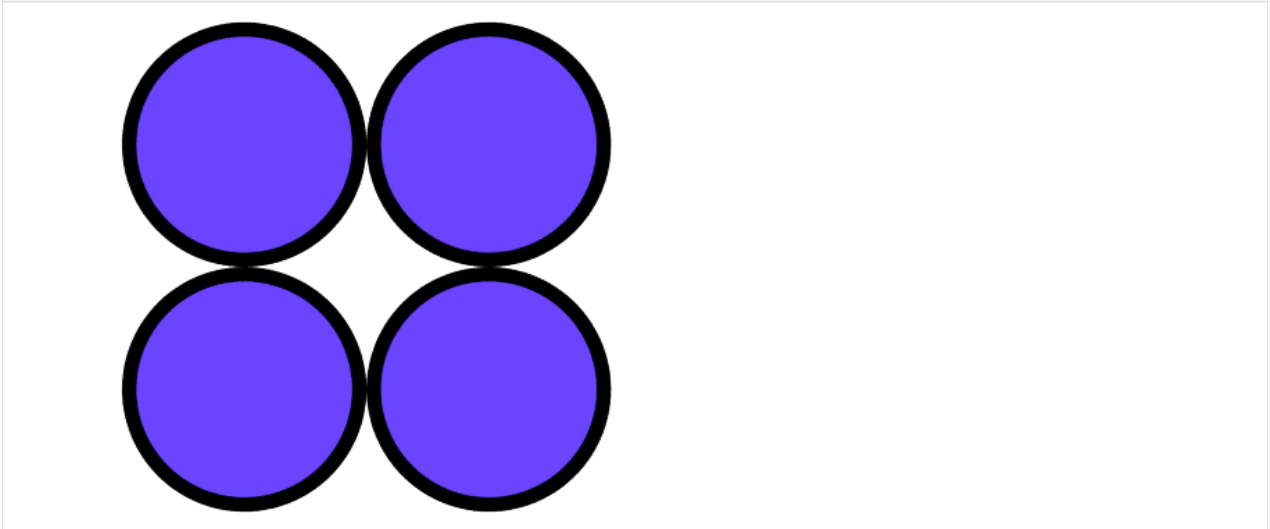
19.3 Remove geometry

Call **remove** to completely remove a geometry instance from the scene. It cannot be added back.

[9]: `geom2.remove()`

[10]: `fresnel.preview(scene, w=900, h=370)`

[10]:



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DEVICES

Each **Scene** is attached to a specific **Device**. The **Device** controls what hardware the ray tracing executes on. **Scene** implicitly creates a default **Device** when you do not specify one.

20.1 The default device

The default device automatically selects **GPU ray tracing** if the *gpu module is compiled and there is at least one gpu present in the system* - otherwise it selects **CPU ray tracing**.

```
[1]: import fresnel
device = fresnel.Device()
```

20.2 Query available execution modes

The `available_modes` static variable lists which execution modes are available. This will vary based on compile time options and whether there is a GPU present in the system.

```
[2]: print(fresnel.Device.available_modes)

['gpu', 'cpu', 'auto']
```

`available_gpus` lists the GPUs available for rendering in the system.

```
[3]: for g in fresnel.Device.available_gpus:
      print(g)

[0]:      Quadro RTX 5000    48 SM_7.5 @ 1.82 GHz,   8198 MiB DRAM
```

20.3 Choose execution hardware

Explicitly manage a **Device** to control what hardware the ray tracing executes on. Converting the device to a string provides a short summary of the device configuration.

```
[4]: gpu = fresnel.Device(mode='gpu')
      print(gpu)
```

```
<fresnel.Device: Enabled OptiX devices:
[0]:      Quadro RTX 5000   48 SM_7.5 @ 1.82 GHz,   8198 MiB DRAM
>
```

```
[5]: cpu = fresnel.Device(mode='cpu')
     print(cpu)
```

```
<fresnel.Device: All available CPU threads>
```

Set `n` to specify how many CPU threads or GPUs to use in parallel. By default, a device will use all available CPU cores or GPUs in the system.

```
[6]: cpu_limit = fresnel.Device(mode='cpu', n=6)
     print(cpu_limit)
```

```
<fresnel.Device: 6 CPU threads>
```

20.4 Attach a scene to a device

Each **Scene** must be attached to a device when created.

```
[7]: scene_gpu = fresnel.Scene(device=gpu)
```

```
[8]: scene_cpu = fresnel.Scene(device=cpu)
```

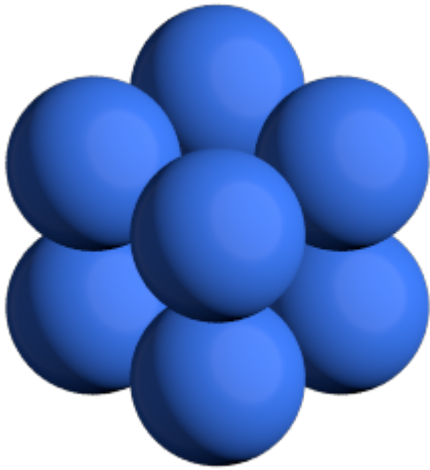
These two scenes have the same API, but different implementations.

```
[9]: for scene in [scene_cpu, scene_gpu]:
     geometry = fresnel.geometry.Sphere(scene, N=8, radius=1.0)
     geometry.position[:] = [[1,1,1],
                             [1,1,-1],
                             [1,-1,1],
                             [1,-1,-1],
                             [-1,1,1],
                             [-1,1,-1],
                             [-1,-1,1],
                             [-1,-1,-1]]
     geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.25,0.5,
     ↪1]))
     scene.camera = fresnel.camera.Orthographic.fit(scene)
```

Rendered output is essentially identical from the two devices.

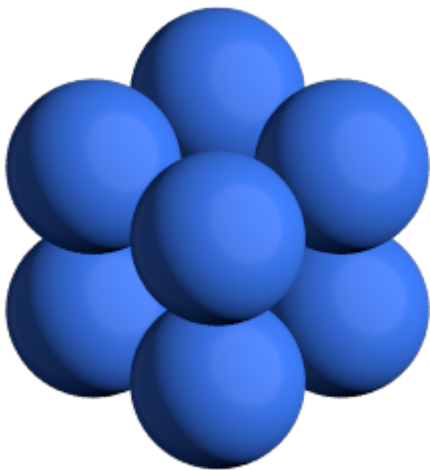
```
[10]: fresnel.preview(scene_gpu, w=300, h=300)
```

[10]:



```
[11]: fresnel.preview(scene_cpu, w=300, h=300)
```

[11]:



20.5 Memory consumption

Each **Device** consumes memory by itself. When maintaining multiple scenes, attach them all to the same device to reduce memory consumption.

```
[12]: import math
scene2_gpu = fresnel.Scene(device=gpu)
position = []
for k in range(5):
```

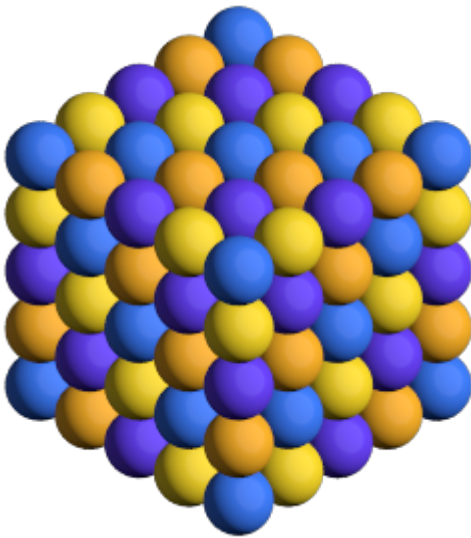
(continues on next page)

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```
for i in range(5):
    for j in range(5):
        position.append([2*i, 2*j, 2*k])
geometry = fresnel.geometry.Sphere(scene2_gpu, position = position, radius=1.0)
geometry.color[:,4] = fresnel.color.linear([0.25,0.5,1])
geometry.color[1::4] = fresnel.color.linear([1,0.714,0.169])
geometry.color[2::4] = fresnel.color.linear([0.42,0.267,1])
geometry.color[3::4] = fresnel.color.linear([1,0.874,0.169])
geometry.material = fresnel.material.Material(solid=0.0, primitive_color_mix=1.0)
scene2_gpu.camera = fresnel.camera.Orthographic.fit(scene2_gpu)
```

```
[13]: fresnel.preview(scene2_gpu, w=300, h=300)
```

```
[13]:
```



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TRACER METHODS

Most of the tutorials use **fresnel.preview()** and **fresnel.pathtrace()** to render output images. This is a convenience API, and there are cases where it is not appropriate. To render many frames, such as in a movie or interactive visualization, use a **Tracer** directly to avoid overhead.

```
[1]: import fresnel
import math
from matplotlib import pyplot
%matplotlib inline
device = fresnel.Device()
scene = fresnel.Scene(device=device)
position = []
for i in range(6):
    position.append([2*math.cos(i*2*math.pi / 6), 2*math.sin(i*2*math.pi / 6), 0])

geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
geometry.material = fresnel.material.Material(solid=0.0, color=fresnel.color.linear([1,0.
↪874,0.169])*0.9)
geometry.outline_width = 0.12
scene.camera = fresnel.camera.Orthographic.fit(scene, view='front', margin=0.2)
```

21.1 Common Tracer operations

The **Tracer** must use the same device as the **Scenes** it renders. Each **Tracer** maintains an output image, and the width **w** and height **h** must be defined when the tracer is created.

```
[2]: tracer = fresnel.tracer.Preview(device=device, w=300, h=300)
```

21.1.1 Rendering and accessing output images

The **render** method renders the output.

```
[3]: out = tracer.render(scene)
```

The return value of **render** is a proxy reference to the internal image buffer of the **Tracer**. You can access with a **numpy** array like interface.

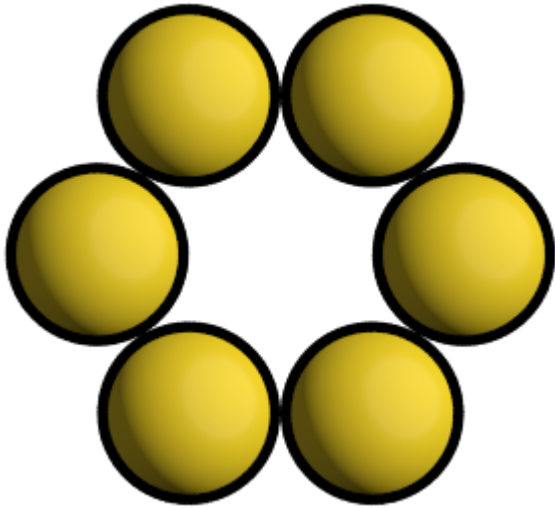
```
[4]: out[100,100]
```

```
[4]: array([139, 121, 21, 255], dtype=uint8)
```

The output object also provides an interface for **jupyter** to display the image.

```
[5]: out
```

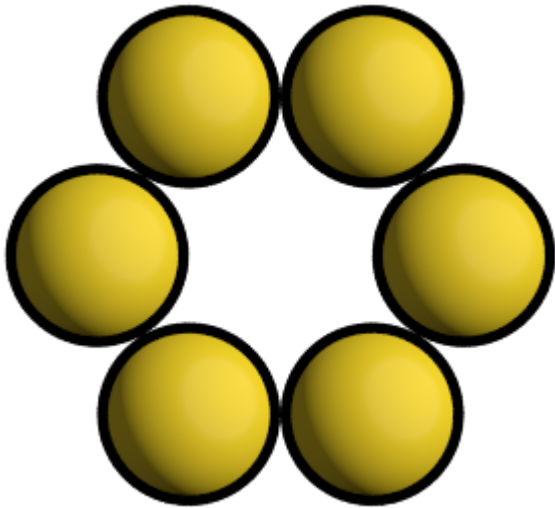
```
[5]:
```



tracer.output also accesses the output buffer.

```
[6]: tracer.output
```

```
[6]:
```



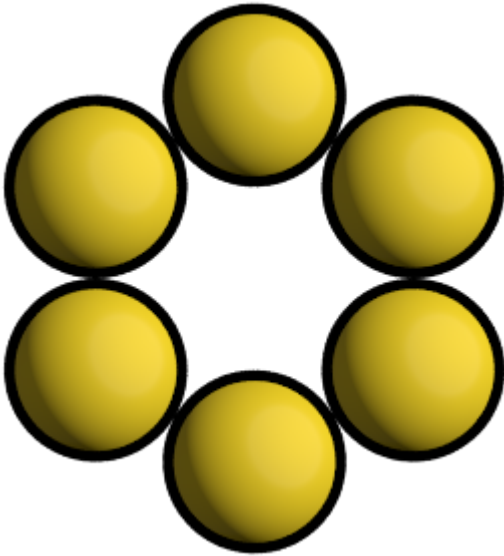
The tracer can render a modified scene without the initialization overhead.

```
[7]: scene.camera.up = (1,0,0)
      tracer.render(scene);
```

After rendering, existing references to the output buffer will access the newly rendered image.

```
[8]: out
```

```
[8]:
```



21.1.2 Evaluate image exposure

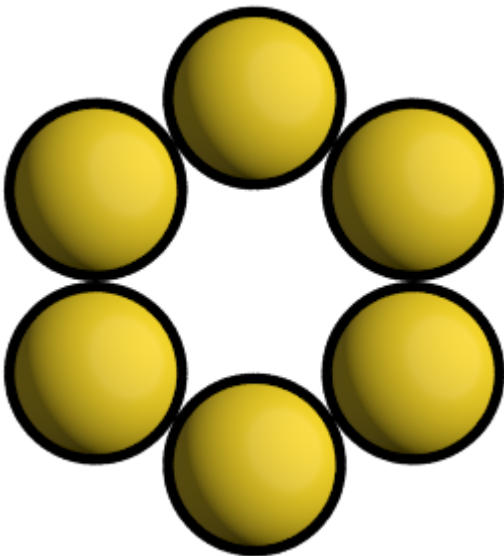
Tracer provides several methods to evaluate image exposure. Enable highlight warnings to flag overexposed pixels in the output image.

```
[9]: tracer.enable_highlight_warning()
```

The test image is exposed correctly, there are no warning pixels.

```
[10]: tracer.render(scene)
```

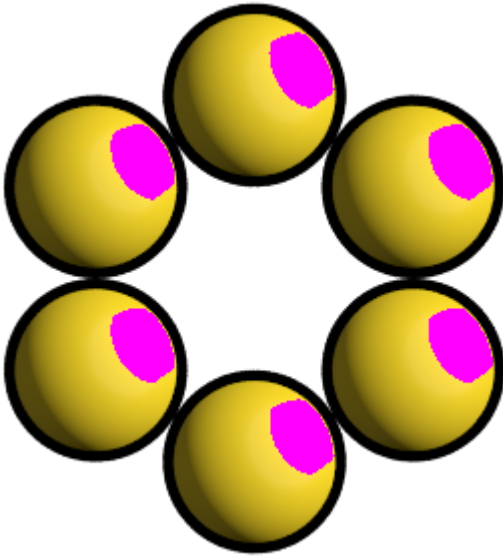
```
[10]:
```



Make the main light brighter to show the highlight warnings.

```
[11]: scene.lights[0].color = (1.2, 1.2, 1.2)
      tracer.render(scene)
```

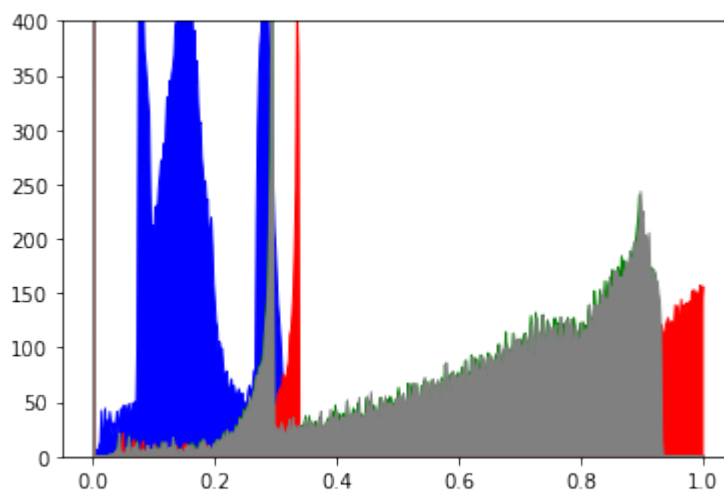
```
[11]:
```



Tracer can also compute the image histogram to evaluate image exposure.

```
[12]: L, bins = tracer.histogram()
      pyplot.fill_between(bins, L[:,3], color='blue');
      pyplot.fill_between(bins, L[:,2], color='green');
      pyplot.fill_between(bins, L[:,1], color='red');
      pyplot.fill_between(bins, L[:,0], color='gray');
      pyplot.axis(ymax=400, ymin=0)
```

```
[12]: (-0.04794921875, 1.04990234375, 0.0, 400.0)
```



```
[13]: tracer.disable_highlight_warning()
```

21.1.3 Resizing the output buffer

Call **resize** to set a new size for the output. When the image is resized, any existing rendered output is lost.

```
[14]: tracer.resize(w=150, h=150)
```

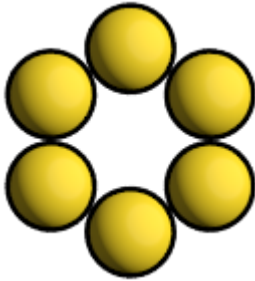
```
[15]: tracer.output
```

```
[15]:
```

The next call to render will render into the new output size.

```
[16]: tracer.render(scene)
```

```
[16]:
```



21.2 The Preview tracer

The **Preview** tracer renders output images quickly with approximate lighting effects.

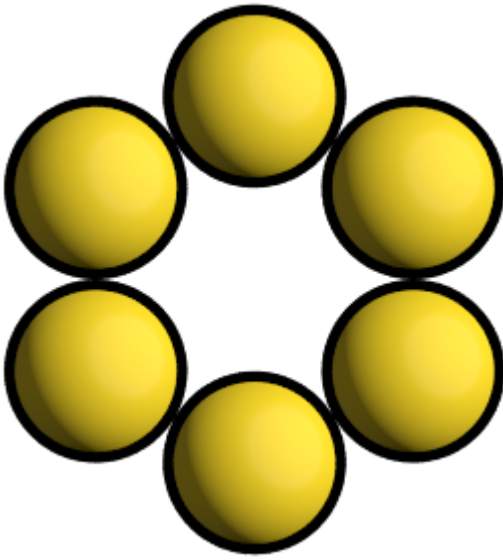
```
[17]: tracer = fresnel.tracer.Preview(device=device, w=300, h=300)
```

A different random number seed will result in different jittered anti-aliasing samples.

```
[18]: tracer.seed = 12
```

```
[19]: tracer.render(scene)
```

[19]:



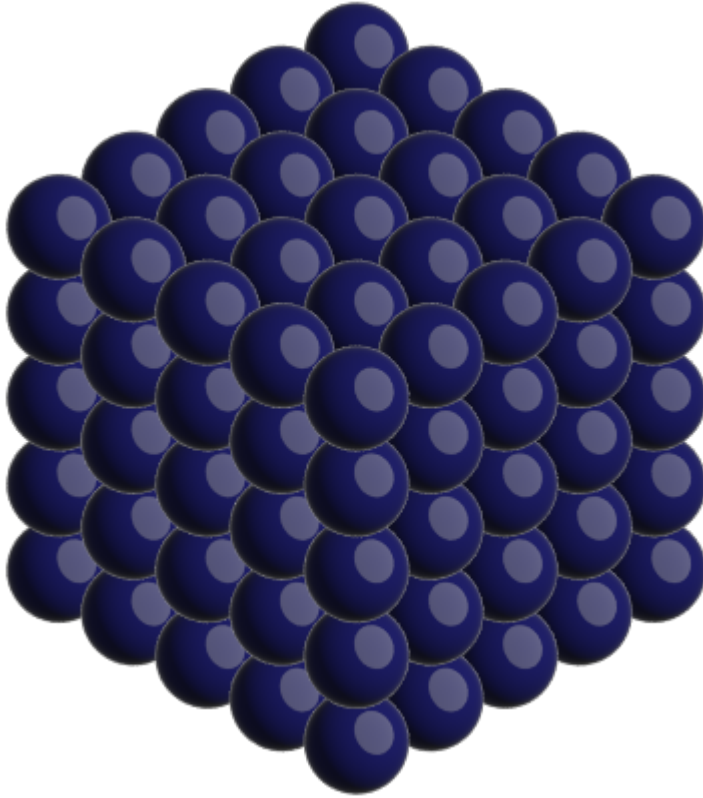
Here is a different scene rendered with the **Preview** tracer:

```
[20]: position = []
      for k in range(5):
          for i in range(5):
              for j in range(5):
                  position.append([2*i, 2*j, 2*k])
      scene = fresnel.Scene(device)
      scene.lights[1].theta = math.pi

      geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
      geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.1,0.1,0.4]),
                                                  roughness=0.1,
                                                  specular=1.0)
      scene.camera = fresnel.camera.Orthographic.fit(scene)

[21]: tracer.resize(w=450, h=450)
      tracer.aa_level = 3
      tracer.render(scene)
```

[21]:



21.3 The Path tracer

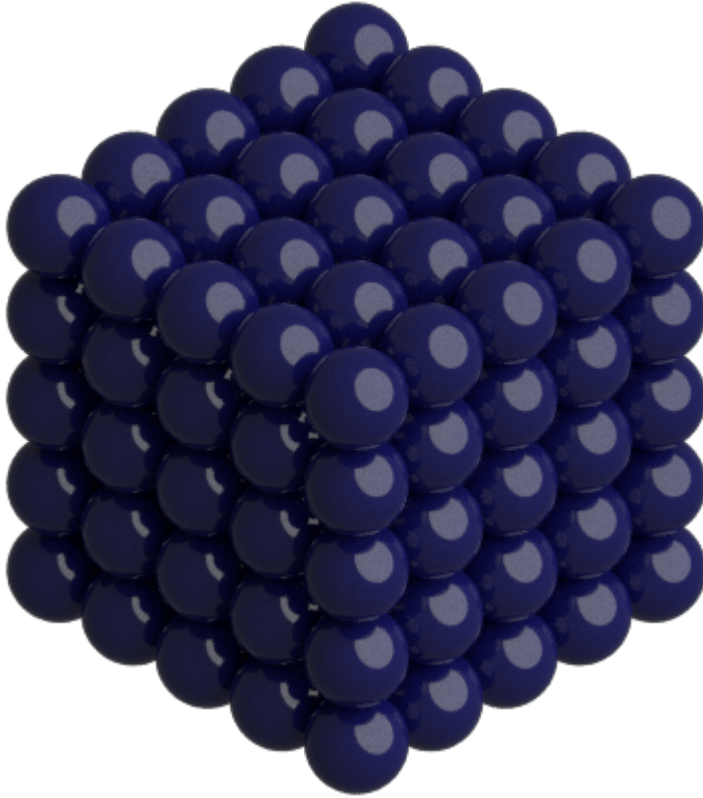
The **Path** tracer supports soft lighting, reflections, and other lighting effects.

Here is the same scene with the path tracer:

```
[22]: path_tracer = fresnel.tracer.Path(device=device, w=450, h=450)
```

```
[23]: path_tracer.sample(scene, samples=64, light_samples=40)
```

[23]:



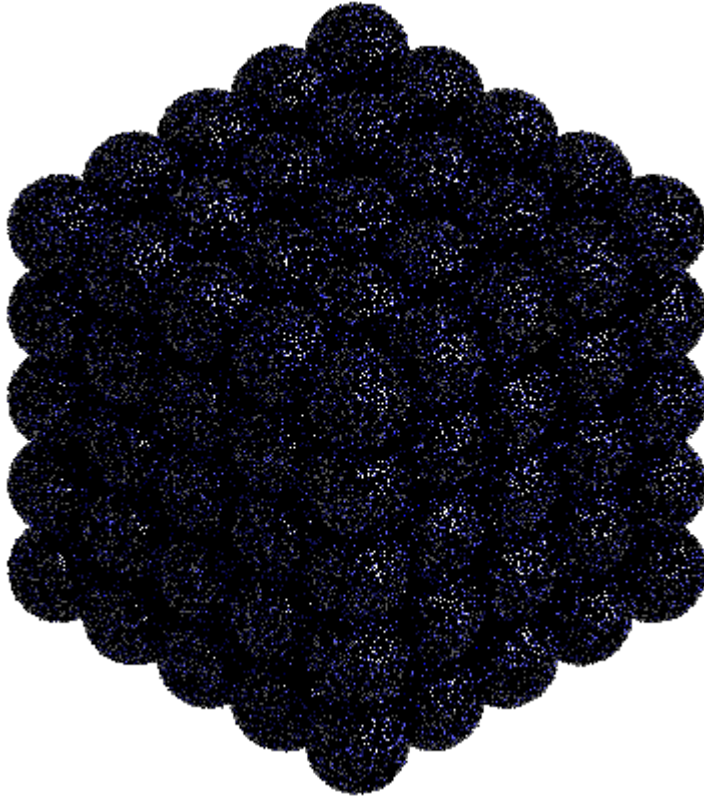
The **Path** tracer performs many independent samples and averages them together. **reset()** starts averaging a new image.

[24]: `path_tracer.reset()`

render() accumulates a single sample into the resulting image.

[25]: `path_tracer.render(scene)`

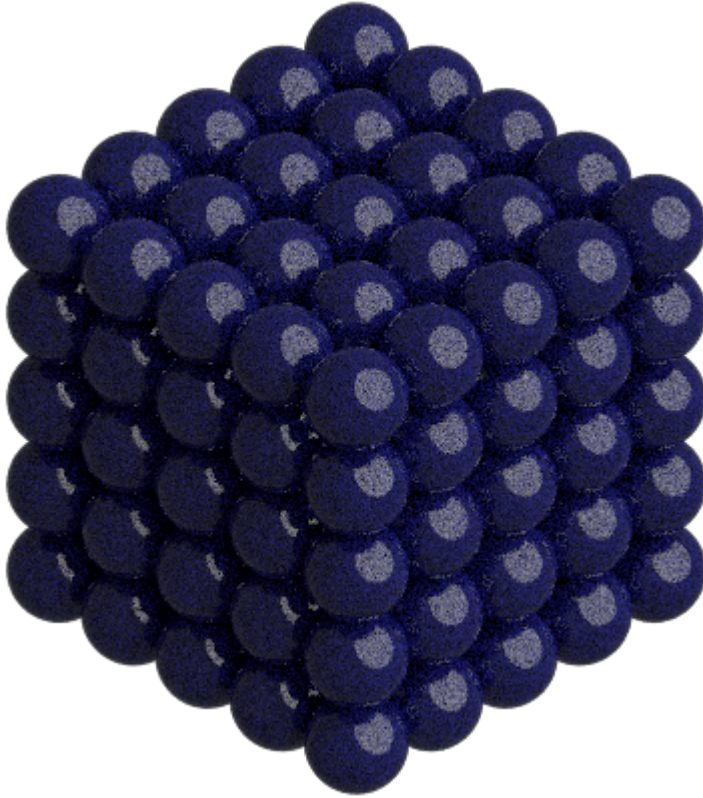
[25]:



The resulting image is noisy, average many samples together to obtain a clean image.

```
[26]: for i in range(64):  
        path_tracer.render(scene)  
  
path_tracer.output
```

[26]:



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```
[1]: import fresnel  
import math
```

INTERACTIVE SCENE VIEW

fresnel provides a Qt widget to interactively display scenes rendered with the **path tracer**. This is implemented with the **PySide2** library. Using jupyter support for this library, you can open an interactive window outside of the browser and interact with it from the jupyter notebook.

First, initialize jupyter's pyside2 integration.

```
[2]: from PySide2 import QtCore
      %gui qt
```

Then, import `fresnel.interact`. This **must** be done after `%gui qt`.

```
[ ]: import fresnel.interact
```

Build a scene

```
[ ]: position = []
      for k in range(5):
          for i in range(5):
              for j in range(5):
                  position.append([2*i, 2*j, 2*k])
      scene = fresnel.Scene()
      scene.lights[1].theta = math.pi

      geometry = fresnel.geometry.Sphere(scene, position = position, radius=1.0)
      geometry.material = fresnel.material.Material(color=fresnel.color.linear([0.1,0.1,0.8]),
                                                    roughness=0.1,
                                                    specular=1.0)
      scene.camera = fresnel.camera.Orthographic.fit(scene)
```

22.1 SceneView widget

Create a `interact.SceneView` widget to visualize the scene.

```
[ ]: view = fresnel.interact.SceneView(scene)
```

When the `SceneView` is the result of a cell, the window shows and gets focus. In JupyterLab environments, you may need to use `view.show()`

```
[ ]: view  
  
# use view.show() if in JupyterLab
```

In the new window, you can click and drag to rotate the camera. Jupyter is still running so you can query changes to the window here. For example, after rotating the camera, inspect the new camera configuration:

```
[ ]: repr(scene.camera)
```

After you change scene properties, call `setScene` to re-render the scene with the changes. For example: change the material color.

```
[ ]: geometry.material.color = fresnel.color.linear([0.8,0.1,0.1])  
view.setScene(scene)
```

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RENDERING IMAGES IN MATPLOTLIB

Images rendered by **fresnel** can be converted to RGBA arrays for display with the **imshow** command in **matplotlib**. This example shows how to build subplots that display the geometries of the Platonic Solids.

```
[1]: import numpy as np
import fresnel
import matplotlib
import matplotlib.pyplot as plt

[2]: platonic_solid_vertices = {
    'Tetrahedron': [
        [0.0, 0.0, 0.612372],
        [-0.288675, -0.5, -0.204124],
        [-0.288675, 0.5, -0.204124],
        [0.57735, 0.0, -0.204124]],
    'Cube': [
        [-0.5, -0.5, -0.5],
        [-0.5, -0.5, 0.5],
        [-0.5, 0.5, -0.5],
        [-0.5, 0.5, 0.5],
        [0.5, -0.5, -0.5],
        [0.5, -0.5, 0.5],
        [0.5, 0.5, -0.5],
        [0.5, 0.5, 0.5]],
    'Octahedron': [
        [-0.707107, 0.0, 0.0],
        [0.0, 0.707107, 0.0],
        [0.0, 0.0, -0.707107],
        [0.0, 0.0, 0.707107],
        [0.0, -0.707107, 0.0],
        [0.707107, 0.0, 0.0]],
    'Dodecahedron': [
        [-1.37638, 0.0, 0.262866],
        [1.37638, 0.0, -0.262866],
        [-0.425325, -1.30902, 0.262866],
        [-0.425325, 1.30902, 0.262866],
        [1.11352, -0.809017, 0.262866],
        [1.11352, 0.809017, 0.262866],
        [-0.262866, -0.809017, 1.11352],
        [-0.262866, 0.809017, 1.11352],
        [-0.688191, -0.5, -1.11352],
```

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```

    [-0.688191, 0.5, -1.11352],
    [0.688191, -0.5, 1.11352],
    [0.688191, 0.5, 1.11352],
    [0.850651, 0.0, -1.11352],
    [-1.11352, -0.809017, -0.262866],
    [-1.11352, 0.809017, -0.262866],
    [-0.850651, 0.0, 1.11352],
    [0.262866, -0.809017, -1.11352],
    [0.262866, 0.809017, -1.11352],
    [0.425325, -1.30902, -0.262866],
    [0.425325, 1.30902, -0.262866]],
    'Icosahedron': [
        [0.0, 0.0, -0.951057],
        [0.0, 0.0, 0.951057],
        [-0.850651, 0.0, -0.425325],
        [0.850651, 0.0, 0.425325],
        [0.688191, -0.5, -0.425325],
        [0.688191, 0.5, -0.425325],
        [-0.688191, -0.5, 0.425325],
        [-0.688191, 0.5, 0.425325],
        [-0.262866, -0.809017, -0.425325],
        [-0.262866, 0.809017, -0.425325],
        [0.262866, -0.809017, 0.425325],
        [0.262866, 0.809017, 0.425325]],
    ]
}

```

The render function returns a NumPy array of the output buffer, which can be passed directly to **imshow**.

```

[3]: def render(shape, color_id=0):
    verts = platonic_solid_vertices[shape]
    scene = fresnel.Scene(fresnel.Device(mode='cpu'))
    scene.lights = fresnel.light.lightbox()
    poly_info = fresnel.util.convex_polyhedron_from_vertices(verts)
    cmap = matplotlib.cm.get_cmap('tab10')
    geometry = fresnel.geometry.ConvexPolyhedron(
        scene, poly_info,
        position = [0, 0, 0],
        orientation = [0.975528, 0.154508, -0.154508, -0.024472],
        outline_width = 0.015)
    geometry.material = fresnel.material.Material(
        color = fresnel.color.linear(cmap(color_id)[:3]),
        roughness = 0.1,
        specular = 1)
    geometry.outline_material = fresnel.material.Material(
        color = (0., 0., 0.),
        roughness = 0.1,
        metal = 1.0)

    scene.camera = fresnel.camera.Orthographic.fit(scene, view='front')
    out = fresnel.pathtrace(scene, samples=64,
                            light_samples=32,
                            w=200, h=200)

```

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```
return out[:]
```

Below, `imshow` is used to render one scene in each subplot. Specifying an interpolation with `imshow` improves image quality.

```
[4]: def show_shape(shape, location, color_id):
    ax = axs[location]
    ax.imshow(render(shape, color_id), interpolation='lanczos')
    ax.set_xlabel(shape, fontsize=22)

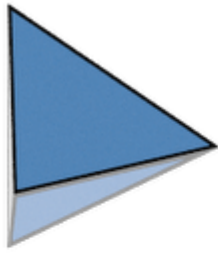
fig, axs = plt.subplots(ncols=3, nrows=2, figsize=(10, 8))

show_shape('Tetrahedron', (0, 0), 0)
show_shape('Cube', (0, 1), 1)
show_shape('Octahedron', (0, 2), 2)
show_shape('Dodecahedron', (1, 0), 3)
show_shape('Icosahedron', (1, 1), 4)

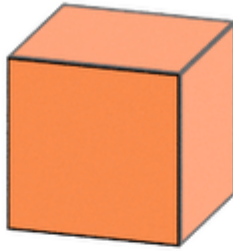
for ax in axs.flatten():
    ax.set_xticks([])
    ax.set_yticks([])
    ax.spines['right'].set_visible(False)
    ax.spines['top'].set_visible(False)
    ax.spines['bottom'].set_visible(False)
    ax.spines['left'].set_visible(False)

fig.suptitle('The Platonic Solids', y=0.92, fontsize=32)
plt.show()
```

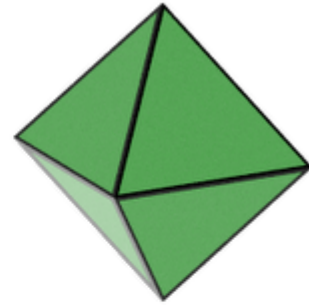
The Platonic Solids



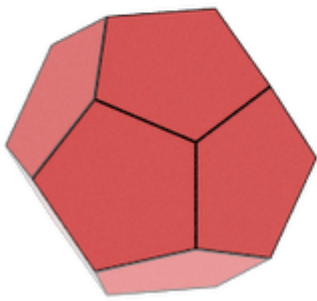
Tetrahedron



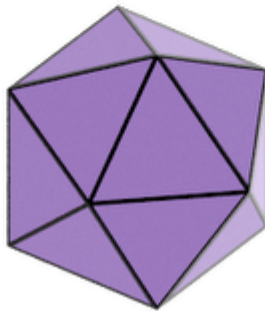
Cube



Octahedron



Dodecahedron



Icosahedron

VISUALIZING GSD FILE

In this example, we will use `fresnel` to visualize a `gsd` file. We will color the particles & bonds by types, as well as visualize the simulation box.

We will need the `gsd` package to run this example.

```
[ ]: import fresnel
import gsd.hoomd
import numpy as np
```

First we read in the `.gsd` file.

```
[ ]: with gsd.hoomd.open(name="molecules.gsd", mode="rb") as gsd_file:
    snap = gsd_file[0]

box = snap.configuration.box
```

We want to color by particle type. We will color A types red, B types blue, and C types green.

```
[3]: N = snap.particles.N
particle_types = snap.particles.typeid
colors = np.empty((N, 3))

# Color by typeid
colors[particle_types == 0] = fresnel.color.linear([.95, 0, 0]) # A type
colors[particle_types == 1] = fresnel.color.linear([0, .95, 0]) # B type
colors[particle_types == 2] = fresnel.color.linear([0, 0, .95]) # C type
```

```
[4]: scene = fresnel.Scene()

# Spheres for every particle in the system
geometry = fresnel.geometry.Sphere(scene, N=N, radius=0.2)
geometry.position[:] = snap.particles.position
geometry.material = fresnel.material.Material(roughness=0.9)
geometry.outline_width = 0.05

# use color instead of material.color
geometry.material.primitive_color_mix = 1.0
geometry.color[:] = fresnel.color.linear(colors)
```

```
[5]: # create box in fresnel
fresnel.geometry.Box(scene, box, box_radius=.07)

[5]: <fresnel.geometry.Box at 0x7f5fbc92670>
```

We will visualize bonds using cylinders, and color the bonds to match the particle types. To aid visualization, we will first remove any bonds that span the periodic boundary.

```
[6]: all_bonds = np.stack(
    [
        snap.particles.position[snap.bonds.group[:, 0]],
        snap.particles.position[snap.bonds.group[:, 1]],
    ],
    axis=1,
)

# Use a distance cutoff (L/2) to filter bonds that span the periodic boundary
bond_distances = np.linalg.norm(all_bonds[:,0,:]-all_bonds[:,1,:], axis=1)

# This simple method will work for cubic cells
L = box[0]
bond_indices = np.where(bond_distances < L/2)[0]
filtered_bonds = all_bonds[bond_indices, :, :]

N_bonds = filtered_bonds.shape[0]
bonds = fresnel.geometry.Cylinder(scene, N=N_bonds)
bonds.material = fresnel.material.Material(roughness=0.5)
bonds.outline_width = 0.05

# Color by bond typeid
bond_ids = snap.bonds.typeid[bond_indices]
bond_colors = np.empty((N_bonds, 3))
bond_colors[bond_ids == 0] = fresnel.color.linear([0, .95, 0]) # B-B Bonds
bond_colors[bond_ids == 1] = fresnel.color.linear([0, 0, .95]) # C-C Bonds

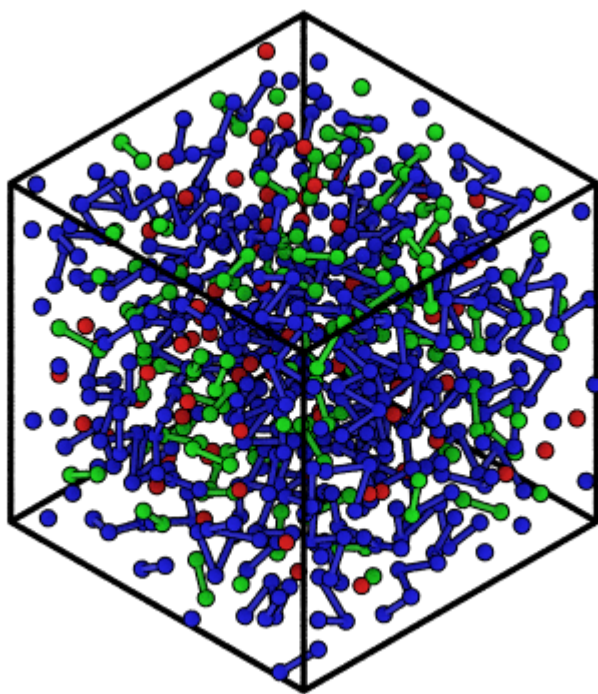
bonds.material.primitive_color_mix = 1.0
bonds.points[:] = filtered_bonds

bonds.color[:] = np.stack(
    [fresnel.color.linear(bond_colors), fresnel.color.linear(bond_colors)], axis=1
)
bonds.radius[:] = [0.1] * N_bonds
```

Now that we have everything setup, we will render everything and apply some ring lighting conditions.

```
[7]: scene.camera = fresnel.camera.Orthographic.fit(scene)
scene.lights = fresnel.light.lightbox()
fresnel.pathtrace(scene, light_samples=5)
```

[7]:



FRESNEL

Overview

<i>Device</i>	Hardware device to use for ray tracing.
<i>pathtrace</i>	Path trace a scene.
<i>preview</i>	Preview a scene.
<i>Scene</i>	Content of the scene to ray trace.

Details

The fresnel ray tracing package.

class `fresnel.Device`(*mode*='auto', *n*=None)
Hardware device to use for ray tracing.

Parameters

- **mode** (*str*) – Specify execution mode: Valid values are `auto`, `gpu`, and `cpu`.
- **n** (*int*) – Specify the number of cpu threads / GPUs this device will use. *None* will use all available threads / devices.

Device defines hardware device to use for ray tracing. *Scene* and *Tracer* instances must be attached to a *Device*. You may attach any number of scenes and tracers to a single *Device*.

See also:

Tutorials:

- *Devices*
- *Tracer methods*

When mode is `auto`, the default, *Device* will select GPU rendering if available and fall back on CPU rendering if not. Set mode to `gpu` or `cpu` to force a specific mode.

Important: By default (`n=None`), this device will use all available GPUs or CPU cores. Set *n* to the number of GPUs or CPU cores this device should use. When selecting *n* GPUs, the device selects the first *n* in the *available_gpus* list.

Tip: Use only a single *Device* to reduce memory consumption.

The static member `available_modes` lists which modes are available. For a mode to be available, the corresponding module must be enabled at compile time. Additionally, there must be at least one GPU present for the `gpu` mode to be available.

```
>>> fresnel.Device.available_modes
['gpu', 'cpu', 'auto']
```

available_gpus = []
Available GPUS.

Type `list[str]`

available_modes = []
Available execution modes.

Type `list[str]`

property mode
The active mode.

Type `str`

class `fresnel.Scene(device=None, camera=None, lights=None)`
Content of the scene to ray trace.

Parameters

- **device** (`Device`) – Device to use when rendering the scene.
- **camera** (`camera.Camera`) – Camera to view the scene. When `None`, defaults to:

```
camera.Orthographic(position=(0, 0, 100),
                    look_at=(0, 0, 0),
                    up=(0, 1, 0),
                    height=100)
```

- **lights** (`list[Light]`) – Lights to light the scene. When `None`, defaults to: `light.rembandt()`

Scene defines the contents of the scene to be traced, including any number of *Geometry* objects, the *Camera*, the *background_color*, *background_alpha*, and *lights*.

Every *Scene* must be associated with a *Device*. For convenience, *Scene* creates a default *Device* when *device* is `None`.

See also:

Tutorials:

- [Introduction](#)
- [Scene properties](#)
- [Lighting setups](#)
- [Devices](#)

property background_alpha
Background alpha (opacity) in the range [0,1].

Type `float`

property background_color
Background color linear RGB.

Note: Use `fresnel.color.linear` to convert standard sRGB colors into the linear color space used by fresnel.

Type ((3,) `numpy.ndarray` of `numpy.float32`)

property camera

Camera view parameters.

Type `camera.Camera`

property device

Device this `Scene` is attached to.

Type `Device`

get_extents()

Get the extents of the scene.

Returns The lower left and upper right corners of the scene.

Return type (3,2) `numpy.ndarray` of `numpy.float32`

property lights

Lights in the scene.

`lights` is a sequence of up to 4 directional lights that apply to the scene. Each light has a direction, color, and size.

Type `list[Light]`

`fresnel.pathtrace(scene, w=600, h=370, samples=64, light_samples=1)`

Path trace a scene.

Parameters

- **scene** (`Scene`) – Scene to render.
- **w** (`int`) – Output image width (in pixels).
- **h** (`int`) – Output image height (in pixels).
- **samples** (`int`) – Number of times to sample the pixels of the scene.
- **light_samples** (`int`) – Number of light samples to take for each pixel sample.

`pathtrace()` is a shortcut that renders output with `tracer.Path`.

`fresnel.preview(scene, w=600, h=370, anti_alias=True)`

Preview a scene.

Parameters

- **scene** (`Scene`) – Scene to render.
- **w** (`int`) – Output image width (in pixels).
- **h** (`int`) – Output image height (in pixels).
- **anti_alias** (`bool`) – Whether to perform anti-aliasing.

`preview()` is a shortcut that renders output with `tracer.Preview`.

Modules

25.1 fresnel.camera

Overview

<i>Camera</i>	Camera base class.
<i>Orthographic</i>	Orthographic camera.
<i>Perspective</i>	Perspective camera.

Details

Cameras.

class `fresnel.camera.Camera(_camera)`

Bases: `object`

Camera base class.

A *Camera* defines the view into the *Scene*.

Camera space is a coordinate system centered on the camera's position. Positive *x* points to the right in the image, positive *y* points up, and positive *z* points out of the screen. The visible area in the image plane is centered on *look_at* with the given *height*. The visible width is *height* * *aspect* where *aspect* is the aspect ratio determined by the resolution of the image in *Tracer* (*aspect* = *tracer.w* / *tracer.h*). *Camera* space shares units with *Scene* space.

Camera provides common methods and properties for all camera implementations. *Camera* cannot be used directly, use one of the subclasses.

See also:

- *Orthographic*
- *Perspective*

property `basis`

Orthonormal camera basis.

basis is computed from *position*, *look_at*, and *up*. The 3 vectors of the basis define the +x, +y, and +z camera space directions in scene space.

Type `((3, 3) numpy.ndarray of numpy.float32)`

property `height`

The height of the image plane.

Type `float`

property `look_at`

The point the camera looks at.

position - *look_at* defines the +z direction in camera space.

Type `((3,) numpy.ndarray of numpy.float32)`

property position

Camera position.

Type ((3,) `numpy.ndarray` of `numpy.float32`)

property up

A vector pointing toward the +y direction in camera space.

The component of `up` perpendicular to `look_at - position` defines the +y direction in camera space.

Type ((3,) `numpy.ndarray` of `numpy.float32`)

class `fresnel.camera.Orthographic`(*position*, *look_at*, *up*, *height*)

Bases: `fresnel.camera.Camera`

Orthographic camera.

Parameters

- **position** ((3,) `numpy.ndarray` of `numpy.float32`) – Camera position.
- **look_at** ((3,) `numpy.ndarray` of `numpy.float32`) – The point the camera looks at (the center of the focal plane).
- **up** ((3,) `numpy.ndarray` of `numpy.float32`) – A vector pointing toward the +y direction in camera space.
- **height** (*float*) – The height of the image plane.

An orthographic camera traces parallel rays from the image plane into the scene. Lines that are parallel in the *Scene* will remain parallel in the rendered image.

position is the center of the image plane in *Scene* space. *look_at* is the point in *Scene* space that will be in the center of the image. Together, these vectors define the image plane which is perpendicular to the line from *position* to *look_at*.

up is a vector in *Scene* space that defines the (+y) direction in the camera space). *up* does not need to be perpendicular to the line from *position* to *look_at*, but it must not be parallel to that line. *height* sets the height of the image sensor in *Scene* units. The width is `height * aspect` where *aspect* is the aspect ratio determined by the resolution of the image in *Tracer* (`aspect = tracer.w / tracer.h`).

Note: Only objects inside the rectangular cuboid defined by corners of the image sensor and the focal plane (extended to infinite height) will appear in the image.

Objects in front of the image plane will appear in the rendered image, objects behind the plane will not.

Tip: Place the camera *position* outside the geometry of the *Scene*. Decrease *height* to zoom in and increase *height* to zoom out.

classmethod `fit`(*scene*, *view*='auto', *margin*=0.05)

Fit a camera to a *Scene*.

Create an orthographic camera that fits the entire height of the scene in the image plane.

Parameters

- **scene** (*Scene*) – Fit the camera to this scene.
- **view** (*str*) – Select view

- **margin** (*float*) – Fraction of extra space to leave on the top and bottom of the scene.

view may be 'auto', 'isometric', or 'front'.

The isometric view is an orthographic projection from a particular angle so that the x,y, and z directions are equal lengths. The front view is an orthographic projection where +x points to the right, +y points up and +z points out of the screen in the image plane. 'auto' automatically selects 'isometric' for 3D scenes and 'front' for 2D scenes.

```
class fresnel.camera.Perspective(position, look_at, up, focal_length=0.5, focus_distance=10, f_stop=inf,
                                height=0.24)
```

Bases: `fresnel.camera.Camera`

Perspective camera.

Parameters

- **position** ((3,) `numpy.ndarray` of `numpy.float32`) – Camera position.
- **look_at** ((3,) `numpy.ndarray` of `numpy.float32`) – The point the camera looks at (the center of the focal plane).
- **up** ((3,) `numpy.ndarray` of `numpy.float32`) – A vector pointing toward the +y direction in camera space.
- **focal_length** (*float*) – Focal length of the camera lens.
- **focus_distance** (*float*) – Distance to the focal plane.
- **f_stop** (*float*) – F-stop ratio for the lens.
- **height** (*float*) – The height of the image plane.

A perspective camera traces diverging rays from the camera position through the image plane into the scene. Lines that are parallel in the `Scene` will converge rendered image.

position is the center of projection `Scene` space. *look_at* is the point in `Scene` space that will be in the center of the image. Together, these vectors define the image plane which is perpendicular to the line from *position* to *look_at*.

up is a vector in `Scene` space that defines the (+y) direction in the camera space). *up* does not need to be perpendicular to the line from *position* to *look_at*, but it must not be parallel to that line.

Note: Only objects inside the rectangular pyramid defined by the position and corners of the image sensor (extended to infinite height) will appear in the image.

`Perspective` models an ideal camera system with a sensor and a thin lens. The sensor lies in the image plane and is the location where the pixels in the rendered image will be captured. *height* sets the height of the sensor in `Scene` units. The width is *height* * *aspect* where *aspect* is the aspect ratio determined by the resolution of the image in `Tracer` (*aspect* = `tracer.w` / `tracer.h`). *focal_length* sets the distance between *position* and the image plane.

Note: The camera *height* should be small relative to the objects in the `Scene` with those objects in front of the image plane. If the scene units are decimeters, the default *height* of 0.24 is 24 mm, the height of a 35 mm camera sensor.

Tip: There are two ways to zoom a perspective camera. 1) Move the position of the camera while keeping the focal length fixed. Photographers call this “zooming with your feet” and it maintains a fixed field of view. 2) Increase the `focal_length` to zoom in or decrease it to zoom out while keeping position fixed. This is the equivalent of rotating the focal length setting on a zoom lens. Changing `focal_length` changes the field of view.

Like a digital camera, the `Perspective` camera must be focused. The focal plane is parallel to the image plane at a distance `focus_distance` from the camera `position`. Objects on the focal plane will be in sharp focus. Objects in front of and behind the plane will be out of focus. Out of focus areas in an image are called **bokeh** and can be used to draw the viewer’s attention to the subject that is in clear focus. The space in front of and behind the focal plane that appears to be in focus is the **depth of field**. Set `f_stop` to control the amount of depth of field. Small, non-zero values will lead to very little depth of field and a value of `inf` will extend the depth of field to infinity.

Note: There are convenience methods to set the camera parameters:

- `focus_on` takes a point and computes the `focus_distance` to put that point on the focal plane.
 - `depth_of_field` computes the `f_stop` needed to achieve a given depth of field.
 - `vertical_field_of_view` computes the `focal_length` needed to achieve a given field of view angle.
-

Tip: The default `height` of 0.24 works well for scene objects that are size ~1 or larger. If the typical objects in your scene are much smaller, adjust `height` by an appropriate fraction.

property `depth_of_field`

The distance about the focal plane in sharp focus.

The area of sharp focus extends in front and behind the focal plane. The distance between the front and back areas of sharp focus is the depth of field.

The depth of field is a function of `focus_distance`, `focal_length`, `f_stop`, and `height`.

Setting `depth_of_field` computes `f_stop` to obtain the desired depth of field as a function of `focus_distance`, `focal_length`, and `height`.

Note: `depth_of_field` does not remain fixed after setting it.

Type `float`

property `f_stop`

F-stop ratio for the lens.

Set the aperture of the opening into the lens in f-stops. This sets the range of the scene that is in sharp focus. Smaller values of `f_stop` result in more background blur.

Tip: Use `depth_of_field` to set the range of sharp focus in `Scene` distance units.

Type `float`

property focal_length

Focal length of the camera lens.

The focal length relative to the image *height* sets the field of view. Given a fixed *height*, a larger *focal_length* gives a narrower field of view.

Tip: With the default height of 0.24, typical focal lengths range from .18 (wide angle) to 0.5 (normal) to 6.0 (telephoto).

See also:

vertical_field_of_view

Type `float`

property focus_distance

Distance to the focal plane.

The focus distance is the distance from the camera position to the center of focal plane.

Tip: Use *focus_on* to compute the focus distance to a particular point in the *Scene*.

Type `float`

property focus_on

A point in the focal plane.

The area of sharp focus extends in front and behind the focal plane.

The focal plane is a function of *focus_distance*, *position*, and *look_at*.

Setting *focus_on* computes *focus_distance* so that the given point is on the focal plane.

Note: *focus_on* does not remain fixed after setting it.

Type `(3,) numpy.ndarray of numpy.float32`

property vertical_field_of_view

Vertical field of view.

The vertical field of view is the angle (in radians) that the camera covers in the +y direction. It is a function of *focal_length* and *height*.

Setting *vertical_field_of_view* computes *focal_length* to achieve the given field of view.

Note: *vertical_field_of_view* does not remain fixed after setting it.

Type `float`

25.2 fresnel.color

Overview

<i>linear</i>	Convert a sRGB color (or colors) into the linear space.
---------------	---

Details

Color utilities.

`fresnel.color.linear(color)`

Convert a sRGB color (or colors) into the linear space.

Standard tools for working with sRGB colors provide gamma corrected values. fresnel needs to perform calculations in a linear color space. This method converts from sRGB to the linear space. Use `linear()` when specifying material or particle colors with sRGB inputs (such as you find in a color picker).

`linear()` accepts RGBA input (such as from matplotlib's `colors.to_rgba` colormap method), but ignores the alpha channel and outputs an Nx3 array.

Parameters `color` ((3,), (4,), (N, 3), or (N, 4) `numpy.ndarray` of `numpy.float32`) – RGB or RGBA colors.

Color components are in the range [0,1].

Returns `numpy.ndarray` with the linearized color(s), same shape as `color`.

25.3 fresnel.geometry

Overview

<i>Box</i>	Box geometry.
<i>ConvexPolyhedron</i>	Convex polyhedron geometry.
<i>Cylinder</i>	Cylinder geometry.
<i>Geometry</i>	Geometry base class.
<i>Mesh</i>	Mesh geometry.
<i>Polygon</i>	Polygon geometry.
<i>Sphere</i>	Sphere geometry.

Details

Geometric primitives.

Geometry defines objects that are visible in a *Scene*. The base class `Geometry` provides common operations and properties. Instantiate specific geometry class to add objects to a *Scene*.

See also:

Tutorials:

- *Primitive properties*
- *Material properties*

- *Outline materials*
- *Multiple geometries*

class `fresnel.geometry.Box(scene, box, box_radius=0.5, box_color=[0, 0, 0])`

Bases: `fresnel.geometry.Cylinder`

Box geometry.

Generate a triclinic box outline with *spherocylinders*. The geometry's material defaults to `material.Material(solid=1.0)`.

Parameters

- **scene** (`Scene`) – Add the geometry to this scene.
- **box** ((1,), (3,), or (6,) `numpy.ndarray` of float32) – Box parameters.
- **box_radius** (`float`) – Radius of box edges.
- **box_color** ((3,) `numpy.ndarray` of float32) – Color of the box edges.

Note: A 1-element *box* array expands to a cube. A 3-element *box* array [Lx, Ly, Lz] expands to an orthorhombic cuboid, and a 6-element *box* array represents a fully triclinic box in the same format as GSD and HOOMD: [Lx, Ly, Lz, xy, xz, yz].

See also:

Tutorials:

- *Box*
- *Visualizing GSD File*

Note: The Box class is constructed from *spherocylinders*, which can be modified individually. The convenience attributes `box_radius` and `box_color` can be used to set the thickness and color of the entire box.

property `box`

Box parameters.

Set *box* to update the shape of the box.

Type (1,), (3,), or (6,) `numpy.ndarray` of float32

property `box_color`

Color of the box edges.

Note: This property sets the color of the *material*.

Type (3,) `numpy.ndarray` of float32

property `box_radius`

Radius of box edges.

Type (`float`)

```
class fresnel.geometry.ConvexPolyhedron(scene, polyhedron_info, position=(0, 0, 0), orientation=(1, 0, 0, 0), color=(0, 0, 0), N=None, material=None, outline_material=None, outline_width=0.0)
```

Bases: [fresnel.geometry.Geometry](#)

Convex polyhedron geometry.

Define a set of convex polyhedron primitives with individual positions, orientations, and colors.

A convex polyhedron is defined by P outward facing planes (origin and normal vector) and a radius that encompass the shape. Use [convex_polyhedron_from_vertices](#) to construct this from the convex hull of a set of vertices.

Parameters

- **scene** ([Scene](#)) – Add the geometry to this scene.
- **polyhedron_info** (*Dict*) – A dictionary containing the face normals (`face_normal`), origins (`face_origin`), face colors (`face_color`), and the radius (`radius`).
- **position** ((N, 3) [numpy.ndarray](#) of float32) – Position of each polyhedron instance.
- **orientation** ((N, 4) [numpy.ndarray](#) of float32) – Orientation of each polyhedron instance (as a quaternion).
- **color** ((N, 3) [numpy.ndarray](#) of float32) – Color of each polyhedron.
- **N** (*int*) – Number of spheres in the geometry. If `None`, determine N from *position*.
- **material** ([material.Material](#)) – Define how light interacts with the geometry. When `None`, defaults to `material.Material()`.
- **outline_material** ([material.Material](#)) – Define how light interacts with the geometry's outline. When `None`, defaults to `solid black material.Material(solid=1, color=(0,0,0))`.
- **outline_width** (*float*) – Width of the outline in scene units.

See also:

Tutorials:

- [Convex polyhedron](#)

Hint: Avoid costly memory allocations and type conversions by specifying primitive properties in the appropriate array type.

property color

The color of each polyhedron.

Type (N, 3) [Array](#)

property color_by_face

Mix face colors with the per-polyhedron color.

Set to 0 to color particles by the per-particle [color](#). Set to 1 to color faces by the per-face color. Set to a value between 0 and 1 to blend between the two colors.

Type [float](#)

get_extents()

Get the extents of the geometry.

Returns The lower left and upper right corners of the scene.

Return type (3,2) `numpy.ndarray` of float32

property orientation

The orientation of each polyhedron.

Type (N, 4) `Array`

property position

The position of each polyhedron.

Type (N, 3) `Array`

class `fresnel.geometry.Cylinder`(*scene*, *points*=((0, 0, 0), (0, 0, 0)), *radius*=0.5, *color*=(0, 0, 0), *N*=None, *material*=None, *outline_material*=None, *outline_width*=0.0)

Bases: `fresnel.geometry.Geometry`

Cylinder geometry.

Define a set of spherocylinder primitives with individual start and end positions, radii, and colors.

Parameters

- **scene** (`Scene`) – Add the geometry to this scene.
- **points** ((N, 2, 3) `numpy.ndarray` of float32) – *N* cylinder start and end points.
- **radius** ((N,) `numpy.ndarray` of float32) – Radius of each cylinder.
- **color** ((N, 2, 3) `numpy.ndarray` of float32) – Color of each start and end point.
- **N** (`int`) – Number of cylinders in the geometry. When `None`, determine *N* from *points*.
- **material** (`material.Material`) – Define how light interacts with the geometry. When `None`, defaults to `material.Material()`.
- **outline_material** (`material.Material`) – Define how light interacts with the geometry's outline. When `None`, defaults to solid black `material.Material(solid=1, color=(0,0,0))`.
- **outline_width** (`float`) – Width of the outline in scene units.

See also:

Tutorials:

- [*Cylinder*](#)

Hint: Avoid costly memory allocations and type conversions by specifying primitive properties in the appropriate array type.

Tip: When all cylinders are the same size or color, pass a single value and NumPy will broadcast it to all elements of the array.

property color

Color of each start and end point.

Type (N, 2, 3) `Array`

get_extents()

Get the extents of the geometry.

Returns The lower left and upper right corners of the scene.

Return type (3,2) `numpy.ndarray` of float32

property points

The start and end points of the cylinders.

Type (N, 2, 3) `Array`

property radius

The radii of the cylinders.

Type (N,) `Array`

class `fresnel.geometry.Geometry`

Bases: `object`

Geometry base class.

Geometry provides operations and properties common to all geometry classes.

Note: You cannot instantiate a `Geometry` directly. Use one of the subclasses.

disable()

Disable the geometry.

When disabled, the geometry will not be visible in the *Scene*.

See also:

enable

enable()

Enable the geometry.

When enabled, the geometry will be visible in the *Scene*.

See also:

disable

property material

Define how light interacts with the geometry.

Type *material.Material*

property outline_material

Define how light interacts with the geometry's outline.

Type *material.Material*

property outline_width

Width of the outline in scene units.

Type `float`

remove()

Remove the geometry from the scene.

After calling *remove*, the geometry is no longer part of the scene. It cannot be added back into the scene.

Use *disable* and *enable* to hide geometry reversibly.

class `fresnel.geometry.Mesh`(*scene*, *vertices*, *position*=(0, 0, 0), *orientation*=(1, 0, 0, 0), *color*=(0, 0, 0),
N=None, *material*=None, *outline_material*=None, *outline_width*=0.0)

Bases: *fresnel.geometry.Geometry*

Mesh geometry.

Define a set of triangle mesh primitives with individual positions, orientations, and colors.

Parameters

- **scene** ([Scene](#)) – Add the geometry to this scene.
- **vertices** ((3T, 3) [numpy.ndarray](#) of float32) – Vertices of the triangles, listed contiguously. Vertices 0,1,2 define the first triangle, 3,4,5 define the second, and so on.
- **color** ((3T, 3) [numpy.ndarray](#) of float32) – Color of each vertex.
- **position** ((N, 3) [numpy.ndarray](#) of float32) – Position of each mesh instance.
- **orientation** ((N, 4) [numpy.ndarray](#) of float32) – Orientation of each mesh instance (as a quaternion).
- **N** ([int](#)) – Number of mesh instances in the geometry. If `None`, determine *N* from *position*.
- **material** ([material.Material](#)) – Define how light interacts with the geometry. When `None`, defaults to `material.Material()`.
- **outline_material** ([material.Material](#)) – Define how light interacts with the geometry’s outline. When `None`, defaults to `solid black material.Material(solid=1, color=(0,0,0))`.
- **outline_width** ([float](#)) – Width of the outline in scene units.

See also:

Tutorials:

- [Mesh](#)

Hint: Avoid costly memory allocations and type conversions by specifying primitive properties in the appropriate array type.

property color

The color of each sphere.

Type (N, 3) [Array](#)

get_extents()

Get the extents of the geometry.

Returns The lower left and upper right corners of the scene.

Return type (3,2) [numpy.ndarray](#) of float32

property orientation

The orientation of each mesh.

Type (N, 4) [Array](#)

property position

The position of each mesh.

Type (N, 3) [Array](#)

```
class fresnel.geometry.Polygon(scene, vertices, position=(0, 0), angle=0, color=(0, 0, 0),
                               rounding_radius=0, N=None, material=None, outline_material=None,
                               outline_width=0.0)
```

Bases: [fresnel.geometry.Geometry](#)

Polygon geometry.

Define a set of simple polygon primitives in the xy plane with individual positions, rotation angles, and colors.

Parameters

- **scene** ([Scene](#)) – Add the geometry to this scene.
- **vertices** ((N_vert, 2) [numpy.ndarray](#) of float32) – Polygon vertices.
- **position** ((N, 2) [numpy.ndarray](#) of float32) – Position of each polygon.
- **angle** ((N,) [numpy.ndarray](#) of float32) – Orientation angle of each polygon (in radians).
- **color** ((N, 3) [numpy.ndarray](#) of float32) – Color of each polygon.
- **rounding_radius** ([float](#)) – Rounding radius for spheropolygons.
- **N** ([int](#)) – Number of polygons in the geometry. If `None`, determine *N* from *position*.
- **material** ([material.Material](#)) – Define how light interacts with the geometry. When `None`, defaults to `material.Material()`.
- **outline_material** ([material.Material](#)) – Define how light interacts with the geometry's outline. When `None`, defaults to `solid black material.Material(solid=1, color=(0,0,0))`.
- **outline_width** ([float](#)) – Width of the outline in scene units.

See also:

Tutorials:

- [Polygon](#)

Hint: Avoid costly memory allocations and type conversions by specifying primitive properties in the appropriate array type.

property angle

The rotation angle of each polygon (in radians).

Type (N,) [Array](#)

property color

The color of each polygon.

Type (N, 2, 3) [Array](#)

get_extents()

Get the extents of the geometry.

Returns The lower left and upper right corners of the scene.

Return type (3,2) [numpy.ndarray](#) of float32

property position

The position of each polygon.

Type (N, 2) [Array](#)

class `fresnel.geometry.Sphere`(*scene*, *position*=(0, 0, 0), *radius*=0.5, *color*=(0, 0, 0), *N*=None, *material*=None, *outline_material*=None, *outline_width*=0.0)

Bases: [fresnel.geometry.Geometry](#)

Sphere geometry.

Define a set of sphere primitives with individual positions, radii, and colors.

Parameters

- **scene** ([Scene](#)) – Add the geometry to this scene.
- **position** ((N, 3) [numpy.ndarray](#) of float32) – Position of each sphere.
- **radius** ((N,) [numpy.ndarray](#) of float32) – Radius of each sphere.
- **color** ((N, 3) [numpy.ndarray](#) of float32) – Color of each sphere.
- **N** ([int](#)) – Number of spheres in the geometry. If `None`, determine *N* from *position*.
- **material** ([material.Material](#)) – Define how light interacts with the geometry. When `None`, defaults to `material.Material()`.
- **outline_material** ([material.Material](#)) – Define how light interacts with the geometry's outline. When `None`, defaults to `solid black material.Material(solid=1, color=(0,0,0))`.
- **outline_width** ([float](#)) – Width of the outline in scene units.

See also:

Tutorials:

- [Sphere](#)

Hint: Avoid costly memory allocations and type conversions by specifying primitive properties in the appropriate array type.

Tip: When all spheres are the same size, pass a single value for *radius* and numpy will broadcast it to all elements of the array.

property color

The color of each sphere.

Type (N, 3) [Array](#)

get_extents()

Get the extents of the geometry.

Returns The lower left and upper right corners of the scene.

Return type (3,2) [numpy.ndarray](#) of float32

property position

The position of each sphere.

Type (N, 3) [Array](#)

property radius

The radius of each sphere.

Type (N,) [Array](#)

25.4 fresnel.interact

Overview

<i>SceneView</i>	View a fresnel Scene in real time.
------------------	------------------------------------

Details

Interactive Qt widgets.

class `fresnel.interact.SceneView(scene, max_samples=2000)`

View a fresnel Scene in real time.

SceneView is a PySide2 widget that displays a *Scene*, rendering it with *Path* interactively. Use the mouse to rotate the camera view.

Parameters

- **scene** (*Scene*) – The scene to display.
- **max_samples** (*int*) – Sample a total of max_samples.
- Left click to pitch and yaw
- Right click to roll and zoom
- Middle click to pan
- Hold ctrl to make small adjustments

Using in a standalone script

To use *SceneView* in a standalone script, import the *fresnel.interact* module, create a *Scene*, instantiate the *SceneView*, show it, and start the app event loop.

```
import fresnel, fresnel.interact
# build scene
view = fresnel.interact.SceneView(scene)
view.show()
fresnel.interact.app.exec_();
```

Using with Jupyter notebooks

To use *SceneView* in a Jupyter notebook, import `PySide2.QtCore` and activate Jupyter's qt5 integration.

```
from PySide2 import QtCore
% gui qt
```

Import the *fresnel.interact* module, create a *Scene*, and instantiate the *SceneView*. Do not call the app event loop, Jupyter is already running the event loop in the background. When the *SceneView* object is the result of a cell, it will automatically show and activate focus.

```
import fresnel, fresnel.interact
# build Scene
fresnel.interact.SceneView(scene)
```

Note: The interactive window will open on the system that *hosts* Jupyter.

See also:

Tutorials:

- *Interactive scene view*

TIMEOUT = 100

Timeout for delayed actions to take effect.

property scene

The scene rendered in this view.

Type *Scene*

25.5 fresnel.light

Overview

<i>Light</i>	A light.
<i>butterfly</i>	Create a butterfly lighting setup.
<i>cloudy</i>	Create a cloudy day lighting setup.
<i>lightbox</i>	Create a light box lighting setup.
<i>loop</i>	Create a loop lighting setup.
<i>rembrandt</i>	Create a Rembrandt lighting setup.
<i>ring</i>	Create a ring lighting setup.

Details

Lights.

Light objects in a *Scene*.

See also:

Tutorials:

- *Scene properties*
- *Lighting setups*

class `fresnel.light.Light`(*direction*, *color*=(1, 1, 1), *theta*=0.375)

A light.

Parameters

- **direction** ((3,) `numpy.ndarray` of float32) – Vector direction the light points (in *Camera* space).
- **color** ((3,) `numpy.ndarray` of float32) – Linear RGB color and intensity of the light.

- **theta** (*float*) – Half angle of the cone that defines the area of the light (in radians).

In fresnel, lights are area lights at an infinite distance away in the given *direction* and are circular with the size set by *theta*. *color* sets the light intensity. A (0.5, 0.5, 0.5) light is twice as bright as (0.25, 0.25, 0.25). Lights are normalized so that *color* = (1, 1, 1) should provide approximately a correct exposure. Color values greater than 1 are allowed.

Note: *direction* is in *Camera* space. A direction of (1, 0, 0) sets a light coming from the right in the image, regardless of the camera position.

`fresnel.light.butterfly()`

Create a butterfly lighting setup.

The butterfly portrait lighting setup is front lighting with the key light (index 0) placed high above the camera and the fill light (index 1) below the camera.

Returns The lights.

Return type `list[Light]`

`fresnel.light.cloudy()`

Create a cloudy day lighting setup.

The cloudy lighting setup mimics a cloudy day. A strong light comes from all directions above. A weaker light comes from all directions below (accounting for light reflected off the ground). Use *Path* tracing for best results with this setup.

Returns The lights.

Return type `list[Light]`

`fresnel.light.lightbox()`

Create a light box lighting setup.

The light box lighting setup places a single area light that covers the top, bottom, left, and right. Use *Path* tracing for best results with this setup.

Returns The lights.

Return type `list[Light]`

`fresnel.light.loop(side='right')`

Create a loop lighting setup.

The loop portrait lighting setup places the key light slightly to one side of the camera and slightly up (index 0). The fill light is on the other side of the camera at the level of the camera (index 1).

Parameters *side* (*str*) – ‘right’ or ‘left’ to choose which side of the camera to place the key light.

Returns The lights.

Return type `list[Light]`

`fresnel.light.rembrandt(side='right')`

Create a Rembrandt lighting setup.

The Rembrandt portrait lighting setup places the key light 45 degrees to one side of the camera and slightly up (index 0). The fill light is on the other side of the camera at the level of the camera (index 1).

Parameters *side* (*str*) – ‘right’ or ‘left’ to choose which side of the camera to place the key light.

Returns The lights.

Return type `list[Light]`

`fresnel.light.ring()`

Create a ring lighting setup.

The ring lighting setup provides a strong front area light. This type of lighting is common in fashion photography. Use [Path](#) tracing for best results with this setup.

Returns The lights.

Return type `list[Light]`

25.6 fresnel.material

Overview

<i>Material</i>	Define material properties.
-----------------	-----------------------------

Details

Materials describe the way light interacts with surfaces.

class `fresnel.material.Material`(*solid=0, color=(0.9, 0.9, 0.9), primitive_color_mix=0, roughness=0.3, specular=0.5, spec_trans=0, metal=0*)

Define material properties.

Materials control how light interacts with the geometry.

Parameters

- **solid** (*float*) – Set to 1 to pass through a solid color, regardless of the light and view angle.
- **color** ((3,) `numpy.ndarray` of `float32`) – Linear material color.
- **primitive_color_mix** (*float*) – Set to 1 to use the color provided in the [Geometry](#), 0 to use the color specified in the [Material](#), or a value in the range [0, 1] to mix the two colors.
- **roughness** (*float*) – Roughness of the material. Nominally in the range [0.1, 1].
- **specular** (*float*) – Control the strength of the specular highlights. Nominally in the range [0, 1].
- **spec_trans** (*float*) – Control the amount of specular light transmission. In the range [0, 1].
- **metal** (*float*) – Set to 0 for dielectric material, or 1 for metal. Intermediate values interpolate between the two.

See also:

Tutorials:

- [Material properties](#)

Note: Colors are in the linearized color space. Use [fresnel.color.linear](#) to convert standard sRGB colors into this space.

property color

- Linear material color.

Type ((3,) `numpy.ndarray` of float32))

property metal

Set to 0 for dielectric material, or 1 for metal.

Intermediate values interpolate between the two.

Type `float`

property primitive_color_mix

Mix the material color with the geometry.

Set to 1 to use the color provided in the *Geometry*, 0 to use the color specified in the *Material*, or a value in the range [0, 1] to mix the two colors.

Type `float`

property roughness

Roughness of the material.

Nominally in the range [0.1, 1].

Type `float`

property solid

Is this material a solid color?

Set to 1 to pass through a solid color, regardless of the light and view angle.

Type `float`

property spec_trans

Control the amount of specular light transmission.

In the range [0, 1].

Type `float`

property specular

Control the strength of the specular highlights.

Nominally in the range [0, 1].

Type `float`

25.7 fresnel.tracer

Overview

<i>Path</i>	Path tracer.
<i>Preview</i>	Preview ray tracer.
<i>Tracer</i>	Base class for all ray tracers.

Details

Ray tracers process a *Scene* and render output images.

- *Preview* generates a quick approximate render.
- *Path* which provides soft shadows, reflections, and other effects.

See also:

Tutorials:

- *Introduction*
- *Tracer methods*

class `fresnel.tracer.Path(device, w, h)`

Bases: `fresnel.tracer.Tracer`

Path tracer.

Parameters

- **device** (*Device*) – Device to use.
- **w** (*int*) – Output image width.
- **h** (*int*) – Output image height.

The path tracer applies advanced lighting effects, including soft shadows, reflections, and depth of field. It operates by Monte Carlo sampling. Each call to *render* performs one sample per pixel. The *output* image is the mean of all the samples. Many samples are required to produce a smooth image. *sample* provides a convenience API to make many samples with a single call.

reset()

Clear the output buffer.

Start sampling a new image. Increment the random number seed so that the new image is statistically independent from the previous.

sample(*scene, samples, reset=True, light_samples=1*)

Sample the image.

Parameters

- **scene** (*Scene*) – The scene to render.
- **samples** (*int*) – The number of samples to take per pixel.
- **reset** (*bool*) – When True, call *reset* before sampling
- **light_samples** (*int*) – The number of light samples per primary camera ray.

As an unbiased renderer, the sampling noise will scale as $\frac{1}{\sqrt{}}$

Returns

A reference to the current *output* buffer.

Return type

ImageArray

Note: When *reset* is False, subsequent calls to *sample* will continue to add samples to the current output image. Use the same number of light samples when sampling an image in this way.

class `fresnel.tracer.Preview(device, w, h, anti_alias=True)`

Bases: `fresnel.tracer.Tracer`

Preview ray tracer.

Parameters

- **device** (*Device*) – Device to use.
- **w** (*int*) – Output image width.
- **h** (*int*) – Output image height.
- **anti_alias** (*bool*) – Whether to perform anti-aliasing. If True, uses an 64 samples.

Overview

The *Preview* tracer produces a preview of the scene quickly. It approximates the effect of light on materials. The output of the *Preview* tracer will look very similar to that from the *Path* tracer, but will miss soft shadows, reflection, transmittance, depth of field and other effects.

Anti-aliasing

The default value of *anti_alias* is True to smooth sharp edges in the image. The anti-aliasing level corresponds to `aa_level=3` in fresnel versions up to 0.11.0. Different *seed* values will result in different output images.

property *anti_alias*

Whether to perform anti-aliasing.

Type `bool`

class `fresnel.tracer.Tracer`

Bases: `object`

Base class for all ray tracers.

Tracer provides operations common to all ray tracer classes.

Each *Tracer* instance stores a pixel output buffer. When you *render* a *Scene*, the *output* is updated.

Note: You cannot instantiate *Tracer* directly. Use one of the subclasses.

disable_highlight_warning()

Disable the highlight clipping warnings.

enable_highlight_warning(color=(1, 0, 1))

Enable highlight clipping warnings.

When a pixel in the rendered image is too bright to represent, make that pixel the given *color* to flag the problem to the user.

Parameters *color* (*tuple*) – Color to make the highlight warnings.

histogram()

Compute a histogram of the image.

The histogram is computed as a lightness in the sRGB color space. The histogram is computed only over the visible pixels in the image, fully transparent pixels are ignored. The returned histogram is nbins x 4, the first column contains the lightness histogram and the next 3 contain R,B, and G channel histograms respectively.

Returns (histogram, bin_positions).

property linear_output

Reference to the current output buffer in linear color space.

Note: The output buffer is modified by *render* and *resize*.

Type *Array*

property output

Reference to the current output buffer.

Note: The output buffer is modified by *render* and *resize*.

Type *ImageArray*

render(*scene*)

Render a scene.

Parameters **scene** (*Scene*) – The scene to render.

Returns A reference to the current output buffer as a *fresnel.util.ImageArray*.

Render the given scene and write the resulting pixels into the output buffer.

resize(*w*, *h*)

Resize the output buffer.

Parameters

- **w** (*int*) – New output buffer width.
- **h** (*int*) – New output buffer height.

Warning: *resize* clears the output buffer.

property seed

Random number seed.

Type *int*

25.8 fresnel.util

Overview

<i>Array</i>	Access fresnel memory buffers.
<i>convex_polyhedron_from_vertices</i>	Make a convex polyhedron from vertices.
<i>ImageArray</i>	Access fresnel images.

Details

Utilities.

class `fresnel.util.Array(buf, geom)`

Bases: `object`

Access fresnel memory buffers.

`Array` provides a python interface to access the internal data of memory buffers stored and managed by fresnel. You can access a `Array` as if it were a `numpy.ndarray` (with limited operations). Below, *slice* is a `slice` or array indexing mechanic that `numpy` understands.

Writing

Write to an array with `array[slice] = v` where *v* is `numpy.ndarray`, `list`, or scalar value to broadcast. When *v* is a *contiguous* `numpy.ndarray` of the same data type, the data is copied directly from *v* into the internal buffer. Otherwise, it is converted to a `numpy.ndarray` before copying.

Reading

Read from an array with `v = array[slice]`. This returns a **copy** of the data as a `numpy.ndarray` each time it is called.

shape

Dimensions of the array.

Type `tuple[int, [int]]`

dtype

Numpy data type

class `fresnel.util.ImageArray(buf, geom)`

Bases: `fresnel.util.Array`

Access fresnel images.

Provide `Array` functionality with some additional convenience methods specific to working with images. Images are represented as (W, H, 4) `numpy.ndarray` of `uint8` values in **RGBA** format.

When a `ImageArray` is the result of an image in a Jupyter notebook cell, Jupyter will display the image.

fresnel.util.convex_polyhedron_from_vertices(vertices)

Make a convex polyhedron from vertices.

Parameters `vertices` ((3,) `numpy.ndarray` of `float32`) – Vertices of the polyhedron.

Returns

Convex hull of *vertices* in a format used by `ConvexPolyhedron`.

The dictionary contains the keys `face_origin`, `face_normal`, `face_color`, and `radius`.

Return type `dict`

The dictionary can be used directly to draw a polyhedron from its vertices:

```
scene = fresnel.Scene()
polyhedron = fresnel.util.convex_polyhedron_from_vertices(vertices)
geometry = fresnel.geometry.ConvexPolyhedron(scene,
```

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```
polyhedron,  
position=[0, 0, 0],  
orientation=[1, 0, 0, 0])
```

25.9 fresnel.version

Version and build information.

`fresnel.version.version`

fresnel package version, following semantic versioning.

Type `str`

CODE STYLE

All code in fresnel must follow a consistent style to ensure readability. We provide configuration files for linters and autoformatters (specified below) so that developers can automatically validate and format files.

These tools are configured for use with `pre-commit` in `.pre-commit-config.yaml`. You can install pre-commit hooks to validate your code. Checks will run on pull requests. Run checks manually with:

```
pre-commit run --all-files
```

26.1 Python

Python code in GSD should follow [PEP8](#) with the formatting performed by `yapf` (configuration in `setup.cfg`). Code should pass all **flake8** tests and formatted by **yapf**.

26.1.1 Tools

- Linter: `flake8`
 - With these plugins:
 - * `pep8-naming`
 - * `flake8-docstrings`
 - * `flake8-rst-docstrings`
 - Configure `flake8` in your editor to see violations on save.
- Autoformatter: `yapf`
 - Run: `pre-commit run --all-files` to apply style changes to the whole repository.

26.1.2 Documentation

Python code should be documented with docstrings and added to the Sphinx documentation index in `doc/`. Docstrings should follow [Google style](#) formatting for use in [Napoleon](#).

26.2 C++/CUDA

- Style is set by clang-format
 - Whitesmith’s indentation style.
 - 100 character line width.
 - Indent only with spaces.
 - 4 spaces per indent level.
 - See `.clang-format` for the full **clang-format** configuration.
- Naming conventions:
 - Namespaces: All lowercase `somenamespace`
 - Class names: `UpperCamelCase`
 - Methods: `lowerCamelCase`
 - Member variables: `m_` prefix followed by lowercase with words separated by underscores `m_member_variable`
 - Constants: all upper-case with words separated by underscores `SOME_CONSTANT`
 - Functions: `lowerCamelCase`

26.2.1 Tools

- Autoformatter: `clang-format`.
 - Run: `pre-commit run --all-files --hook-stage manual` to apply changes to the whole repository. You must have a `conda` installation in your `PATH` to run this.

26.2.2 Documentation

Documentation comments should be in Javadoc format and precede the item they document for compatibility with Doxygen and most source code editors. Multi-line documentation comment blocks start with `/**` and single line ones start with `///`.

26.3 Other file types

Use your best judgment and follow existing patterns when styling CMake and other files types. The following general guidelines apply:

- 100 character line width.
- 4 spaces per indent level.
- 4 space indent.

26.4 Editor configuration

Visual Studio Code users: Open the provided workspace file (`fresnel.code-workspace`) which provides configuration settings for these style guidelines.

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- Bryan VanSaders, University of Michigan
- Mike Henry, Boise State University
- Jenny Fothergill, Boise State University
- Corwin Kerr, University of Michigan

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